

A decorative horizontal band of white circles is positioned above the main title. The circles are arranged in a regular grid pattern across the width of the slide.

ProfiNet

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- Overview

Overview

systemrequirements

CP1616

configuration as controller

configuration as device

configuration on robotside

Example of a installation and configuration

For using the new fieldbus ProfiNet you need the following system components

- **KRC Edition 2005**
- **Systemsoftware V 5.4.x or V 5.5.x**

ProfiNet is a ethernet based fieldbus

Device types:

Controller: is a control, which superordinate controls all components of system.

Device: is field device, which is controlled by a controller. A device comprises of several modules and sub-modules. A devices can contain several Controllers (Masters)

A physical device, such as the Robot Control can be controller and/or device. The project planning of communication devices take place exclusively at the controller side.

A project planning can be created with the folling programs and loaded on the contructions groups:

- NCM(Siemens) till firmware 2.0
- Step 7 (siemens) starting from firmware 2.1

• Siemens CP1616 in PC

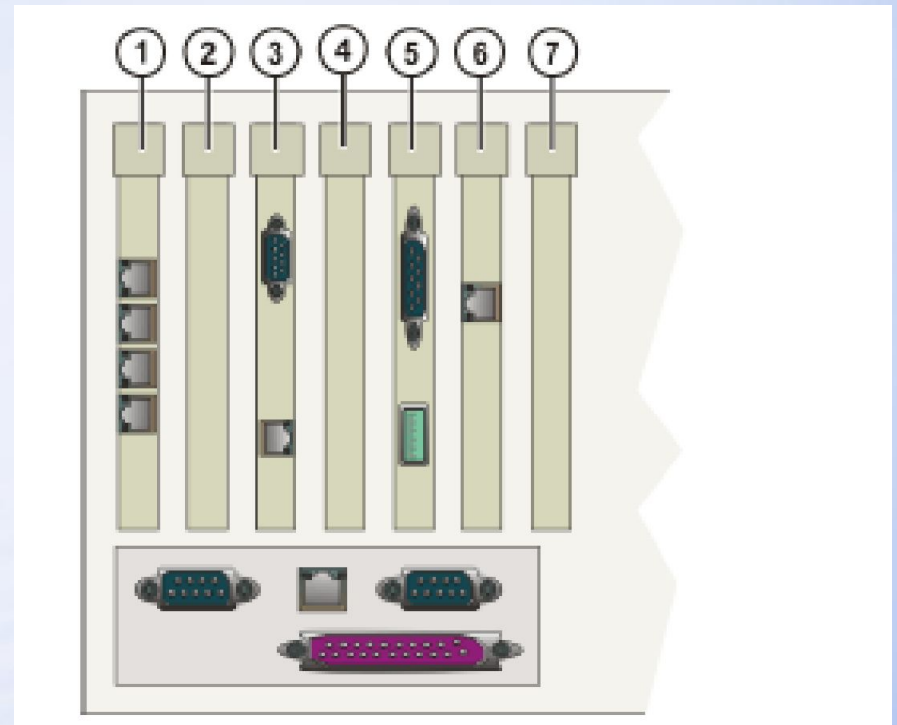
The PCI-card CP 1616 has the following properties:

- can be configured and parameterized via the network
- up to 256 devices
- Connections are designed for 10BASE-T and 100BASE-TX
- Data transmission speeds of 10 and 100 Mbit/s in full/semi-duplex mode are supported
- Operation of the CP1616 as Controller and/or Device
- Project planning with NCM 5.4 or Step 7 Software
- Use of acyclic channels
- Use of Profinet IO Communication
- Support of shared devices
- 4 RJ45-connectors for connecting terminals or other network components.
- Intergrated 4-Port-Real-Time-Switch.

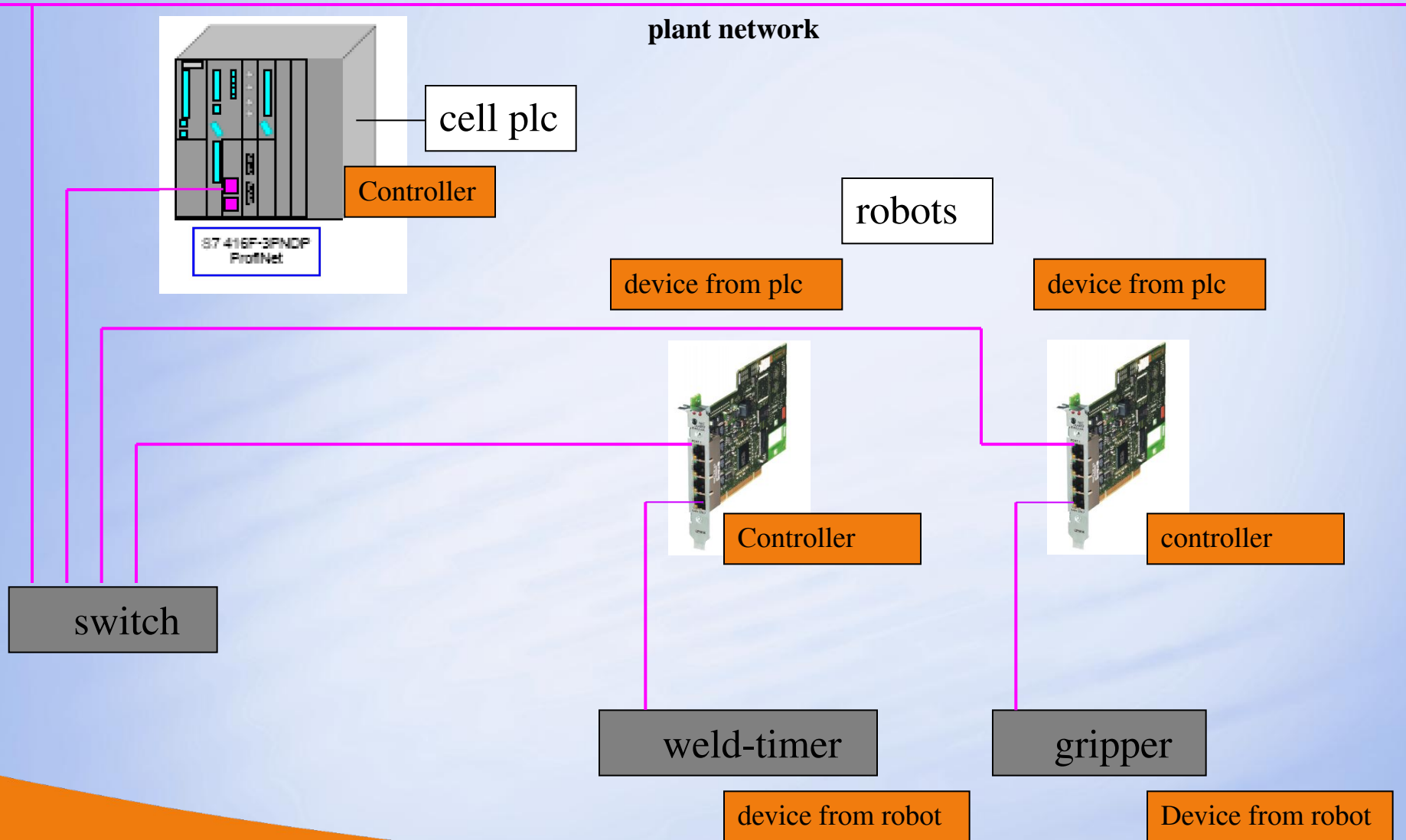


placement for CP1616 in PC

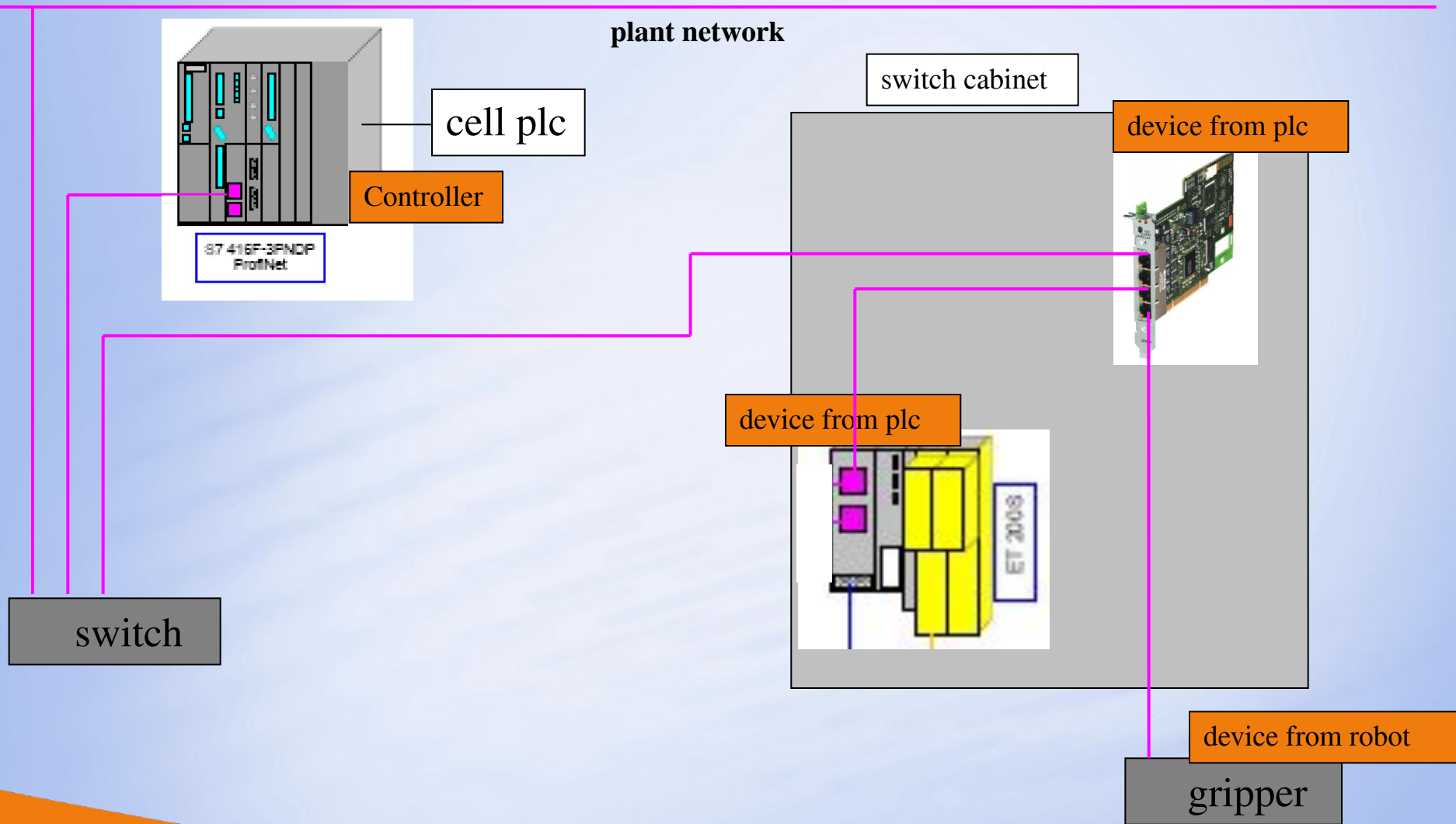
1	PCI CP1616-card ProiNet
2	free
3	KVGA-card
4	DSE-IBS-C33 Aux-card (option)
5	MFC3-card
6	Networkcard (3COM)
7	free



standard assembly in a roboter-cell



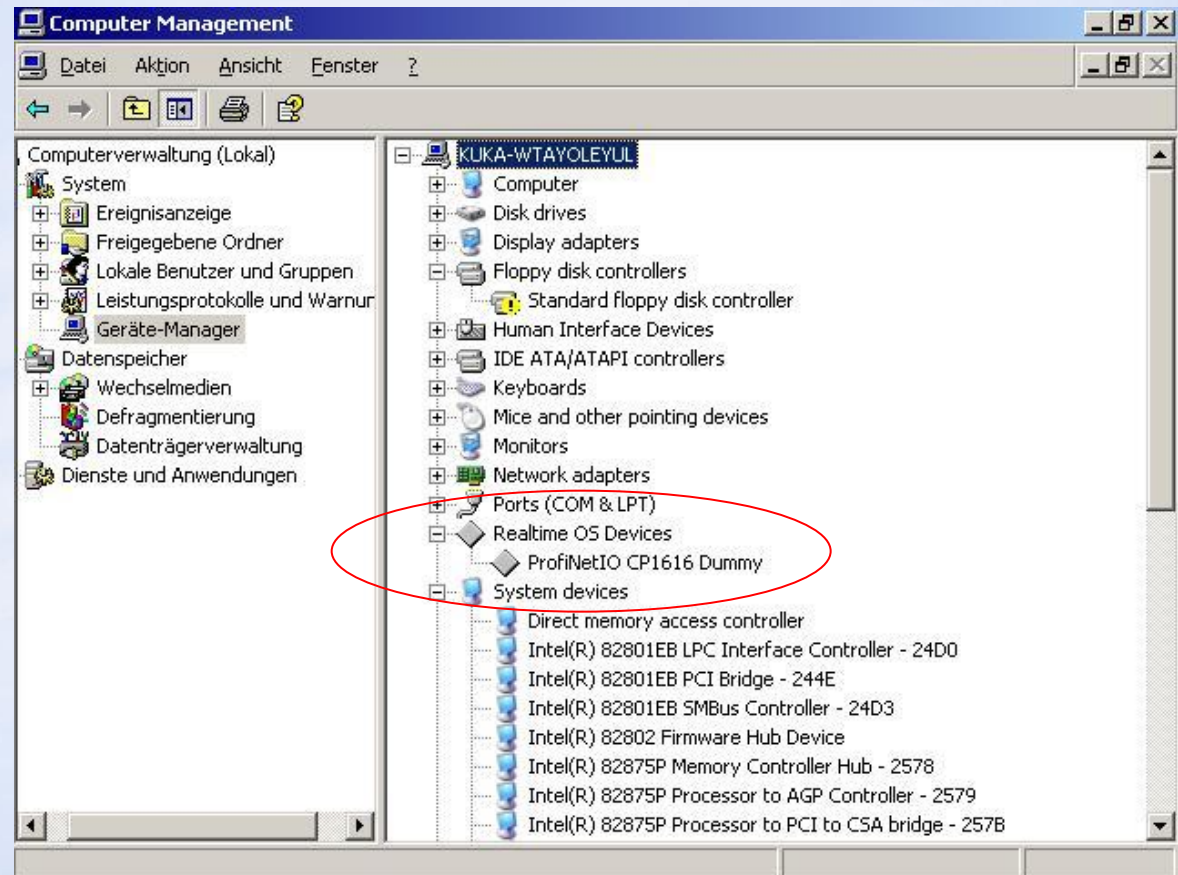
standard BMW-switch cabinet



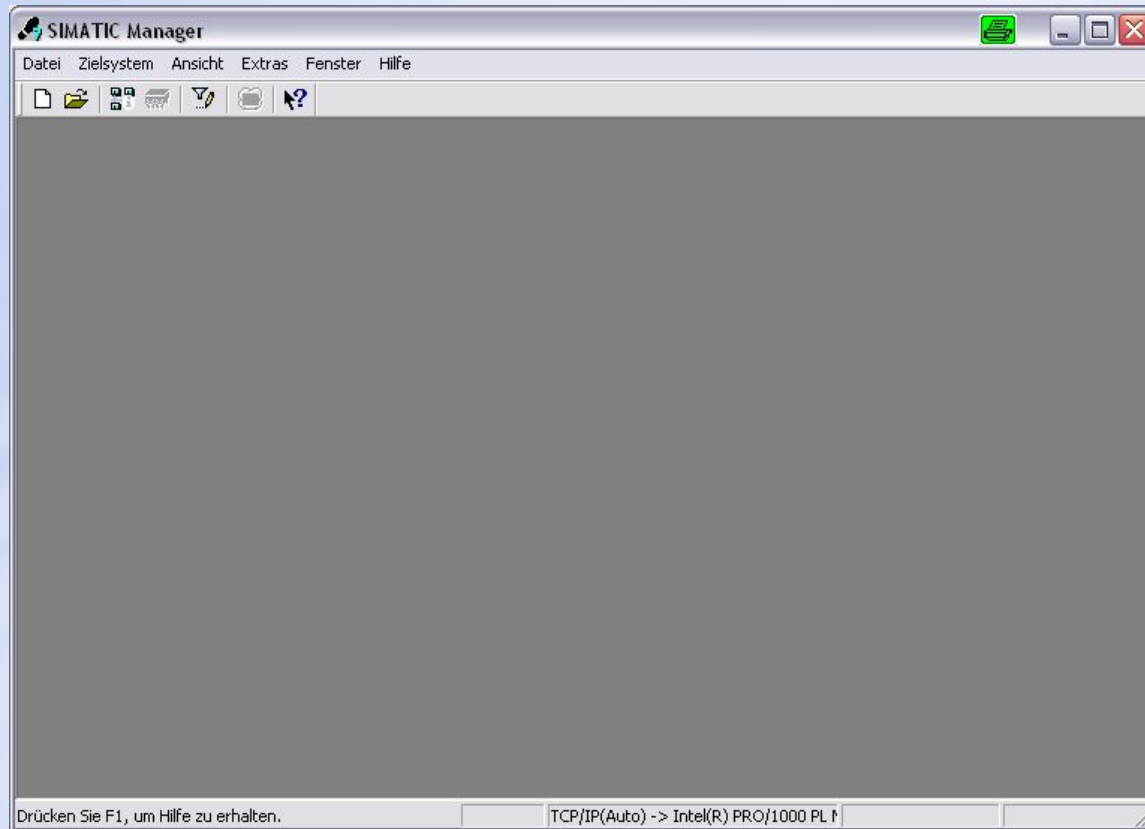
- shutdown Pc
- plug in CP1616
- start pc and stop startup in windows
- start setup.exe

The setup install all components. Drivers for windows and for VxWorks.

The setup installed a dummy driver for windows. The driver make the CP1616 invisible for windows.



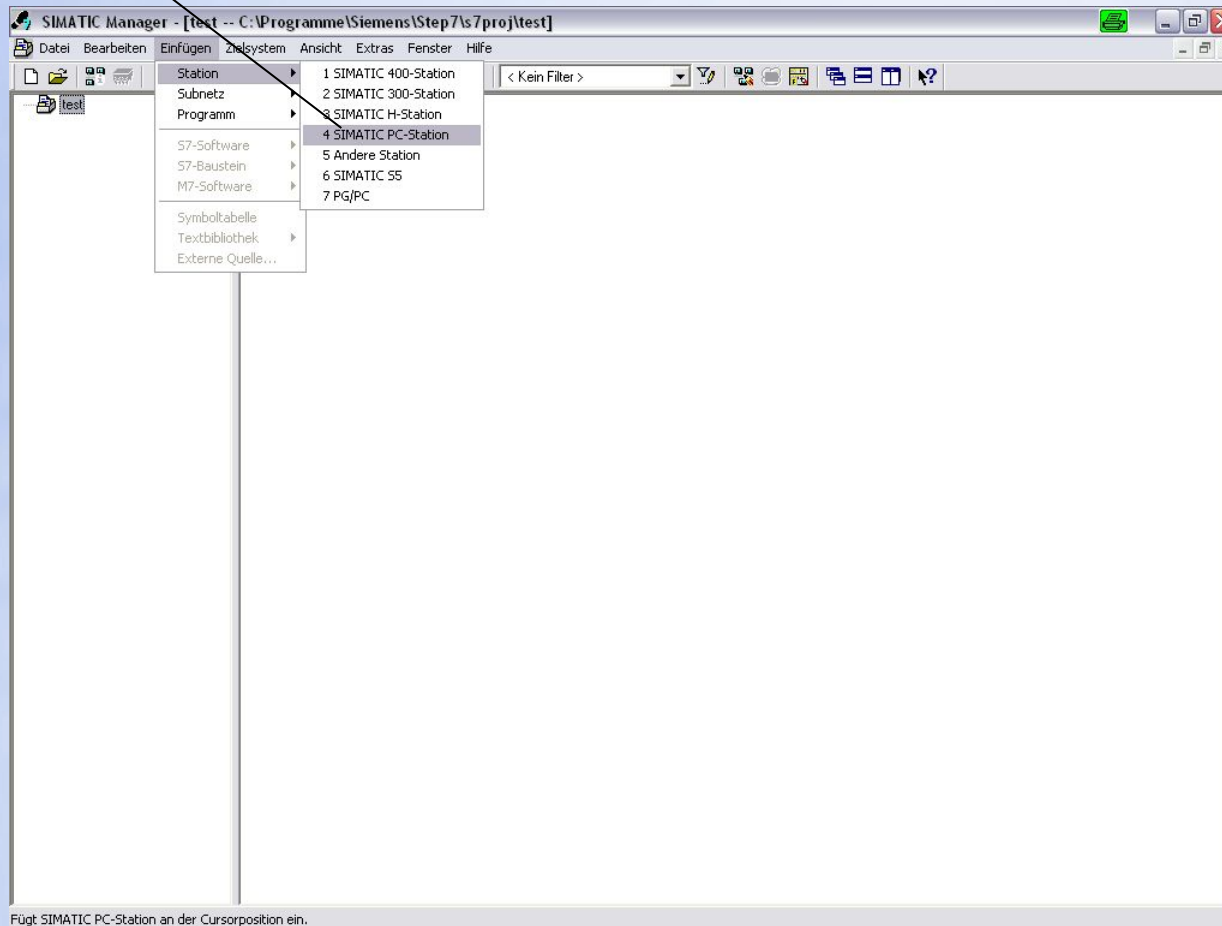
configuration roboter as contoller in Step7/NCM-Manager



configuration roboter as contoller in Step7/NCM-Manager



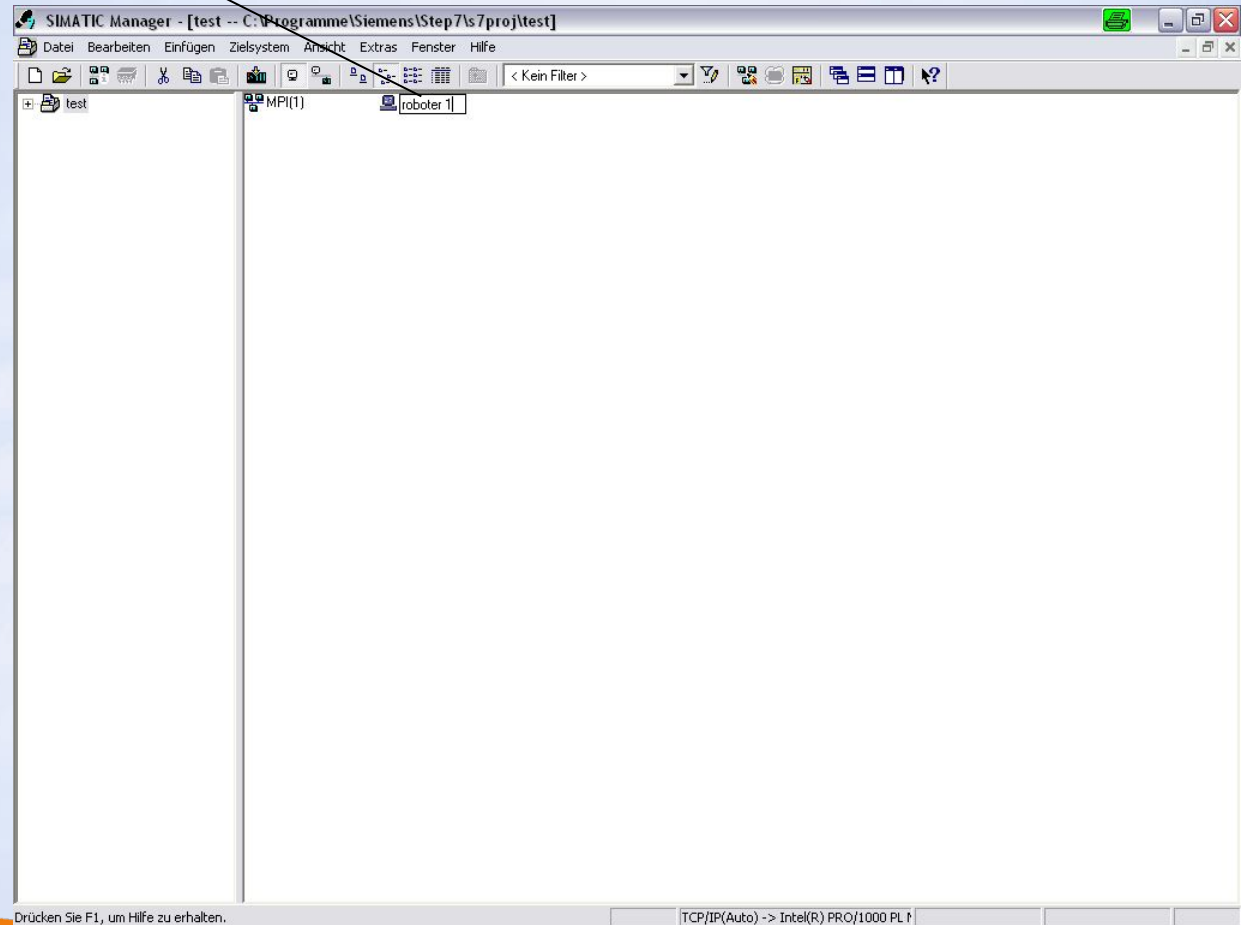
insert PC-station



configuration roboter as contoller in Step7/NCM-Manager



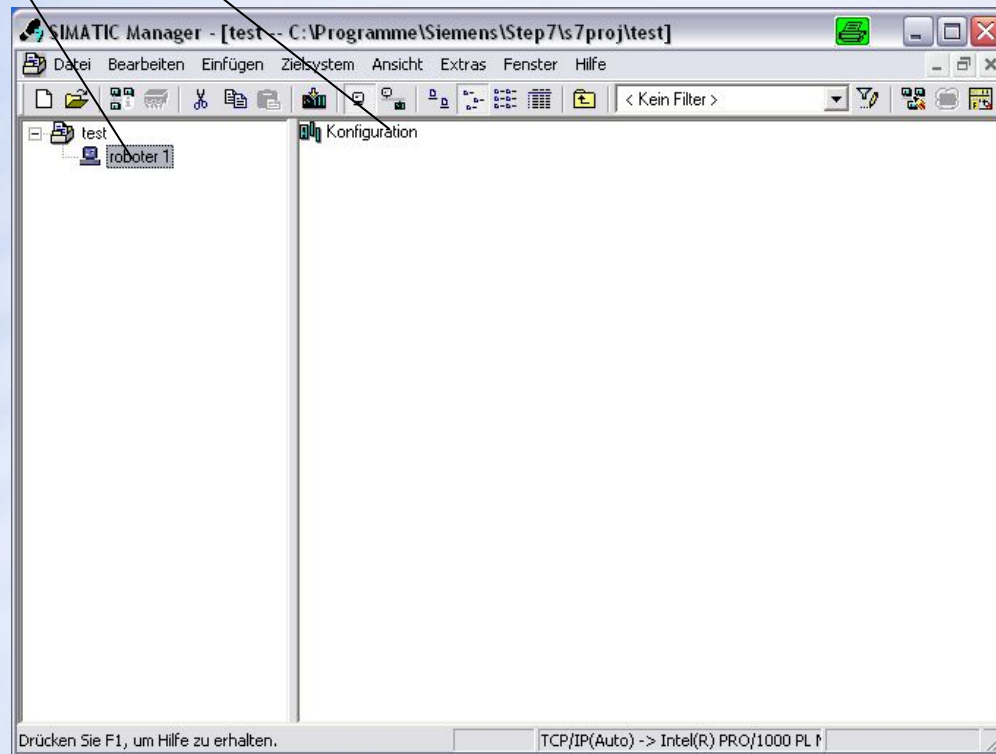
Rename station name



configuration roboter as contoller in Step7/NCM-Manager



Open station on left side and make double-click on Configuration



configuration roboter as contoller in Step7/NCM-Manager



Select CP1616-V2.1 and drop it into slot1 from pc-station

The screenshot shows the Step7/NCM-Manager software interface. The main window is titled "HW Konfig - [roboter 1 (Konfiguration) -- test]". It features a menu bar with options like "Station", "Bearbeiten", "Einfügen", "Zielsystem", "Ansicht", "Extras", "Fenster", and "Hilfe".

On the left side, there is a "PC" station view with a table showing slots 1 through 8. Slot 1 is highlighted in green. Below this is a larger table with columns: "Index", "Baugruppe", "Bestellnu...", "Fi...", "M...", and "Kommentar". The first row (Index 1) is also highlighted in green.

On the right side, there is a component library tree. The "SIMATIC PC Station" folder is expanded, showing sub-folders for "Controller" and "CP-Industrial Ethernet". Under "CP-Industrial Ethernet", various CP models are listed, including CP 1411, CP 1413, CP 1511, CP 1512, CP 1604, CP 1612, CP 1613, and CP 1616. The CP 1616 folder is expanded, showing versions V1.0, V2.0, V2.1 (PN V1.0), and V2.1 (PN V2.0). The V2.1 (PN V2.0) component is highlighted with a mouse cursor. A yellow callout box with an arrow points to this component, containing the text: "Select CP1616-V2.1 and drop it into slot1 from pc-station".

At the bottom right, there is a status bar with the text: "6GK1 161-6AA00 SIMATIC NET CP 1616 Industrial Ethernet, PROFINET IO-Controller V2.0, IO-Router, Firmware V2.1".

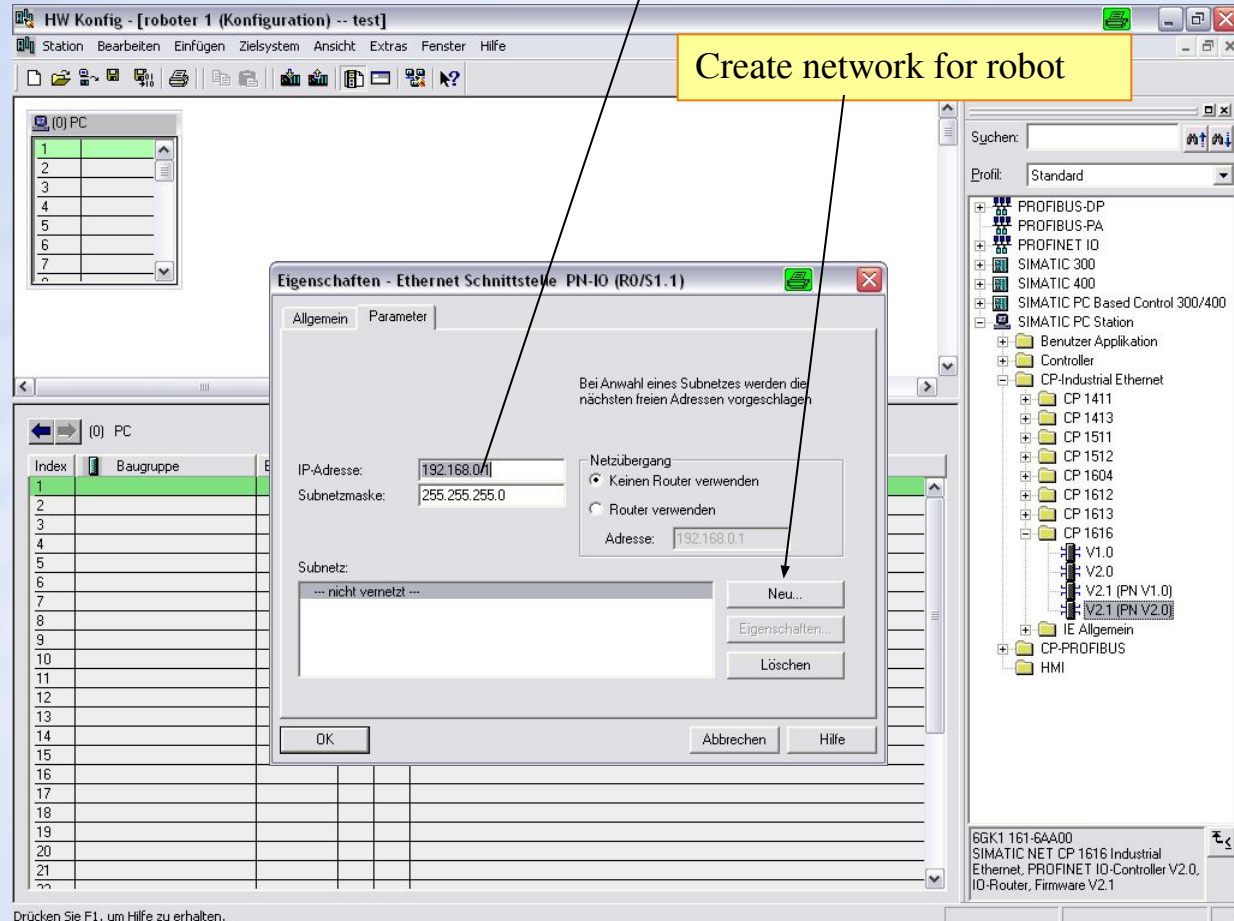
Drücken Sie F1, um Hilfe zu erhalten.

configuration roboter as contoller in Step7/NCM-Manager



define ip address for the cp1616

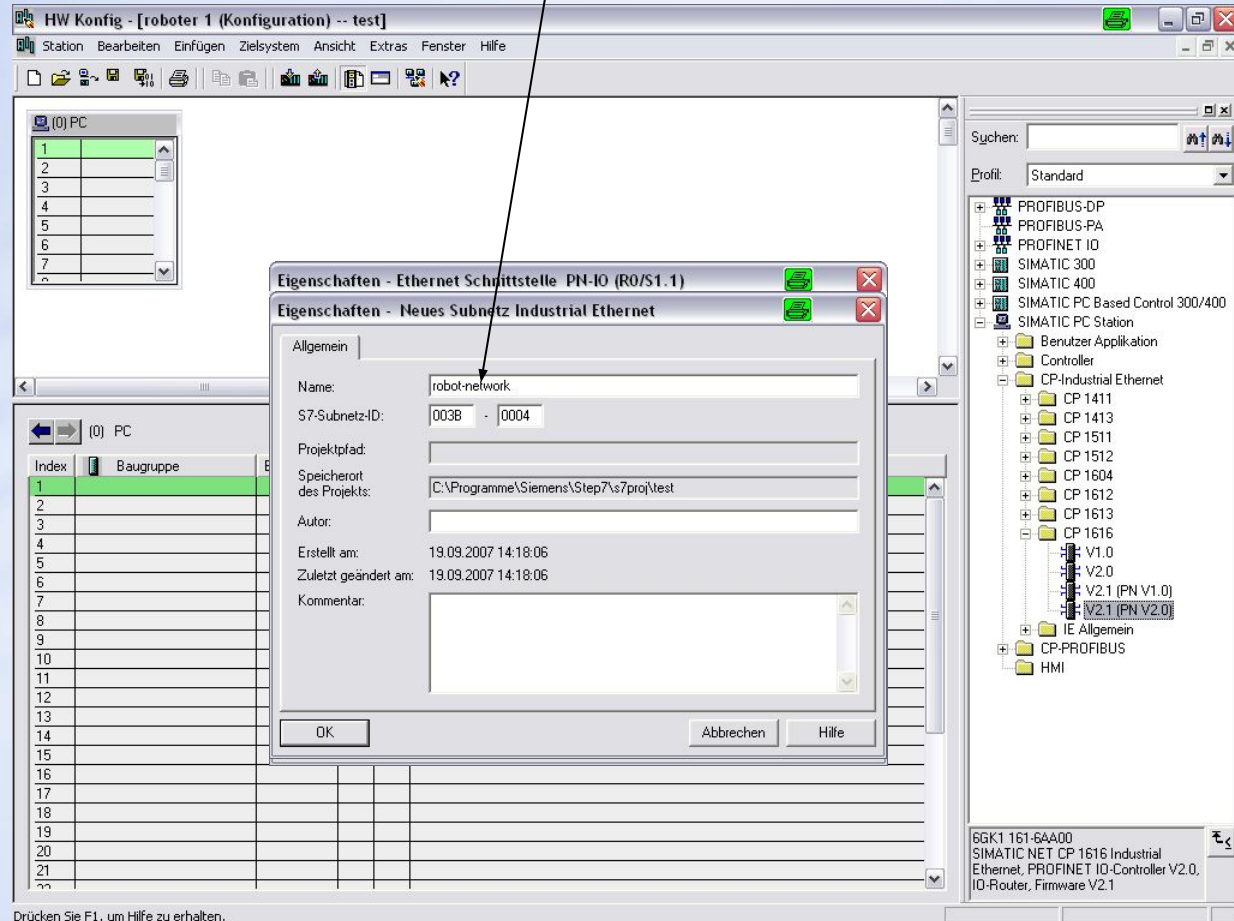
Create network for robot



configuration roboter as controller in Step7/NCM-Manager



create name for profiNet network



Drücken Sie F1, um Hilfe zu erhalten.

configuration roboter as contoller in Step7/NCM-Manager



The screenshot displays the SIMATIC Manager interface for configuring a robot controller. The main window is titled "HW Konfig - [roboter 1 (Konfiguration) -- test]". A dialog box titled "Eigenschaften - Ethernet Schnittstelle PN-IO (R0/S1.1)" is open, showing the configuration for the Ethernet interface. The dialog has two tabs: "Allgemein" and "Parameter". The "Allgemein" tab is active, showing the following fields:

- IP-Adresse: 192.168.0.1
- Subnetzmaske: 255.255.255.0
- Subnetz: -- nicht vernetzt --, robot-network
- Netzübergang: Keinen Router verwenden, Router verwenden
- Adresse: 192.168.0.1

Buttons for "Neu...", "Eigenschaften...", "Löschen", "OK", "Abbrechen", and "Hilfe" are visible. The background shows a tree view of the hardware configuration, including components like PROFIBUS-DP, PROFIBUS-PA, PROFINET IO, SIMATIC 300, SIMATIC 400, SIMATIC PC Based Control 300/400, SIMATIC PC Station, Benutzer Applikation, Controller, CP-Industrial Ethernet, CP 1411, CP 1413, CP 1511, CP 1512, CP 1604, CP 1612, CP 1613, CP 1616, V1.0, V2.0, V2.1 (PN V1.0), V2.1 (PN V2.0), IE Allgemein, CP-PROFIBUS, and HMI. The status bar at the bottom indicates the hardware is a 6GK1 161-6AA00 SIMATIC NET CP 1616 Industrial Ethernet, PROFINET IO-Controller V2.0, IO-Router, Firmware V2.1.

Drücken Sie F1, um Hilfe zu erhalten.

configuration roboter as contoller in Step7/NCM-Manager



CP1616 with ports

Robot network

The screenshot shows the SIMATIC Manager HW Config interface. The main window displays a configuration tree on the left with a CP 1616 controller and its four ports (X1, X1P1, X1P2, X1P3, X1P4). A connection line labeled "robot-network: PROFINET IO-System (100)" is shown between the controller and the network. The bottom part of the window shows a table with the following data:

Index	Baugruppe	Bestellnu...	Fl...	M...	Kommentar
1	CP 1616 V2.1 PN V2.0	6GK1 161-6V2.1			
X1	PN-IO				
X1P1	Port 1				
X1P2	Port 2				
X1P3	Port 3				
X1P4	Port 4				
2					
3					
4					
5					
6					
7					
8					
9					
10					
11					
12					
13					
14					
15					
16					
17					

The right sidebar shows a search bar and a tree view of SIMATIC components, including PROFIBUS, PROFINET, SIMATIC, and CP-Industrial Ethernet. The bottom status bar displays the part number 6GK1 161-6A400 and the description: SIMATIC NET CP 1616 Industrial Ethernet, PROFINET IO-Controller V2.0, IO-Router, Firmware V2.1.

configuration roboter as contoller in Step7/NCM-Manager



Make double-click on PN-IO

create devicename

The screenshot displays the SIMATIC Manager HW Config interface. A dialog box titled "Eigenschaften - PN-IO - (R0/S1.1)" is open, showing the configuration for a PN-IO device. The "Gerätename" field is set to "PN-IO". The "Schnittstelle" (Interface) section shows "Typ: Ethernet", "Gerätenummer: 0", "Adresse: 192.168.0.1", and "Vernetzt: ja". The background shows a project tree with "CP 1616 V2.1 PN V2.06" selected.

very important

For all devices on bus you must define a devicename. The devicename must be unique. The devicename is to define in the configuration and online over the network, directly on the SM-card on the profiNet-device.

The devicename must be the same in the configuration and on the SM-card.

configuration roboter as contoller in Step7/NCM-Manager



Make double-click on Slot 1

define, whether the CP1616 is running as Controller or Controller and Device

Index	Baugruppe
1	CP 1616 V2.1 PN V2.06
X1	PN-IO
X1P1	Port 1
X1P2	Port 2
X1P3	Port 3
X1P4	Port 4
2	
3	
4	
5	
6	
7	
8	
9	
10	
11	
12	
13	
14	
15	
16	
17	

OK Abbrechen Hilfe

GGK1 161-6AA00
SIMATIC NET CP 1616 Industrial
Ethernet, PROFINET IO-Controller V2.0,
IO-Router, Firmware V2.1

configuration roboter as contoller in Step7/NCM-Manager



add IO-device to robot-network

The screenshot shows the 'HW Konfig' window for a robot configuration. On the left, a tree view shows the robot structure with 'CP 161' selected. A line connects this to a 'robot-network: PROFINET-IO-System (100)' in the main workspace. On the right, a device catalog is open, showing various SIMATIC components. The 'IM154-4 PN HF' device is highlighted, and its details are shown at the bottom right.

Index	Baugruppe	Bestellnu...	Fl...	M...	Kommentar
1	CP 1616 V2.1 PN V2.06GK1 161-6V2.1				
X1	PN-IO				
X1P1	Port 1				
X1P2	Port 2				
X1P3	Port 3				
X1P4	Port 4				
2					
3					
4					
5					
6					
7					
8					
9					
10					
11					
12					
13					
14					
15					
16					
17					

GES7 154-4AB00-0AB0
PROFINET IO-Device Interfacemodul
IM 154-4 PN High Feature für ET 200pro

configuration roboter as contoller in Step7/NCM-Manager



add IO-device to robot-network

robot-network: PROFINET-IO-System (100)

(1) IM154-4PNHF

Steckplatz	Baugruppe	Bestellnummer	E-Adresse	A-Adresse	Diagnoseadresse	Kommentar
0	IM154-4PNHF	6ES7 154-4AB00-0AB0			16375*	
1	PN-E DC24V				16375*	
2						
3						
4						
5						
6						
7						
8						
9						
10						
11						
12						
13						
14						
15						
16						
17						

Drücken Sie F1, um Hilfe zu erhalten.

configuration roboter as contoller in Step7/NCM-Manager



HW Konfig - [roboter 1 (Konfiguration) -- test]

Station Bearbeiten Einfügen Zielsystem Ansicht Extras Fenster Hilfe

robot-network: PROFINET-IO-System (100)

(1) IM154-4

Profilt: Standard

PROFIBUS-DP
PROFIBUS-PA
PROFINET IO
Gateway
I/O
ET 200M
ET 200pro
GSD
IM154-4 PN HF
AI
AO
DI
8 DI DC24V
8 DI DC24V HF
8/16 F-DI DC24V
DI/DO
DO
Motorstarter
PM
Pneumatik
IM154-8 CPU
ET 200S
SIMATIC PC-CP
SIMATIC S7-CP
Network Components
Sensors
Weitere FELDGERÄTE
SIMATIC 300
SIMATIC 400
SIMATIC PC Based Control 300/400
SIMATIC PC Station

6ES7 141-4BF00-0AB0
Digitaleingabemodul 8 DI DC24V High
Feature

Steckplatz	Baugruppe	Bestellnummer	E-Adresse	A-Adresse	Diagnoseadresse	Kommentar
0	IM154-4PNHF	6ES7 154-4A600-0AB0			16332*	
1	PN-E DC24V				16335*	
2						
3						
4						
5						
6						
7						
8						
9						
10						
11						
12						
13						
14						
15						
16						
17						

Drücken Sie F1, um Hilfe zu erhalten.

configuration roboter as contoller in Step7/NCM-Manager



define IO-adress of the new modules
make double-click on the modul

Select address tab
modul

Steckplatz	Baugruppe	Bestellnummer
0	IM154-4PNHF	6ES7 154-4AB00
1	PM154-DC24V	
2	8 DI DC24V HF	6ES7 141-4BF00
3	8 DO DC24V 0.5A	6ES7 142-4BF00
4		
5		
6		
7		
8		
9		
10		
11		
12		
13		
14		
15		
16		
17		

Drücken Sie F1, um Hilfe zu erhalten.

configuration roboter as contoller in Step7/NCM-Manager



Save und compile the configuration at the end.

The screenshot shows the Step7 software interface with a configuration window titled "Übersetzen" (Compile) open. The window displays the following information:

- Station: roboter 1
- Baugruppe: [0/1/0] CP 1616 V2.1 PN V2.0

The background interface shows a project tree on the left with "CP 1616 V2" selected, and a hardware rack configuration table below. The rack configuration table is as follows:

Steckplatz	Baugruppe	Bestelln...			
0	IM154-4PNHF	6ES7 154-4PNHF0-0AA0			1600.0
1	PN-E-DC24V				16375°
2	8 DI DC24V HF	6ES7 141-4BF00-0AB0	20.0...20.7		
3	8 DO DC24V 0.5A	6ES7 142-4BF00-0AA0		20.0...20.7	
4					
5					
6					
7					
8					
9					
10					
11					
12					
13					
14					
15					
16					
17					

Additional information in the bottom right corner of the interface: PROFIBUS-DP-Slaves der SIMATIC S7, M7 und C7 (dezentraler Aufbau)

configuration roboter as contoller in Step7/NCM-Manager



Send configuration to cp1616

robot-network: PROFINET-IO-System (100)

Zielbaugruppe auswählen

Baugruppe	Index
CP 1616 V2.1 PN V2.0	1
Stationmanager	125

OK Abbrechen Hilfe

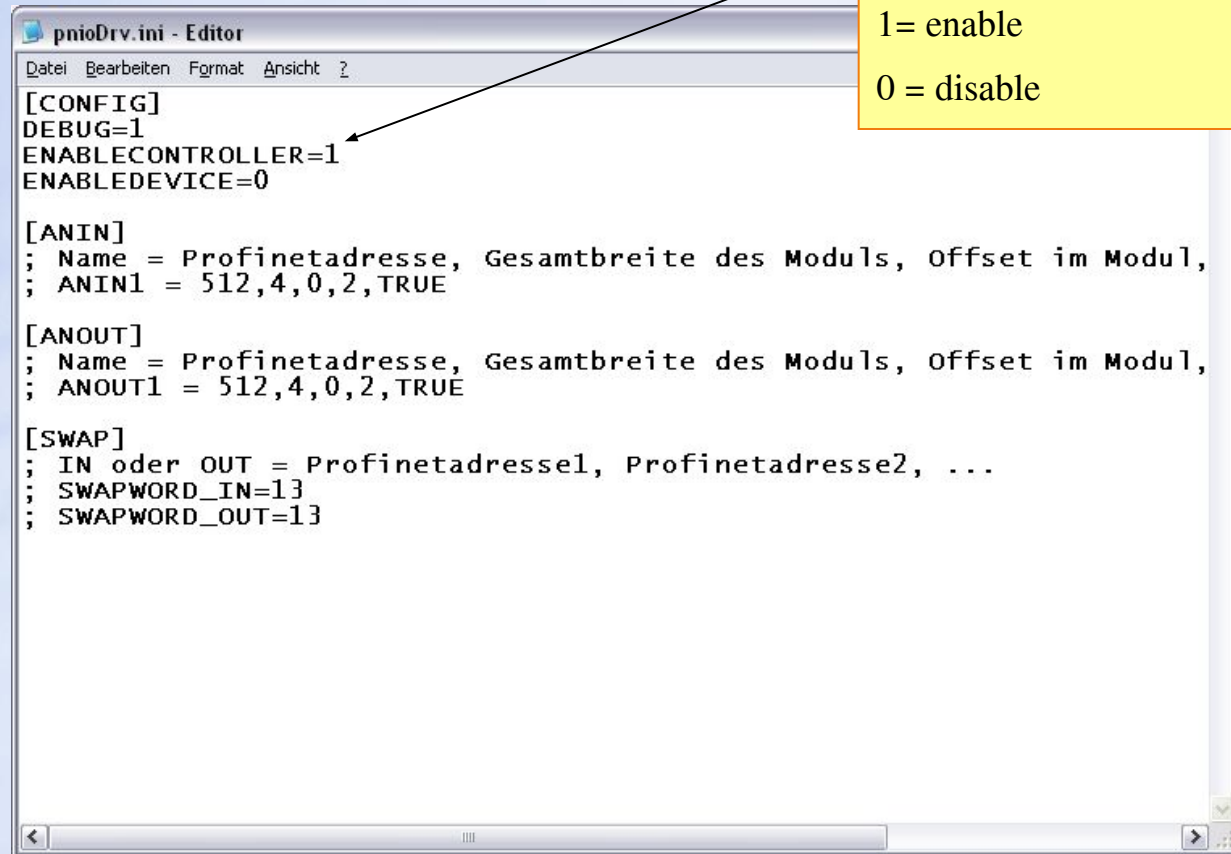
Drücken Sie F1, um Hilfe zu erhalten.

PnioDrv.ini (C:\KRC\Roboter\Ini\PnioDrv.ini)

Activate the requested mode

1 = enable

0 = disable



```
[CONFIG]
DEBUG=1
ENABLECONTROLLER=1
ENABLEDEVICE=0

[ANIN]
; Name = Profinetadresse, Gesamtbreite des Moduls, Offset im Modul,
; ANIN1 = 512,4,0,2,TRUE

[ANOUT]
; Name = Profinetadresse, Gesamtbreite des Moduls, Offset im Modul,
; ANOUT1 = 512,4,0,2,TRUE

[SWAP]
; IN oder OUT = Profinetadressel, Profinetadresse2, ...
; SWAPWORD_IN=13
; SWAPWORD_OUT=13
```


Configuration on robot – IOSYS.INI



HW Konfig - [roboter 1 (Konfiguration) -- test]

Station Bearbeiten Einfügen Zielsystem Ansicht Extras Fenster Hilfe

(0) PC

- 1 CP 1616 V2
- X1 pni-o
- X1P1 Port 1
- X1P2 Port 2
- X1P3 Port 3
- X1P4 Port 4
- 2

robot-network: PROFINET-IO-System (100)

(1) IM154-4

(1) IM154-4PNHF

Steckplatz	Baugruppe	Bestellnummer	E-Adresse	A-Adresse	Diagnoseadresse
0	IM154-4PNHF	6ES7 154-4AB00-0AB0			16376*
1	PM-E DC24V				16375*
2	8 DI DC24V HF	6ES7 141-4BF00-0AB0	20.0...20.7		
3	8 DO DC24V 0.5A	6ES7 142-4BF00-0AA0		20.0...20.7	
4					
5					
6					
7					
8					
9					
10					
11					
12					
13					
14					
15					
16					
17					

Drücken Sie F1, um Hilfe zu erhalten.

```
iosys.ini - Editor
Datei Bearbeiten Format Ansicht ?

; =====
; IOSYS.INI - Configuration fil
; =====
; For configuration help go to
; =====

[CONFIG]
VERSION=2.00

[DRIVERS]
PNET=26,pnioInit,PnetDrv.o

[PNET]
; Controller
INB0=20,x1
OUTB0=20,x1

[END SECTION]
```

Configuration on robot – IOSYS.INI



ANIN1 -> \$anin[1]

2=ident for special handling

512=plc Input adress

14 = number of bit's inc. sign-bit

3 = type (left-justified, with Sign)

8000 = calibration factor

```

iosys.ini - Editor
Datei Bearbeiten Format Ansicht ?

; =====
; IOSYS.INI - Configuration file
; =====
help go to t

[CONFIG]
VERSION=2.00

[DRIVERS]
PNET=26, pnioInit, PnetDrv

[PNET]
; Controller
INB0=20, x1
OUTB0=20, x1

ANIN1=2, 512, 14, 3, ca18000

[END SECTION]
    
```

Steckplatz	Baugruppe	Bestellnummer	E-Adresse	A-Adresse	Di
0	IM154-4PNHF	6ES7 154-4AB00-0AB0			16
1	FM-E DC24V				16
2	8 DI DC24V HF	6ES7 141-4BF00-0AB0	20.0...20.7		
3	8 DO DC24V 0.5A	6ES7 142-4BF00-0AA0		20.0...20.7	
4	4 AI I	6ES7 144-4GF00-0AB0	512...519		
5					
6					
7					
8					
13					
14					

For analog I/O's you need a additional configuration in the PnioDrv.ini

Configuration on robot



PnioDrv.ini (C:\KRC\Roboter\Ini\PnioDrv.ini)

The image shows a text editor window displaying the configuration file `PnioDrv.ini`. Several parameters are annotated with yellow boxes and arrows:

- `ANIN1= $anin[1]` is annotated with a box containing the same text.
- The value `512` in the `ANIN1` and `ANOUT1` lines is annotated with a box: "512 = I/O Base-adress from modul".
- The value `8` in the `ANIN1` and `ANOUT1` lines is annotated with a box: "8=overall width of the modul (8 byte)".
- The value `2` in the `ANIN1` and `ANOUT1` lines is annotated with a box: "2=access with (byte)".
- The value `TRUE` in the `ANIN1` and `ANOUT1` lines is annotated with a box: "swapping (true or false)".
- The value `0` in the `ANIN1` and `ANOUT1` lines is annotated with a box: "0=byte-offset in the Modul".

```
[CONFIG]
DEBUG=1
ENABLECONTROLLER=1
ENABLEDEVICE=0

[ANIN]
; Name = Profinetadresse, Gesamtbreite des Moduls, Offset im Modul,
; ANIN1 = 512,4,0,2,TRUE
ANIN1=512,8,0,2,TRUE

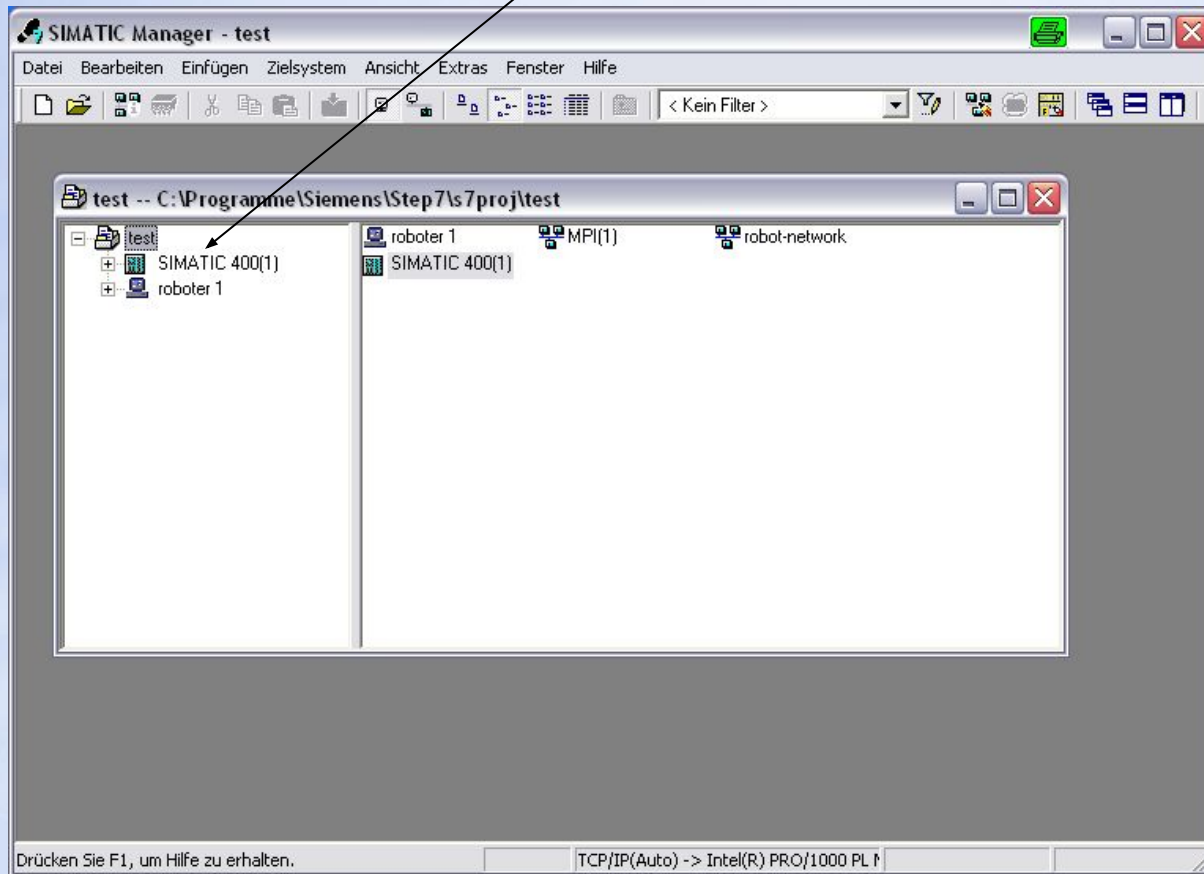
[ANOUT]
; Name = Profinetadresse, Gesamtbreite des M
; ANOUT1 = 512,4,0,2,TRUE

[SWAP]
; Profinetadresse1, Profinetadresse2, ...
;
;
;
```

configuration roboter as device in Step7/NCM-Manager



add Controller



configuration roboter as device in Step7/NCM-Manager



The screenshot shows the SIMATIC Manager HW Config interface. On the left, a rack configuration is shown for a UR2 robot, including a PS 407 20A power supply, a CPU 416F-3, and various modules. A line connects the CPU to a network label 'robot-network: PROFINET-IO-System (100)'. A yellow box with the text 'define device-name for Controller' has an arrow pointing to this label. Another yellow box with the text 'define network for Controller' has an arrow pointing to the same label. On the right, a search tree shows various SIMATIC components, with 'SIMATIC 400' selected. Below the rack configuration, a table for the selected network is shown:

Gerätenummer	IP-Adress...	Gerätename	Bestellnummer	Firmware	Diagnoseadresse	Kommentar

At the bottom of the window, there is a note: 'Drücken Sie F1, um Hilfe zu erhalten.'

configuration roboter as device in Step7/NCM-Manager



The screenshot shows the SIMATIC Manager HW Config interface. On the left, a rack configuration for UR2 is shown with slots 1 (PS 407 20A) and 4 (CPU 416F-3). The CPU slot 4 is expanded to show modules: IF1, X1 (MPI/DP), X5 (PN-IO-1), X5 P1 (Port 1), X5 P2 (Port 2), 6, and 7. A line connects the X5 module to a network line labeled "robot-network: PROFINET-IO-System (100)".

Below the rack configuration is a table for the network system:

Gerätenummer	IP-Adress...	Gerätename	Bestellnummer	Firmware	Diagnoseadresse	Kommentar

On the right, a tree view shows the network configuration. The "robot-network: PROFINET-IO-System (100)" is selected. The tree includes folders for PROFIBUS-DP, PROFIBUS-PA, PROFINET IO, Gateway, I/O, ET 200M, ET 200pro, ET 200S, SIMATIC PC-CP, CP 1604, CP 1616, Migration, V2.1, V1.0, V2.0, SIMATIC S7-CP, Network Components, Sensors, and Weitere FELDERGERÄTE. A search bar at the top right is empty. The status bar at the bottom right shows: 6GK1 161-6AA00, SIEMENS, PCI-Baugruppe CP 1616 für Industrial Ethernet: PROFINET.

Ein PROFINET IO-Device kann nur in ein PROFINET IO-System eingefügt werden.

configuration roboter as device in Step7/NCM-Manager



The screenshot shows the HW Config interface for a SIMATIC 400(1) system. The main window displays a rack configuration with a PS 407 20A power supply, a CPU 416F-3, and a CP 1616 module. The CP 1616 module is connected to a robot-network: PROFINET-IO-System (100). The CP 1616 module is shown with a V2.1 version. The table below provides details for the CP 1616 module.

Steckplatz	Baugruppe	Bestellnummer	E-Adresse	A-Adresse	Diagnoseadresse	Kommentar
0	CP-1616	6GK1 161-6AA00			16378*	
X1	PN-IO				16377*	
X1 P1	Port 1 - RJ45				16376*	
X1 P2	Port 2 - RJ45				16375*	
X1 P3	Port 3 - RJ45				16374*	
X1 P4	Port 4 - RJ45				16373*	
1						
2						
3						
4						
5						
6						
7						
8						
9						
10						
11						

The devicename and the ip-adress from the robot-device must be the same as in the robot-controller configuration.

configuration roboter as device in Step7/NCM-Manager



robot-network: PROFINET-IO-System (100)

(1) CP-1616

Select the I/O's and drag it to the device-module

Steckplatz	Baugruppe	Bestellnummer	E-Adresse	A-Adresse	Diagnoseadresse	Kommentar
0	CP-1616	66K1 161-6AA00			16378*	
X1	FN-IO				16377*	
X1 P1	Port 1 - RJ45				16376*	
X1 P2	Port 2 - RJ45				16375*	
X1 P3	Port 3 - RJ45				16374*	
X1 P4	Port 4 - RJ45				16373*	
1						
2						
3						
4						
5						
6						
7						
8						
9						
10						
11						

configuration roboter as device in Step7/NCM-Manager



robot-network: PROFINET-IO-System (100)

Suchen:

Profil: Standard

- PROFINET IO
 - Gateway
 - LAN
- CP 1604
- CP 1616
 - Migration
 - V2.1
 - V1.0
 - V2.0
 - V2.1
 - DI
 - 1 Byte
 - 16 Byte
 - 20 Byte
 - 240 Byte
 - 254 Byte
 - 4 Byte
 - 64 Byte
 - DI/DD
 - 1 Byte
 - 16 Byte
 - 20 Byte
 - 240 Byte
 - 254 Byte
 - 4 Byte
 - 64 Byte
 - DO

Digitalausgabemodul, 16 Byte DD:
Gesamtkonsistenz
GSDML-V2.0-Siemens-CP16xx-2007052
4.xml

Steckplatz	Baugruppe	Bestellnummer	E-Adresse	A-Adresse	Diagnoseadresse	Kommentar
0	CP-1616	66K1 161-6AA00			16378*	
X1	FN-IO				16377*	
X1 P1	Port 1 - R/MS				16376*	
X1 P2	Port 2 - R/MS				16375*	
X1 P3	Port 3 - R/MS				16374*	
X1 P4	Port 4 - R/MS				16373*	
1	16 Byte		0...15			
2	16 Byte			0...15		
3						
4						
5						
6						
7						
8						
9						
10						
11						

Drücken Sie F1, um Hilfe zu erhalten.

Änd

Now save, translate und download the configuration.

16 bytes input's and
16 bytes output's

configuration roboter as device in iosys.ini



very important:
 device-Input read from controller-output !
 device-output write to controller-input !

1=ident for device-function

INB read from submodul 7

OUTB write to submodul 6

Number of bytes

Steckplatz	Baugruppe	Bestellnummer	E-Adresse	A-Adresse	Diagnose
0	CP-1616	66K1 161-6AA00			16378*
X1	FN-IO				16377*
X1 P1	Port 1 - RM45				16376*
X1 P2	Port 2 - RM45				16375*
X1 P3	Port 3 - RM45				16374*
X1 P4	Port 4 - RM45				16373*
1	16 Byte		0...15		
2	16 Byte			0...15	
3					
4					
5					
6					
7					
8					
9					
10					
11					

```

iosys.ini - Editor
Datei Bearbeiten Format Ansicht ?

=====
; IOSYS.INI - Configuration f
; For configuration help go t
=====

[CONFIG]
;

[DRIVERS]
;

PNET=26,1

[PNET]
; Controller
INB0=20,x1
OUTB0=20,x1

; Device
INB40=1,7,xx16
OUTB40=1,6,xx16

; 1=C
; 1=C

[END SECTION]
    
```