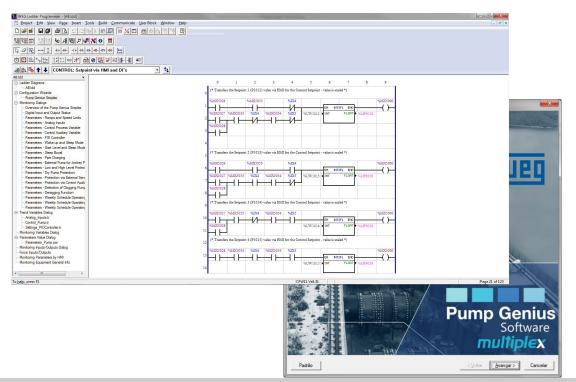


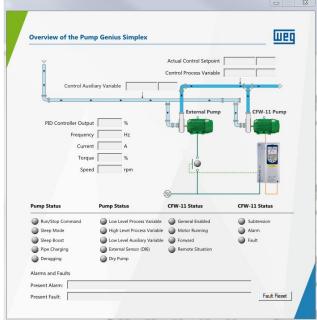
Pump Genius Application Functionalities for control of Pumps



Objective

- Provide the user with flexibility and fast setup process when configuring drive + SoftPLC function towards the control of pumps applications.
- It uses tools of ladder language offered by WLP along with configuration and monitoring assistants.







Pump Genius Platform

SIMPLEX

- Only one pump with speed controlled
- It uses only one drive
- Start/Stop commands for external pump (low demand) using drive output relay.

MULTIPUMP

- It controls the speed of only one paralell pump.
- It uses only one drive
- Start/Stop commands for paralell pumps via output relays.

MULTIPLEX

- Each of the paralell pumps has speed control.
- Up to 6 drives can be used.
- Each paralell pump is drive driven and it can be configured as master/slave(lead/lag).



	Simplex		Multipump		Multiplex
	CFW500	CFW11	CFW500	CFW11	CFW11
Firmware Version	>1.50	Ve5.31	>1.50	Ve5.31	Ve5.31
Maximum number of Pumps	1	1	4 (fixed) or 3 (floating)	6 (fixed) or 5 (floating)	6
Symbinet	-	-	-	-	
Master / Slave	-	-	-	-	
Fixed / Floating Control	-	-			-
Proc. Variable with Eng. Units	*		*		
Setpoint via HMI or Comm.					
4 Setpoints via DI's					
12 Setpoints with time Schedule	-		-	-	-



	Simplex		Multipump		Multiplex
	CFW500	CFW11	CFW500	CFW11	CFW11
Pump to be driven based on sequence	-	-			-
Pump to be driven based on operation time	-	-			
PID Control mode Direct / Reverse					
Manual / Automatic PID control			-	-	-
Wake-up mode or Start by level					
Sleep mode					
Sleep Boost Function					
Pipe filling					



	Simplex		Multipump		Multiplex
	CFW500	CFW11	CFW500	CFW11	CFW11
External Pump			-	-	-
Turn-on/off of paralell pumps	-	-			
Low/High Level of process variable					
Dry Pump					
External Sensor protection via DI6					
Low Level protection Protection of Low level by auxiliary variable	-		-		
Force Pump Rotation	-	-			
Anti-clogging Function			-	-	-

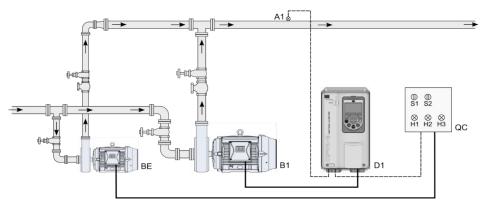


	Simplex		Multipump		Multiplex
	CFW500	CFW11	CFW500	CFW11	CFW11
Run Pump on local mode (HMI)					
Broken wire alarm					

Pump Genius Simplex

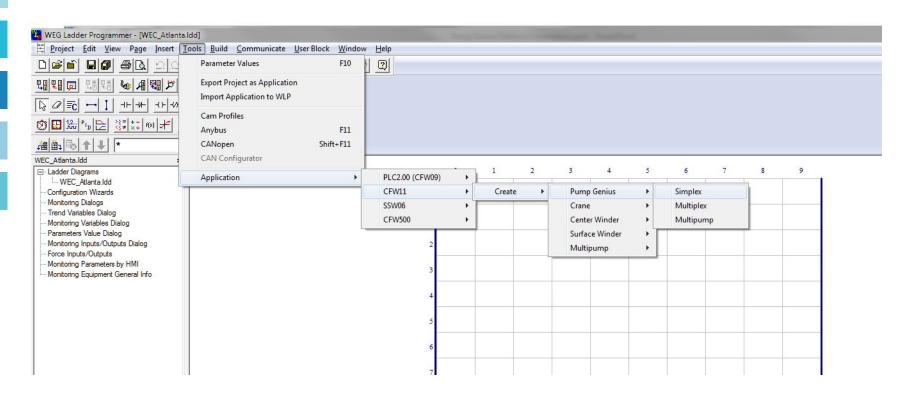


- Pump control where there is only one pump driven by its own VFD with the possibilitity to command an external pump via output relay.
- Main features:
 - Control Setpoint can be via logical combination of Dls(Dl4/Dl5), Al, HMI, Weekly scheduled based.
 - Sleep Boost function
 - Logic to start an external pump at low demand situations(jockey pump)
 - Process Variable can be through one Al or Differential
 - Several Engineering Units to choose
 - PID control
 - Sleep/Wake-up Mode and Start by Level
 - Pipe filling function
 - Broken and Clogged Pipe Functions
 - Deragging Function
 - Dry Pump protection
 - High/Low Level alarms
 - Open application for customer's customization
 - Possibibility for 12 different Control Setpoints based on scheduled time.



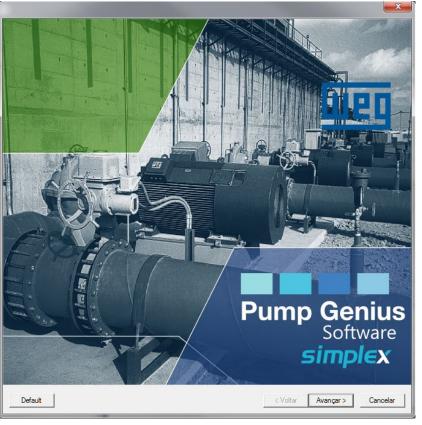


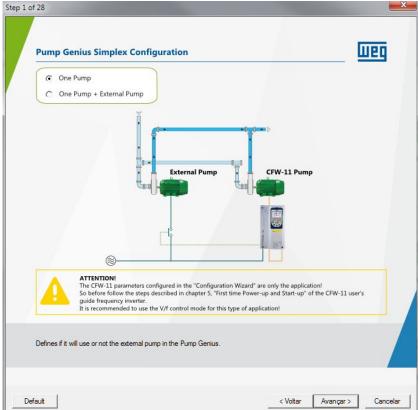
How to open the application Pump Genius Simplex





- Introduction Screen
- Selection of external Pump

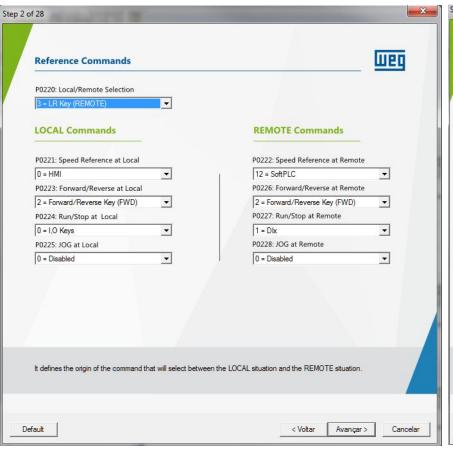






Source of commands e I/Os

- Local/Remote Source of commands for the drive
- Function of I/Os

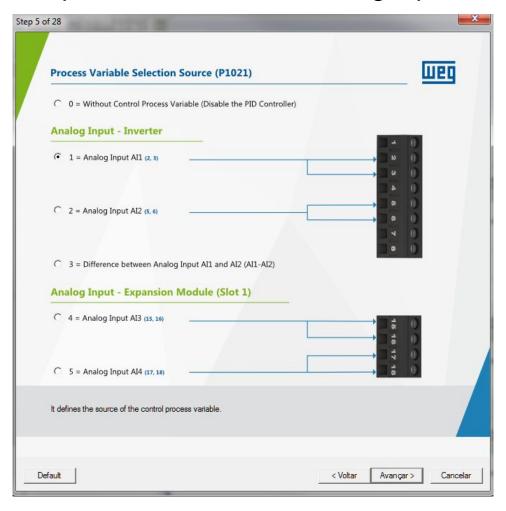






Process Variable

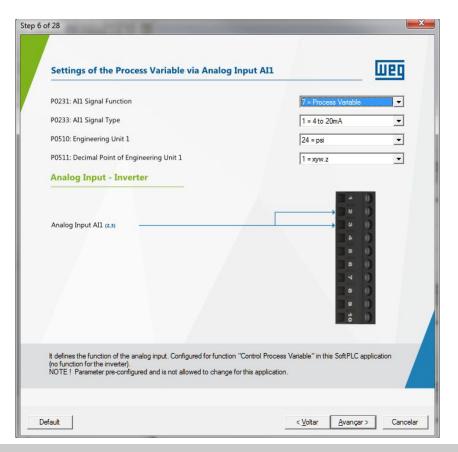
Source of the process variable via Analog Input

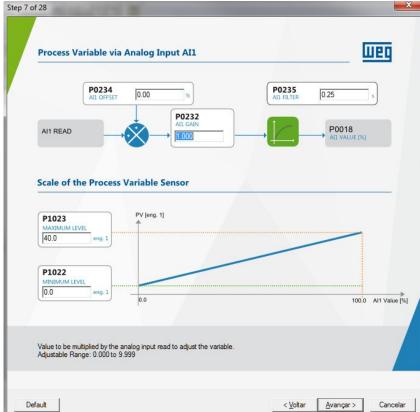




Process Variable

- Type of Signal in the AI (4-20mA / 0-10V)
- Engineering Unit and Sensor scale
- Adjustments in the AI

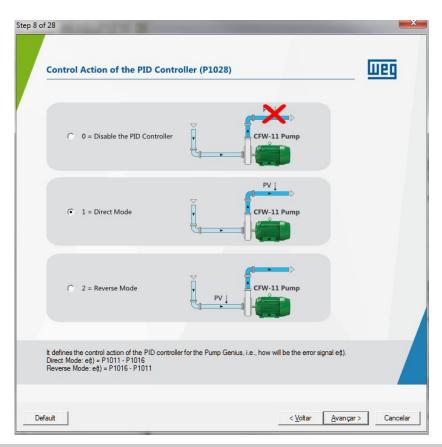


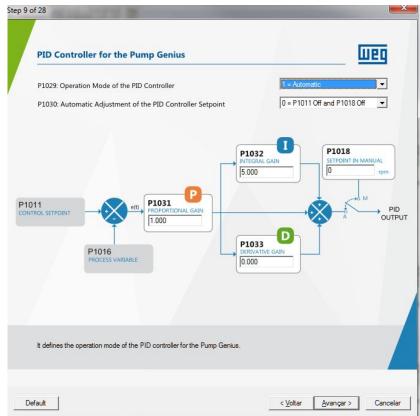




PID Function

- Control mode (disable, directe and reverse)
- Operation mode and setpoint (manual / automatic)
- Gains: Proportional, Integral and Derivative

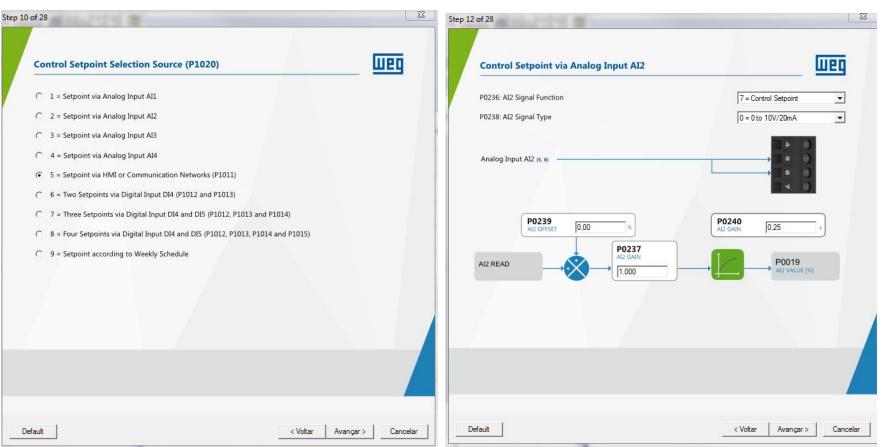






Control Setpoint

- Source of the control setpoint
- Type of signal and adjustments of gains to the AI for the control setpoint.

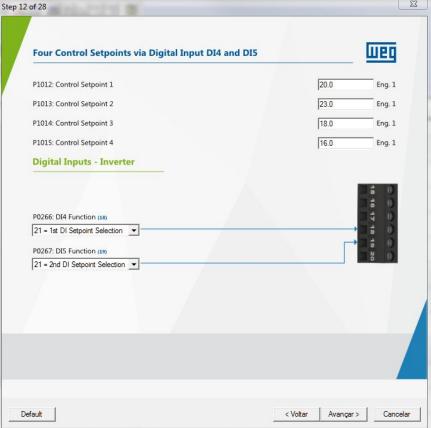




Control Setpoint

- Setpoint via HMI or Communication
- Setpoint via combination of DI's 4 and 5.

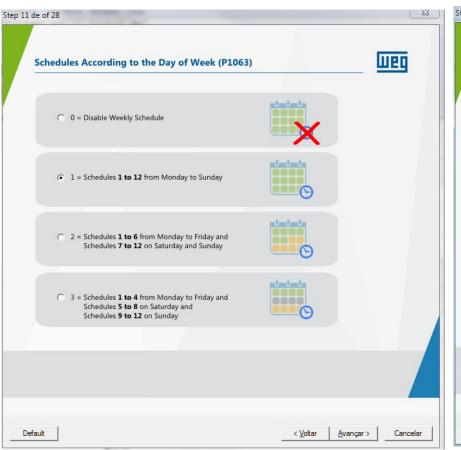






Weekly Schedule (setpoint)

- Configuration of the schedule.
- Definition of Control setpoint based on scheduled time.

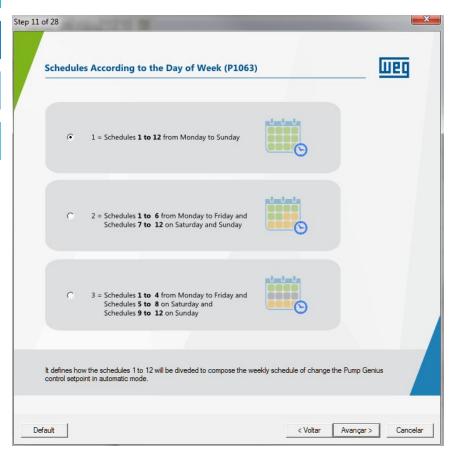






Weekly Schedule (Speed reference)

- Configuration of the schedule.
- Definition of Speed Reference based on scheduled time.

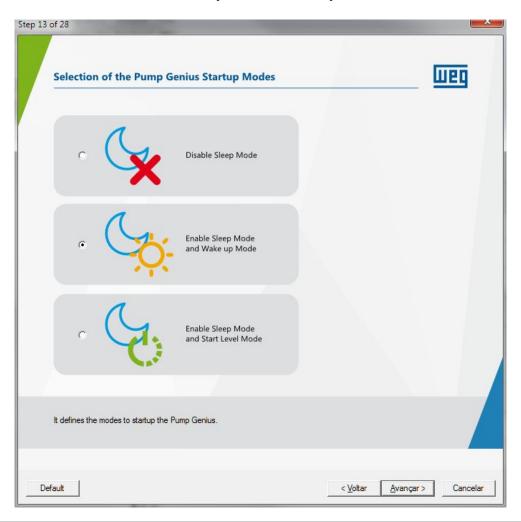






Starting Modes

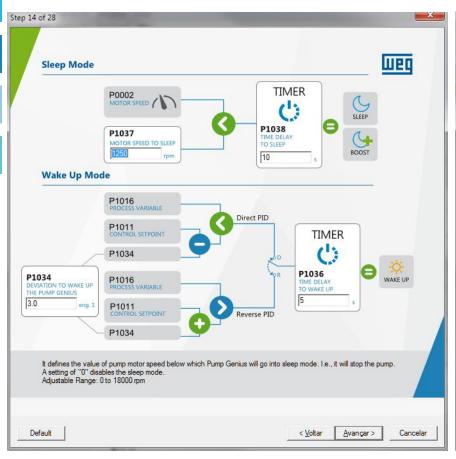
It enables the sleep/Wake-up modes and start by level.





Starting Modes

- It Configures Sleep and Wake-up modes.
- It Configures Sleep mode and Start by level.

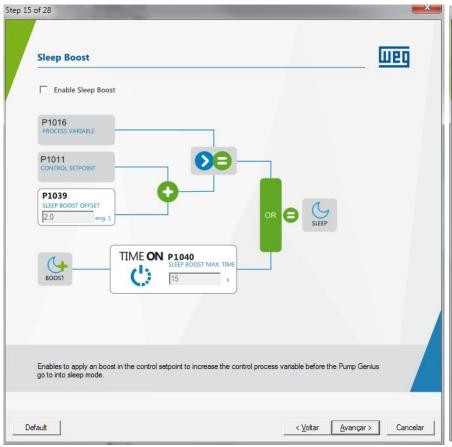


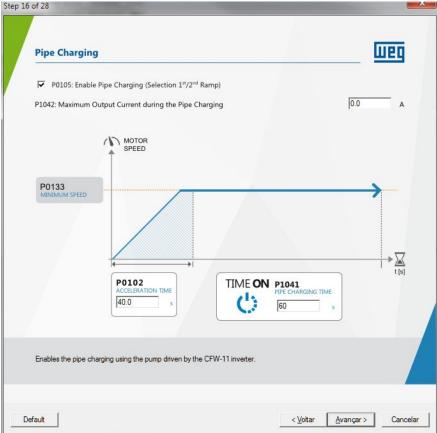




Boost and Pipe Charging Function

- It enables the boost function (sleep boost).
- It enables the Pipe charging function.

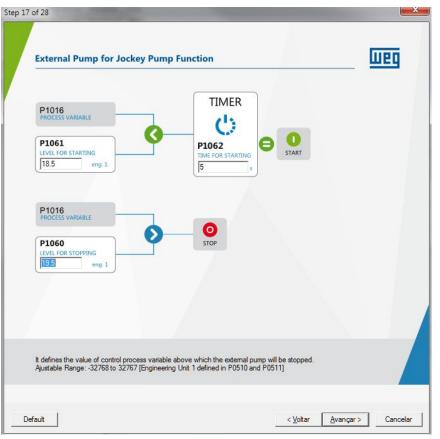


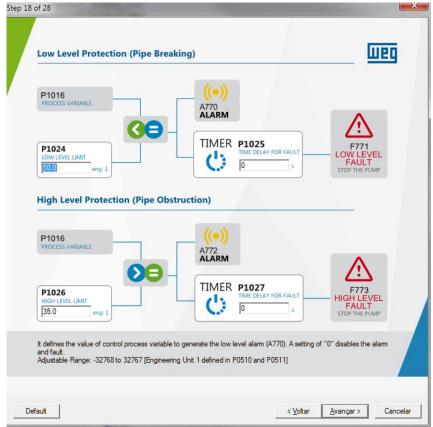


External Pump and Pump protection by Process Variable Level



- The external pum(small pump) is commanded for low demand (jockey pump).
- It enables alarm/fault due to low level(broken pipe).
- It enables alarm/fault due to low high level (clogged pipe).

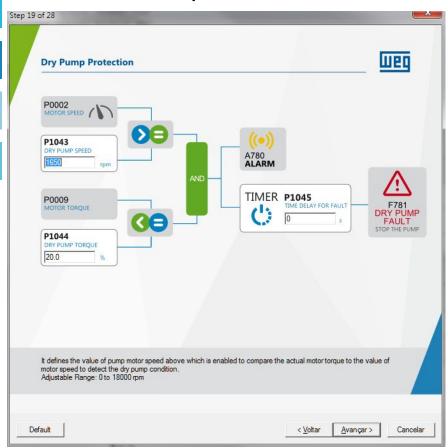


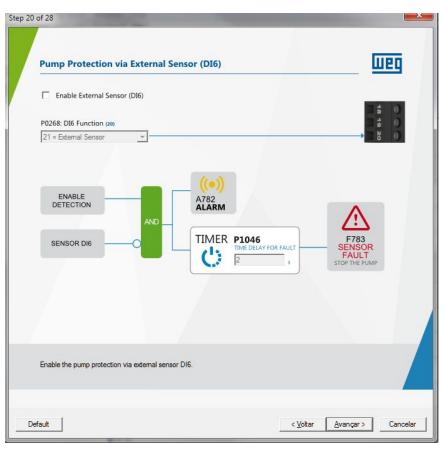


Dry Pump protection and Protection with External Sensor via DI6



- It configures the Dry Pump protection function
- It enables protection with external sensor via DI6

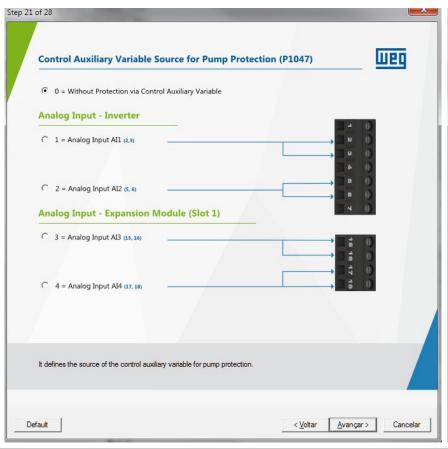


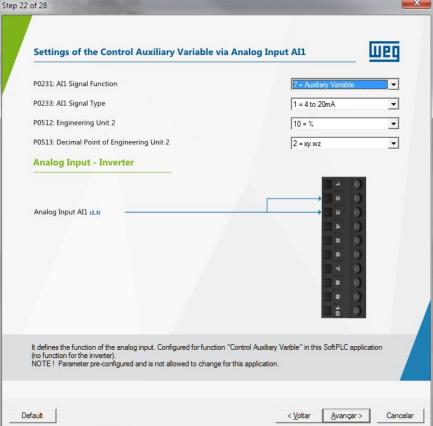




Control Auxiliary Variable

- Source of control auxiliary variable via Al
- Type of the signal in the AI
- Engineering Unit of the sensor

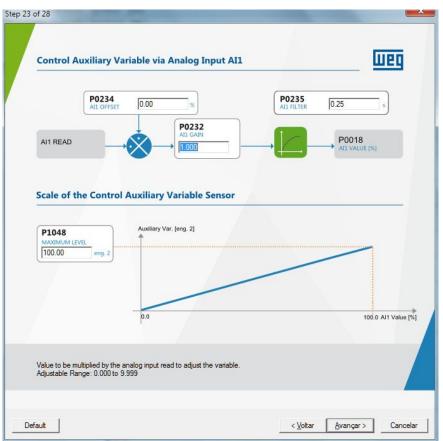


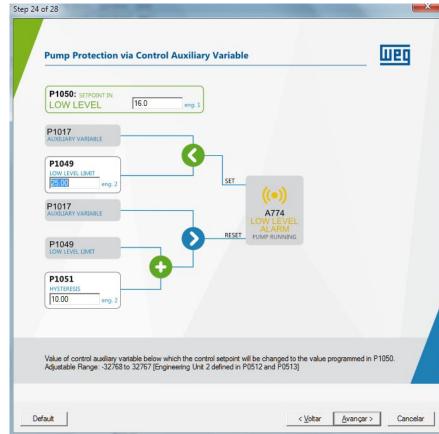




Control Auxiliary Variable

- It adjusts the readings in the AI(gains).
- Scaling of the sensor.
- It configures the pump protection against Cavitation.

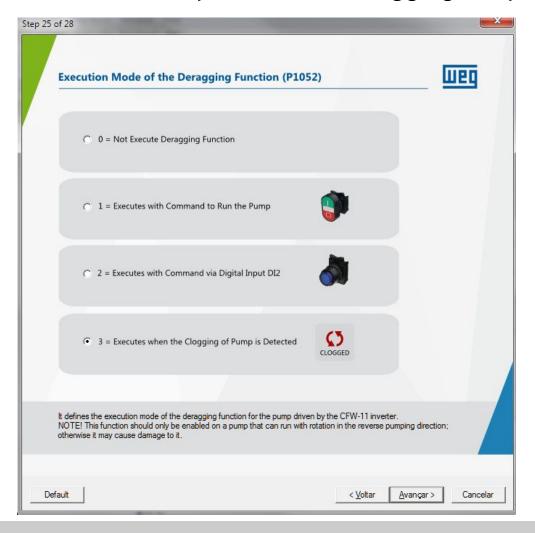






Pump Unclogg function

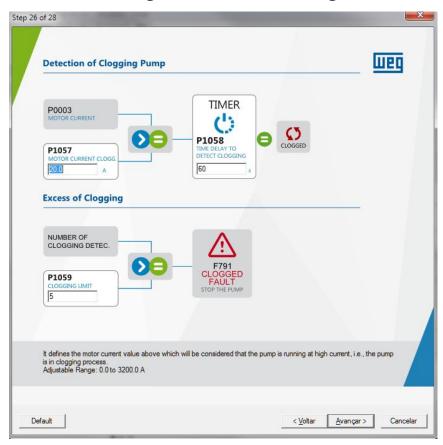
It executes a process of unclogging the pump.

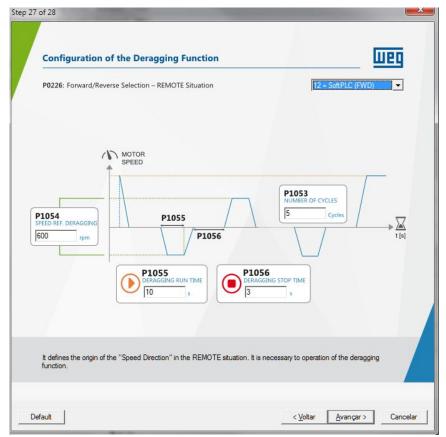




Pump Unclogg function

- It configures the detection of the clogging.
- It enables the fault by excess of clogging.
- It configures the unclog function

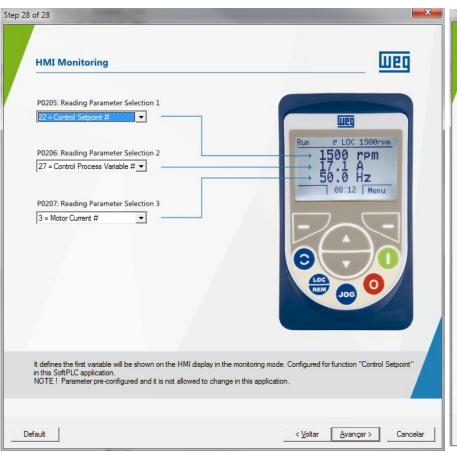


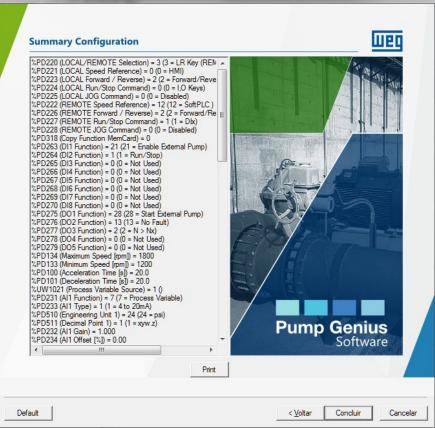




Monitoring Screen via HMI and Summary

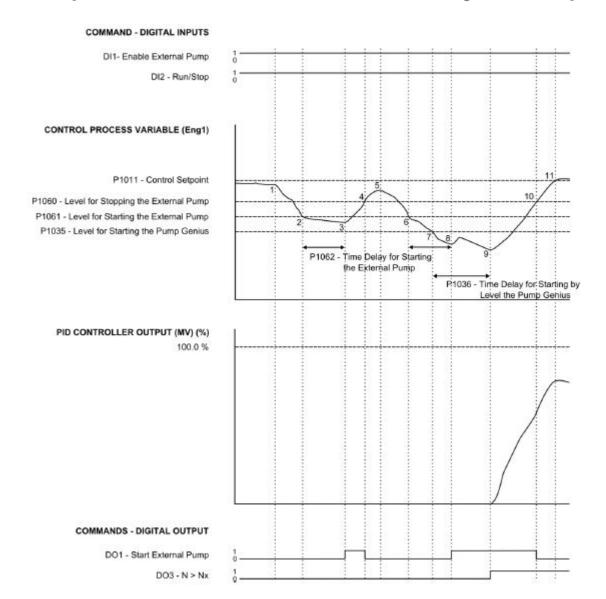
- It configures parameters to be shown on the keypad
- It sumarizes the programming to be loaded in the drive.





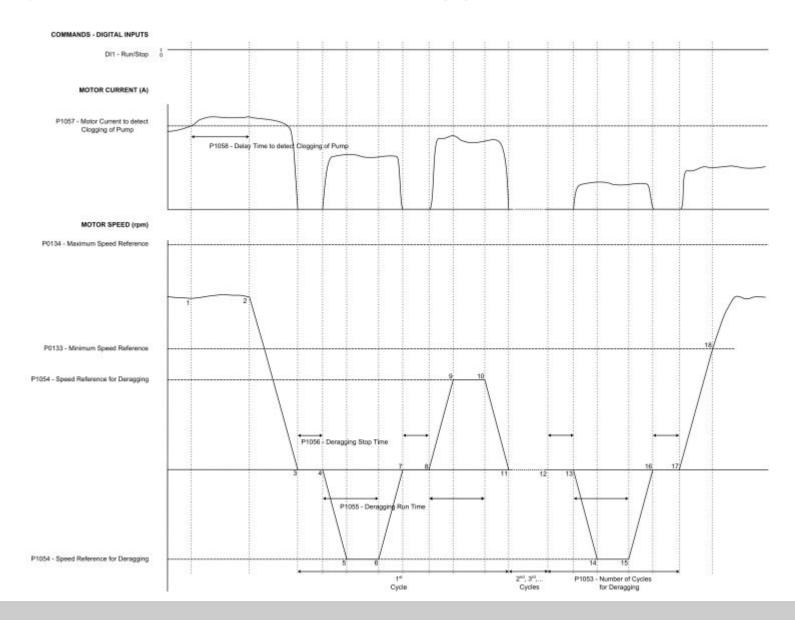


System Operation – Use of Jockey Pump





System Operation – Unclogg function

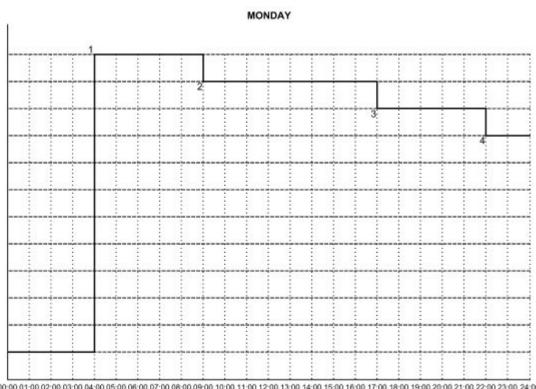




System Operation – Setpoint based in time scheduled

CONTROL SETPOINT (Eng1)

P1066 - Control Setpoint of Schedule 1 P1069 - Control Setpoint of Schedule 2 P1072 - Control Setpoint of Schedule 3 P1075 - Control Setpoint of Schedule 4 P1078 - Control Setpoint of Schedule 5 P1081 - Control Setpoint of Schedule 6 P1084 - Control Setpoint of Schedule 7 P1087 - Control Setpoint of Schedule 8 P1090 - Control Setpoint of Schedule 9 P1093 - Control Setpoint of Schedule 10 P1096 - Control Setpoint of Schedule 11 P1099 - Control Setpoint of Schedule 12



00:00 01:00 02:00 03:00 04:00 05:00 08:00 07:00 08:00 07:00 08:00 10:00 11:00 12:00 13:00 14:00 15:00 16:00 17:00 18:00 19:00 20:00 21:00 22:00 23:00 24:00

(HH:MM)

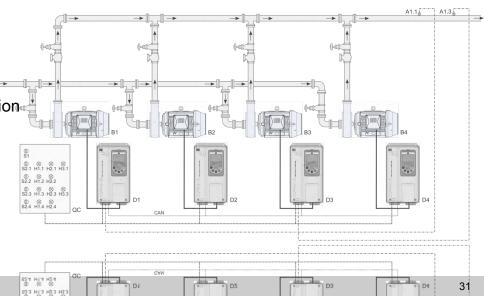


Pump Genius Multiplex

Pump control where each of the pump is driven by its own VFD with the capability for each of the pumps to work as master/slave (lead/lag configuration).

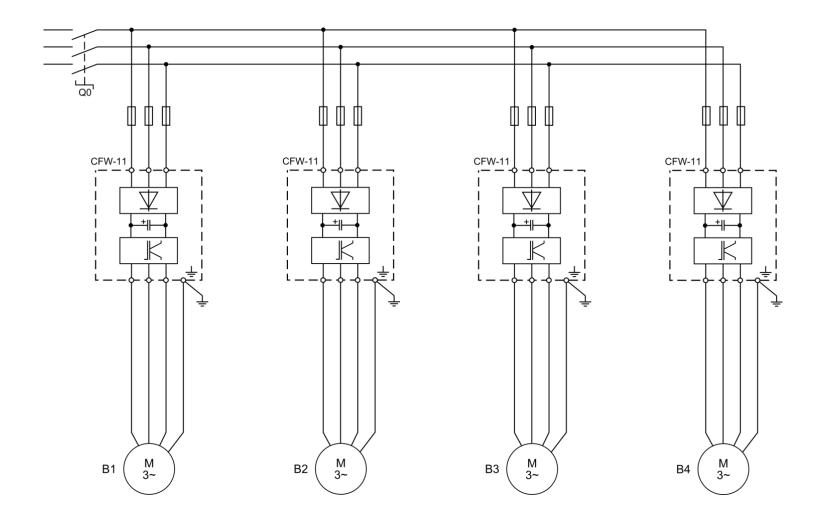
Main features:

- Control of up to 6 pumps in paralell.
- Control Setpoint can be via logical combination of Dls(Dl4/Dl5), Al, HMI.
- Communication between pumps via RS-485/CAN interface
- Configuration of each pump to be Master/Slave or Slave
- Logic to guarantee equal use of all pumps
- Master Swap in case communication loss is detected or broken sensor wire.
- PID control
- Sleep/Wake-up Mode and Start by Level
- Pipe filling function
- Process Variable can be through one AI or Differential
- Several Engineering Units to choose
- Broken /Clogged Pipe Functions
- Force Rotation function
- Dry Pump protection
- High/Low Level alarms
- Open application for customer's customization



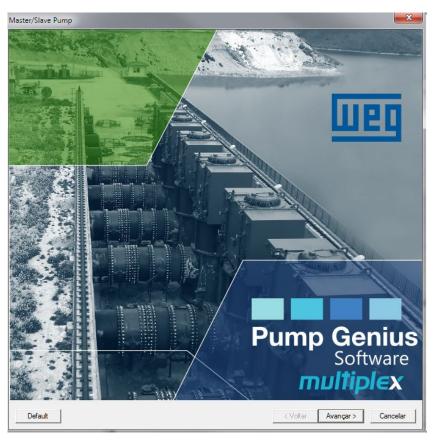


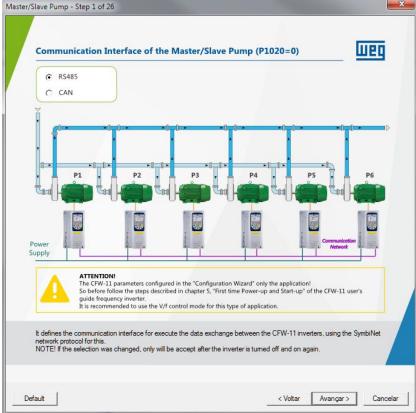
Power Diagram





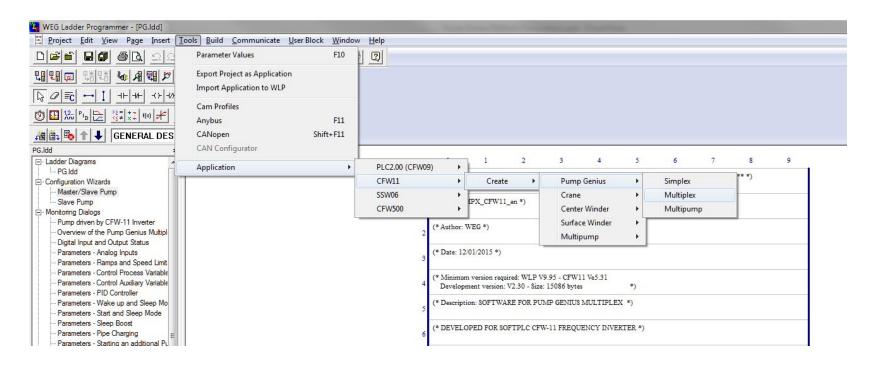
Introduction Screen





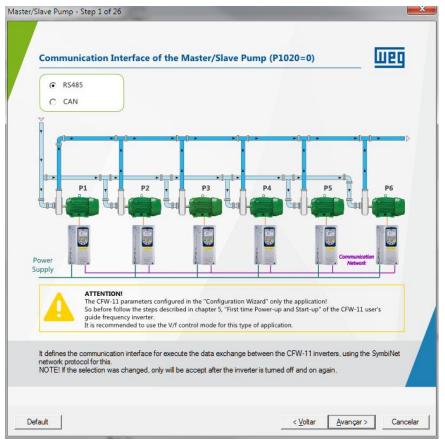


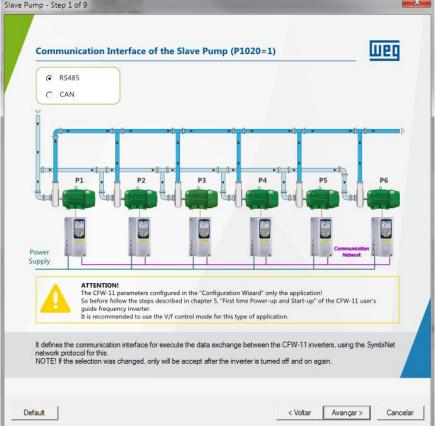
How to open the application Pump Genius Multiplex





- It selects the pump to be Master/Slave and Communication interface.
- It selects the pump to be Slave and Communication interface.







Communication Interface(Symbinet)

- It configures the Communication with RS-485.
- It configures the Communication with CAN.

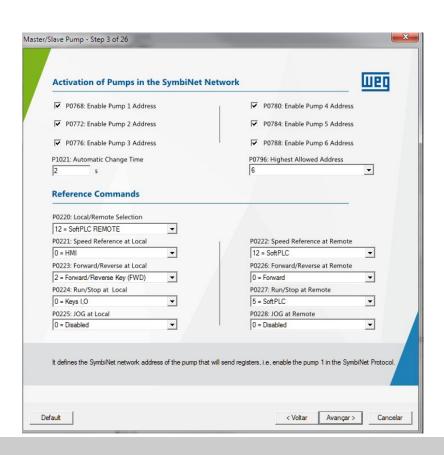




Activation of pumps in the system and Source **WEQ** of commands



- It configures the address of each pump in the Symbinet communication.
- It configures the time for swapping master automatically.
- Source of commands at Local and Remote modes to the VFD.





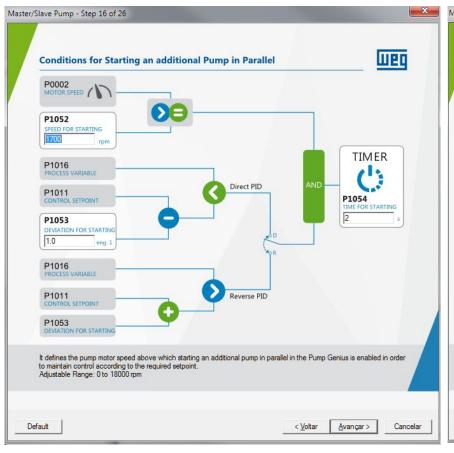
Master Pump Swapping

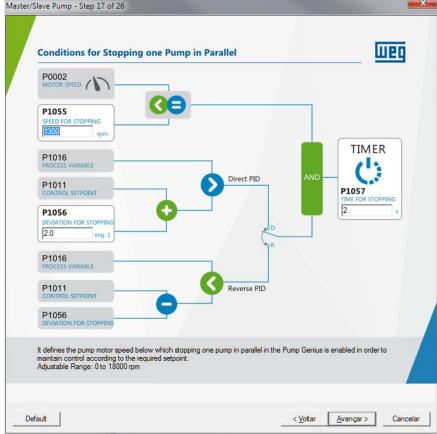
- In case there is a communication loss with the pump configured as Master a message(A758) will come on the keypad "Change Master Pump? Y(Yes)/N(No)". For the pumps configured as Slave a message(A762) will come on the keypad "loss of master".
- The master swapping can be setup to happen through the HMI or automatically based on the time defined by P1021.
- When a command for swapping master is recognized a reset is generated and a routine of acknowledgment of the Symbinet communication is performed(A764).
- Based on the priority pump 1> pump 2> pump 3> pump 4> pump 5> pump 6) a verification for another pump to become the master is performed. Only pumps programmed as master/slave(P1020=0) and that have the Analog Input setup to be process variable can be nominated master.



Turn on/off Paralell Pumps

Conditions to turn the paralell pump on and off.

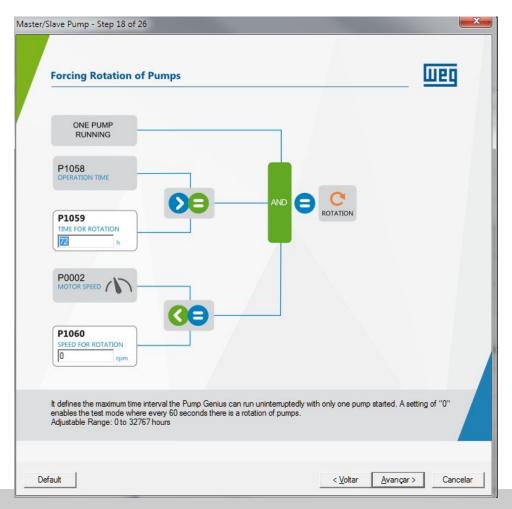






Force Rotation of Pumps

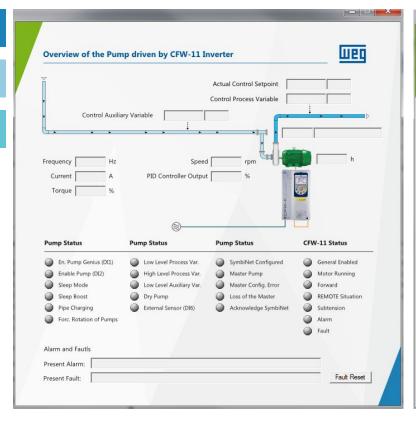
It configures the conditions to force rotation of the pumps. All the pumps are turned off and the one that has run the least is started.

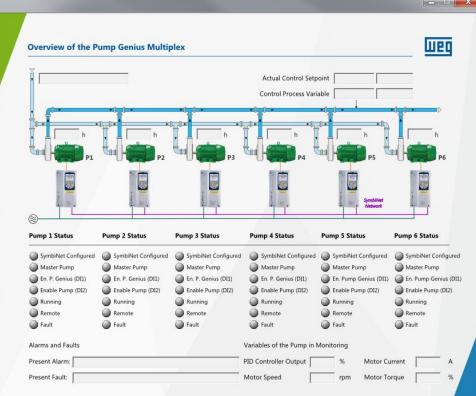




Monitoring Window

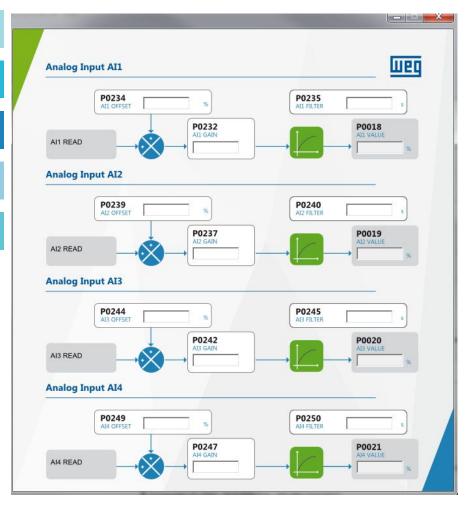
It guides the user during the comissioning bringing to the screen the most importante control variables, status of the system as well as on-line operation.

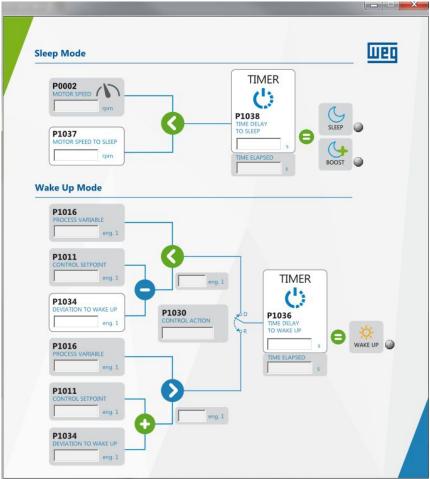






Monitoring Window



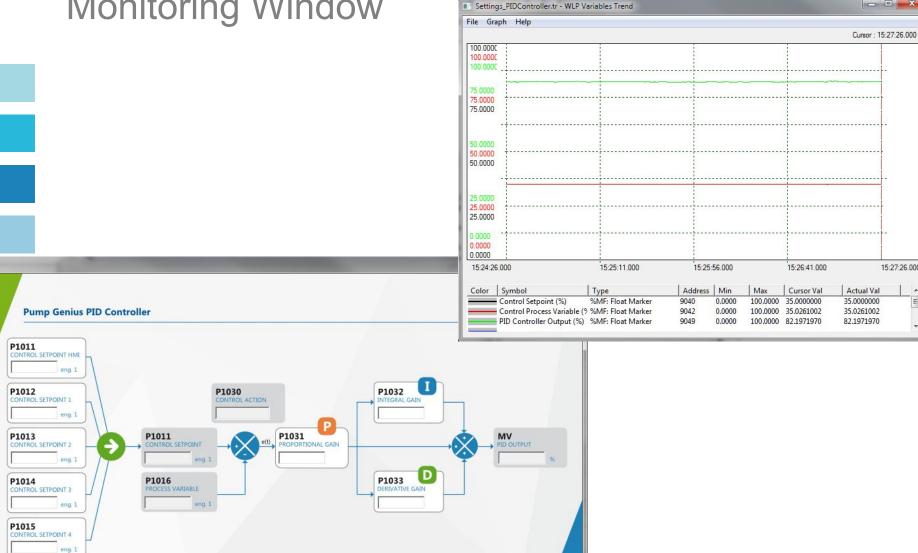




- - X

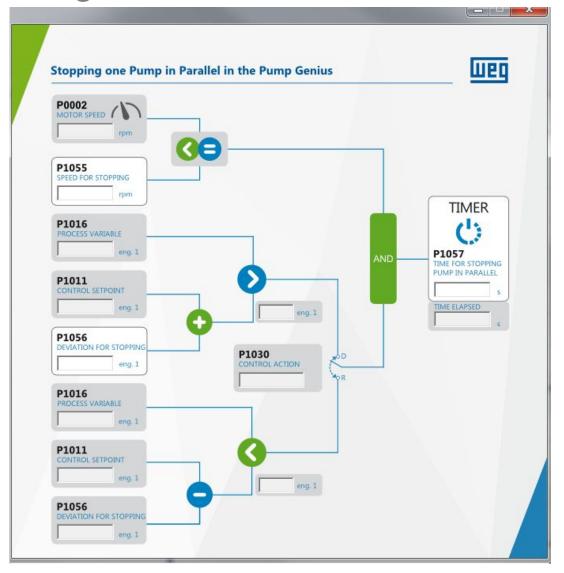
15:27:26.000

Monitoring Window



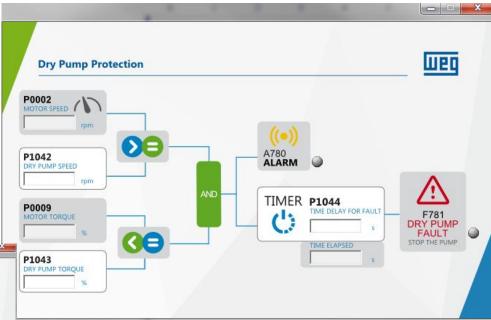


Monitoring Window





Monitoring Window X Weg Low Level Protection (Pipe Breaking) P1016 PROCESS VARIABLE A770 ALARM eng. 1 TIMER P1027 P1026 LOW LEVEL FAULT TIME ELAPSED High Level Protection (Pipe Obstruction) P1016 A772 ALARM TIMER P1029 F773 P1028 TIME DELAY FOR FAULT HIGH LEVEL





System Operation – One Master one Slave

XC1 Terminal Strip Default Function for Master/Slave Pump (Pump 1) and RS485 Interface Positive reference for potentiometer 2 Al1+ Analog input 1 (4-20 mA): Control process variable 3 4 Negative reference for potentiometer REE-5 Analog input 2 (0-10 V): No function Al2-AO1 Analog output 1: Motor speed 8 AGND 9 ACC Analog output 2: Motor current AGND 10 11 DGND Reference (OV) for the 24 VDC power supply 12 COM Common point of the digital inputs 13 24VDC 24 VDC power supply 14 COM Common point of the digital inputs Digital input 1: Enable Pump Genius DI2 Digital input 2: Enable the use of the pump DI3 Digital input 3: No function 18 DI4 Digital input 4: No function 19 Digital input 5: No function DI5 Digital input 6: No function DI6 NC1 22 C1 Digital output 1 DO1 (RL1): No fault 23 NO₁ NC2 C2 Digital output 2 DO2 (RL2): N > Nx NO2 NC3 28 C3 Digital output 3 DO3 (FL3): A770/A772 or F771/F773 (SoftPLC) NO3 XC7 Terminal Strip A-Line (-) PxD/TxD negative B-Line (+) PxD/TxD positive (M isolated from the RS485 circuit Ground Ground (shield)

Control Schematic for Master Control Schematic for Slave

	XC1 Terminal Strip		Default Function for Slave Pump (Pump 2) and RS485 Interface	
	.1	REF+	Positive reference for potentiometer	
	2	Al1+		
	3	Al1-	Analog input 1 (0-10 V): No function	
	4	REF-	Negative reference for potentiometer	
	5	Al2+		
	6	At2-	Analog input 2 (0-10 V): No function	
	7	AO1		
	8	AGND	Analog cutput 1: Motor speed	
	9	AO2		
	10 /	AGND	Analog output 2: Motor current	
	11 I	DGND	Reference (0 V) for the 24 VDC power supply	
2	12	сом	Common point of the digital inputs	
	13 2	24VDC	24 VDC power supply	
	14	COM	Common point of the digital inputs	
4.75.000.000.000.000	15	DH	Digital input 1: No function	
	16	DI2	Digital input 2: Enable the use of the pump	
	17	DI3	Digital input 3: No function	
	18	DI4	Digital input 4: No function	
	19	DI5	Digital input 5: No function	
	20	DI6	Digital input 6: No function	
	21	NC1		
1~ 220V	22	C1	Digital output 1 DO1 (RL1): No fault	
—⊗ ^{H1.2}	23	NO1	300000000000000000000000000000000000000	
	24	NC2		
	25	C2	Digital output 2 DO2 (RL2): N > Nx	
₩H2.2	26	NO2	A. C.	
V	27	NC3		
	28	C3	Digital output 3 DO3 (RL3): No function	
	29	NO3	The second decision of the second sec	
	XC7 Termin	nal Strip		
	. 1 A	-Line (-)	RxD/TxD negative	
:/-	2 B-	Line (+)	RxD/TxD positive	
	3	GND	OV isolated from the RS485 circuit	
	4 0	Ground	Ground (shield)	



System Operation – One Master one Slave

COMMANDS - DIGITAL INPUTS

S1- Enable Pump Genius

S2.1 - Enable Pump 1

S2.2 - Enable Pump 2



COMMANDS - SYMBINET NETWORK

Start Pump 1

Start Pump 2

SPEED OF PUMP 1 (rpm)

P0134 - Maximum Speed Reference

P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel

P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference

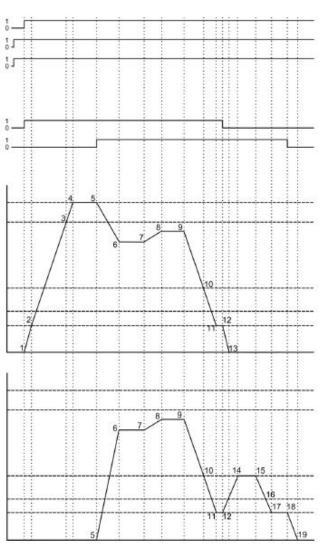
SPEED OF PUMP 2 (rpm)

P0134 - Maximum Speed Reference

P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel

P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference





System Operation – One Master Two Slaves

XC1 Terminal Strip Default Function for Master/Slave Pump (Pump 1) and RS485 Interface REF+ Positive reference for potentiomete 4-20mA Analog Input 1 (4-20 mA): Control process variable 3 Al1-4 BEE-Negative reference for potentiometer 5 Al2+ Analog Input 2 (0-10 V): No function 6 AI2-7 AO1 Analog output 1: Motor speed 8 AGND 9 AO2 Analog output 2: Motor current 10 11 DGND Reference (0 V) for the 24 VDC power supply Common point of the digital inputs 13 24VDC 24 VDC power supply Common point of the digital inputs Digital Input 1: Enable Pump Genius Digital Input 2: Enable the use of the pump Digital Input 3: No function 18 Digital Input 4: No function 19 DI5 Digital Input 5: No function Digital Input 6: No function 20 21 NC1 Digital output 1 DO1 (RL1): No fault 24 NC2 25 C2 Digital output 2 DO2 (RL2): N > Nx NO2 NC3 C3 Digital output 3 DO3 (RL3): A770/A772 or F771/F773 (SoftPLC) NO3 XC7 Terminal Strip PXD/TXD negative B-Line (+) PxD/TxD positive OV isolated from the RS485 circuit Ground (shield)

Figure 2.8 - Terminal strip XC1 and XC7 for master/slave pump (Pump 1) and FIS485 Interface

Control Schematic for Master Control Schematic for Slaves

	XC1 T	erminal Strip	Default Function for Slave Pump (Pump 2) and RS485 Interface	
	1	REF+	Positive reference for potentiometer	
	2	Al1+	Analog input 1 (0-10 V): No function	
	3	Al1-		
	4	REF-	Negative reference for potentiometer	
	5	Al2+		
	6	Al2-	Analog Input 2 (0-10 V): No function	
	7	AO1	Andrew word A Management	
	8	AGND	Analog output 1: Motor speed	
	9	AO2	100 1000	
	10	AGND	Analog output 2: Motor current	
	11	DGND	Reference (0 V) for the 24 VDC power supply	
	12	ООМ	Common point of the digital inputs	
	13	24VDC	24 VDC power supply	
	14	COM	Common point of the digital inputs	
	52.2	Dit	Digital Input 1: No function	
	16	DI2	Digital Input 2: Enable the use of the pump	
	17	DIS	Digital Input 3: No function	
	18	DI4	Digital Input 4: No function	
	19	DI5	Digital Input 5: No function	
	20	DI6	Digital Input 6: No function	
2000	21	NC1		
220V	22	C1	Digital output 1 DO1 (FIL1): No fault	
—⊗ ^{H1.2}	11.2	NO1		
	24	NC2		
	25	C2	Digital output 2 DO2 (FIL2): N > Nx	
— ⊗ [†]	12.2	NO2		
	27	NC3		
	28	СЗ	Digital output 3 DOS (RLS): No function	
	29	NO3	100000	
	XC7 T	erminal Strip		
	1	A-Line (-)	PxD/TxD negative	
A	2	B-Line (+)	PkD/TxD positive	
1	3	GND	OV isolated from the RS485 circuit	
1	4	Ground	Ground (shield)	



System Operation – One Master Two Slaves

Starting the Pumps

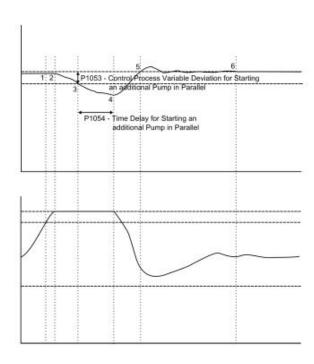
CONTROL PROCESS VARIABLE (Eng1)

P1011 - Control Setpoint

SPEED OF PUMP (rpm)

P0134 - Maximum Speed Reference P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P0133 - Minimum Speed Reference



COMMANDS - DIGITAL INPUTS

S1- Enable Pump Genius S2.1 - Enable Pump 1

> S2.2 - Enable Pump 2 S2.3 - Enable Pump 3

COMMANDS - SYMBINET NETWORK

Start Pump 2

Start Pump 3

Start Pump 1

SPEED OF PUMP 1 (rpm)

P0134 - Maximum Speed Reference P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel

P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference

SPEED OF PUMP 2 (rpm)

P0134 - Maximum Speed Reference

P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel

P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference

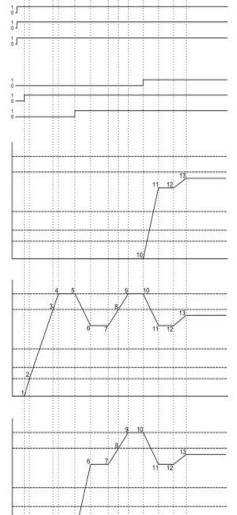
SPEED OF PUMP 3 (rpm)

P0134 - Maximum Speed Reference

P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel

P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference





System Operation – One Master Two Slaves

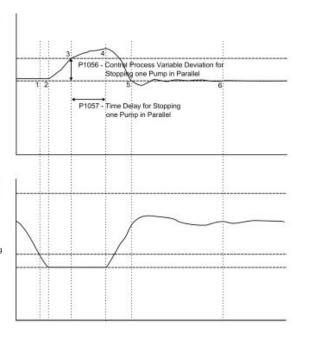
Stopping the Pumps

CONTROL PROCESS VARIABLE (Eng1)

P1011 - Control Setpoint

SPEED OF PUMPS (rpm)
P0134 - Maximum Speed Reference

P1055 - Pump Motor Speed for Stopping one Pump in Parallel P0133 - Minimum Speed Reference



COMMANDS - DIGITAL INPUTS

S1- Enable Pump Genius

S2.1 - Enable Pump 1

S2.2 - Enable Pump 2

S2.3 - Enable Pump 3

COMMANDS - SYMBINET NETWORK

Start Pump 1

Start Pump 2

Start Pump 3

SPEED OF PUMP 1 (rpm)

P0134 - Maximum Speed Reference

P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel

P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference

SPEED OF PUMP 2 (rpm)

P0134 - Maximum Speed Reference

P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel

P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference

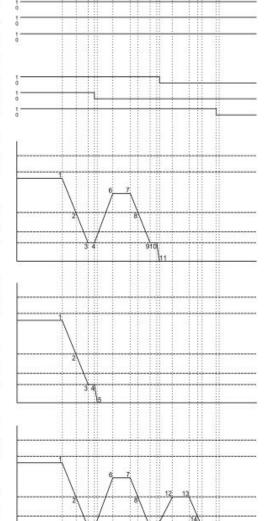
SPEED OF PUMP 3 (rpm)

P0134 - Maximum Speed Reference

P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel

P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference





System Operation – Two Masters Two Slaves

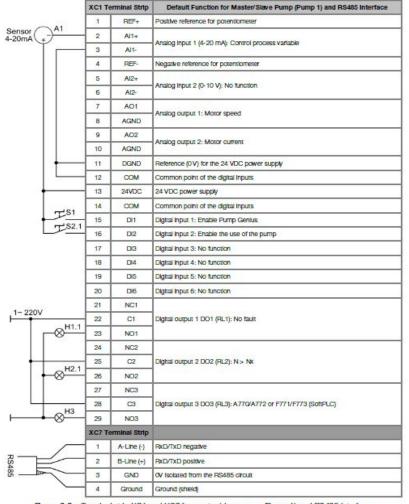


Figure 2.8 - Terminal strip XC1 and XC7 for master/slave pump (Pump 1) and FIS485 Interface

Control Schematic for Masters Control Schematic for Slaves

	XC1 T	erminal Strip	Default Function for Slave Pump (Pump 2) and RS485 Interface
	1	REF+	Positive reference for potentiometer
	2	Al1+	Analog input 1 (0-10 V): No function
	3	Al1-	
	4	REF-	Negative reference for potentiometer
	5	Al2+	
	6	Al2-	Analog Input 2 (0-10 V): No function
	7	AO1	
	8	AGND	Analog output 1: Motor speed
	9	AO2	Analog output 2: Motor current
	10	AGND	
	11	DGND	Reference (0 V) for the 24 VDC power supply
	12	СОМ	Common point of the digital inputs
	13	24VDC	24 VDC power supply
	14	COM	Common point of the digital inputs
رج S2	15	DI1	Digital Input 1: No function
502	16	DI2	Digital Input 2: Enable the use of the pump
	17	DIS	Digital Input 3: No function
	18	DI4	Digital Input 4: No function
	19	DI5	Digital Input 5: No function
	20	DI5	Digital Input 6: No function
200	21	NC1	
0V	22	C1	Digital output 1 DO1 (FIL1): No fault
_—⊗ ^{H1.}	2 23	NO1	
10000	24	NC2	
702	25	C2	Digital output 2 DO2 (RL2): N > Nk
→ ⊗ ^{H2.}	2 26	NO2	
	27	NC3	
	2B	СЗ	Digital output 3 DOS (RLS): No function
	29	NO3	18 3.70
	XC7 T	erminal Strip	
///	1	A-Line (-)	PxD/TxD negative
-#-	2	B-Line (+)	PxD/TxD positive
1	3	GND	OV isolated from the RS485 circuit
1	4	Ground	Ground (shield)



System Operation – Two Masters Two Slaves

Starting the Pumps

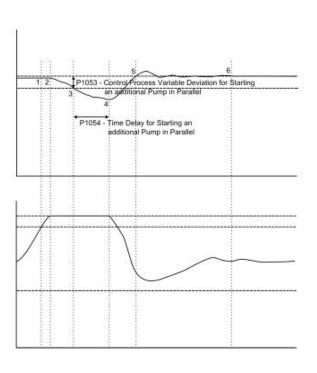
CONTROL PROCESS VARIABLE (Eng1)

P1011 - Control Setpoint

SPEED OF PUMP (rpm)

P0134 - Maximum Speed Reference P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P0133 - Minimum Speed Reference



COMMANDS - DIGITAL INPUTS S1- Enable Pump Genius

S2.1 - Enable Pump 1 S2.2 - Enable Pump 2 S2.3 - Enable Pump 3

\$2.4 - Enable Pump 4

COMMANDS - SYMBINET NETWORK

Start Pump 1

Start Pump 3 Start Pump 4

SPEED OF PUMP 1 (rpm)

P0134 - Maximum Speed Reference P1062 - Pump Motor Speed for Starting an additional Pump in Parallel

P1065 - Pump Motor Speed for Stopping one Pump in Parallel P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0135 - Minimum Speed Reference

SPEED OF PUMP 2 (rpm)

P0134 - Maximum Speed Reference P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel P1037 - Pump Motor Speed below which Pump Genius goes to Steep P0133 - Minimum Speed Reference

SPEED OF PUMP 3 (rpm)

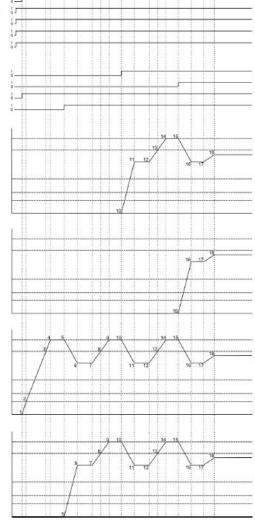
P0134 - Maximum Speed Reference P1052 - Pump Motor Speed for Starting on additional Pump in Parallel

P1055 - Pump Motor Speed for Stopping one Pump in Parallel P1037 - Pump Motor Speed below which Pump Genius goes to Sleep P0133 - Minimum Speed Reference

SPEED OF PUMP 4 (rpm)

P0134 - Maximum Speed Reference P1052 - Pump Motor Speed for Starting an additional Pump in Parallel

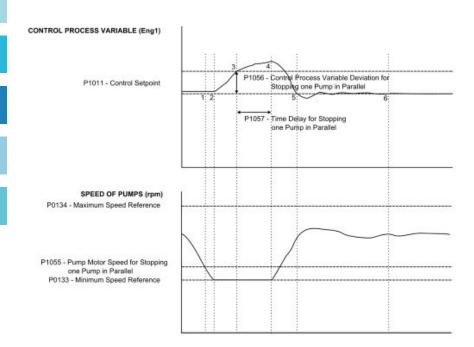
P1055 - Pump Motor Speed for Stopping one Pump in Parallel P1037 - Pump Motor Speed below which Pump Genius goes to Steep P0133 - Minimum Speed Reference

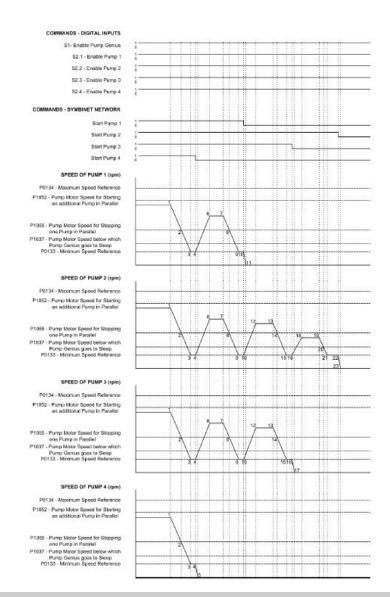




System Operation – Two Masters Two Slaves

Stopping the Pumps



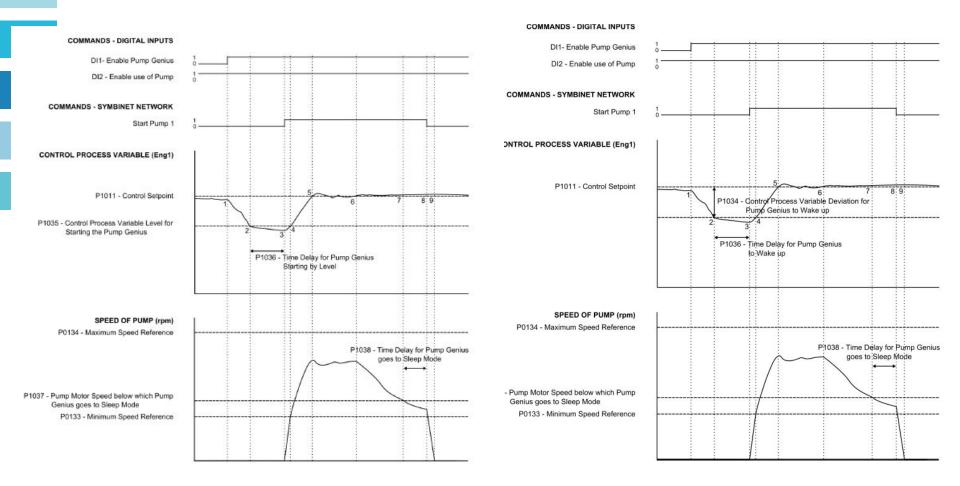




System Operation – Sleep/Wake-up Modes

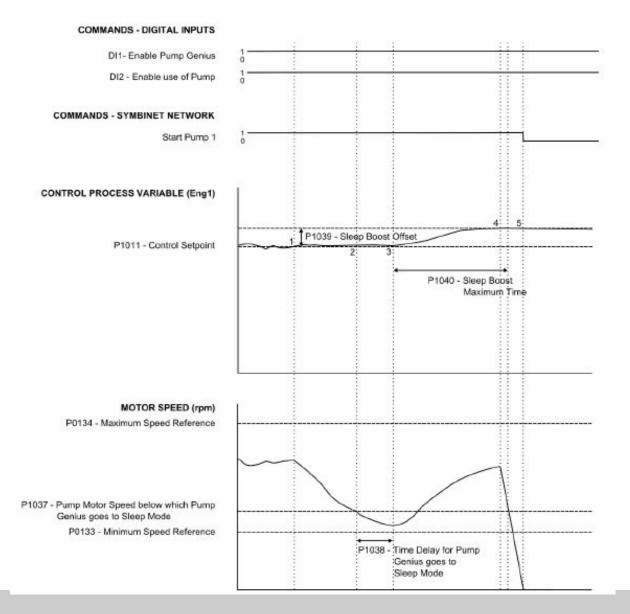
Start by Level and Sleep mode

Wake-up and Sleep mode



System Operation – Sleep mode w/ Sleep boost enabled







System Operation – PID Control

