

### Configuring a SINAMICS G130 or G150 offline





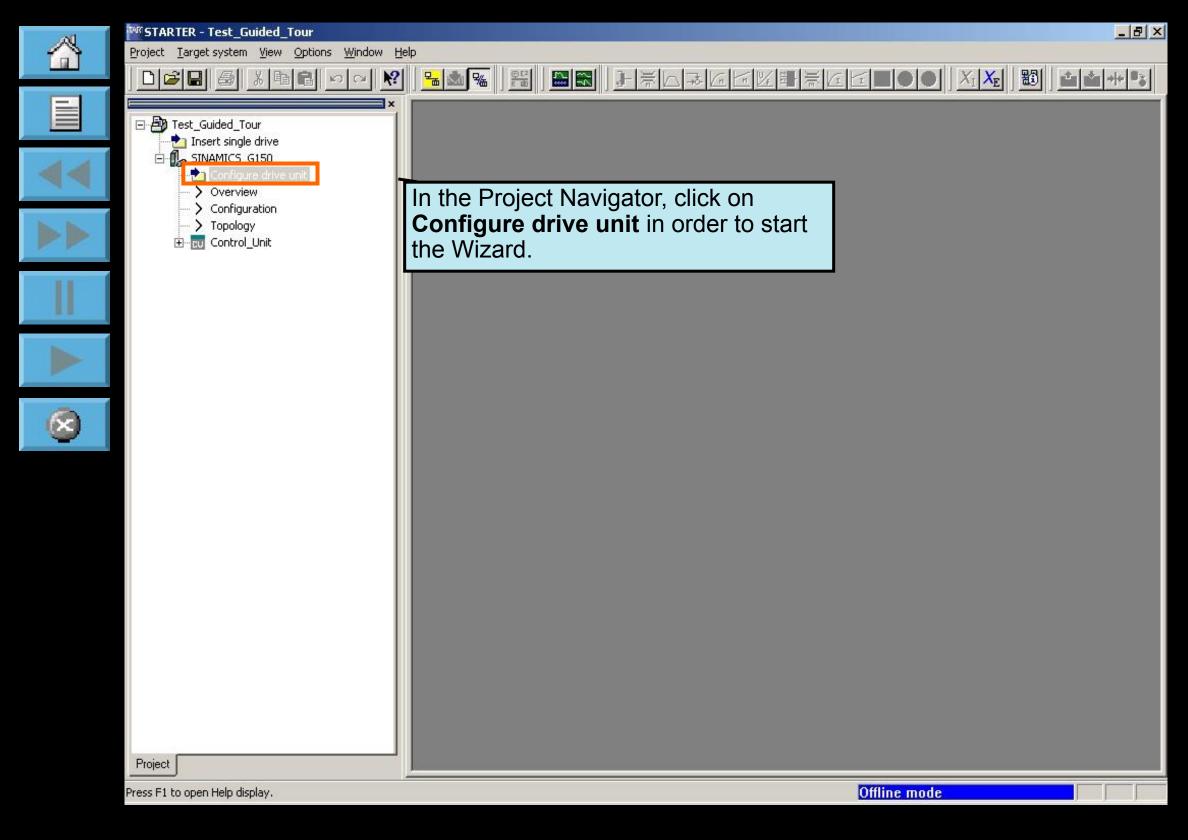








After you have created a project and set-up a drive unit (G130/150), configure this using the Wizard. This involves configuring the drive unit, selecting the option modules and a motor. After the Wizard has been exited, the drive unit is configured and the motor can be tested.





### Selecting the drive unit













■Drive unit □Options	Voltage selection:	400V		
Control structure Drive setting	Display filter:	All drive u	units	
Motor Motor holding brake	Drive unit selection:	S		
Defaults of the setpoint	Type (order no.)	Voltage	Rated power	Rated current
Drive functions	6SL3710-1GE32-1AA0	400V	110kW	210A
]PROFIBUS process da	6SL3710-1GE32-1CA0	400V	110kW	210A
Important parameters	6SL3710-1GE32-1CU0	400V	110kW	210A
1Summary	6SL3710-1GE32-6AA0	400V	132kW	260A
	6SL3710-1GE32-6CA0	400V	132kW	260A
	6SL3710-1GE32-6CU0	400V	132kW	260A
	6SL3710-1GE33-1AA0	400V	160kW	310A
	6SL3710-1GE33-1CA0	400V	160kW	310A
ATA MIN	6SL3710-1GE33-1CU0	400V	160kW	310A
	6SL3710-1GE33-8AA0	400V	200kW	380A
	6SL3710-1GE33-8CA0	400V	200kW	380A
	6SL3710-1GE33-8CU0	400V	200kW	380A
4	Configure the drive:			
	Drive object type:	Vecto	or.	
	Default macro:	G150	Cabinet unit V	2.x 🔻
	Bordaik Macro.	The second second	Cabinet unit V	
			Cabinet unit V	
		[0130	Capinet unit v	

Click on **Continue** to change to the next window.

Here, select the **line supply voltage** of the drive inverter.

Here, select the unit corresponding to the Order No. of the drive unit.

Here, where relevant, select the pre-assignment (default) of the drive units:

- V2.x....terminals, pre-assignment the same as Firmware V2.x (standard)
- V1.3...terminals, pre-assignment the same as Firmware V1.3 (for a firmware upgrade to V2.x and older terminal assignment), select the unit corresponding to the Order No. on the unit.







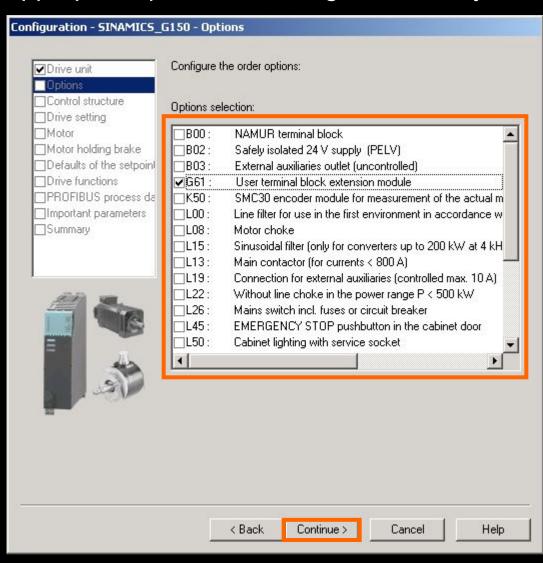






# Selecting the options that you have ordered

In this dialog, you can select the options used so that the Wizard can make the appropriate parameter assignments for you.



Select the options by activating the checkbox.









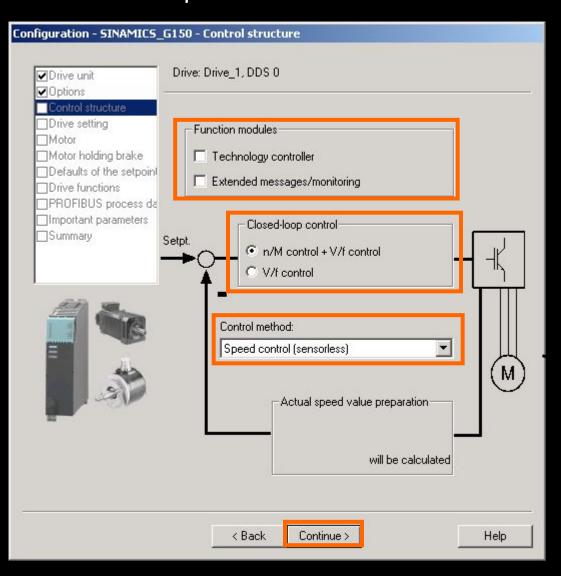






### Selecting the function modules and the control mode

In this dialog you have to choose the operating mode of your drive. The operating mode decides on the possible control modes.



Function modules are additional softwaremodules which allow to realize easy technology functions without a PLC. Before the function modules are usable, they must be activated in the configuration wizard.

Select the operating mode of your drive. In the operating mode "V/f control" no speed or torque control is possible.

Depending on the operating mode choose the control mode of your drive.



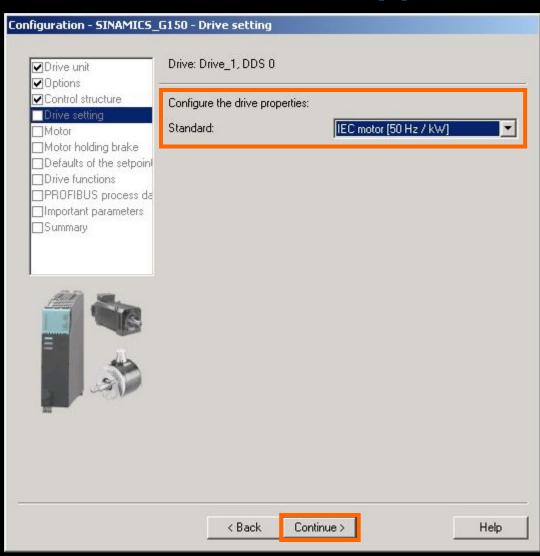
# Select the Standard applicable for the motor











Select the Standard for operation.

- International Standard IEC (Standard)
- US Standard NEMA









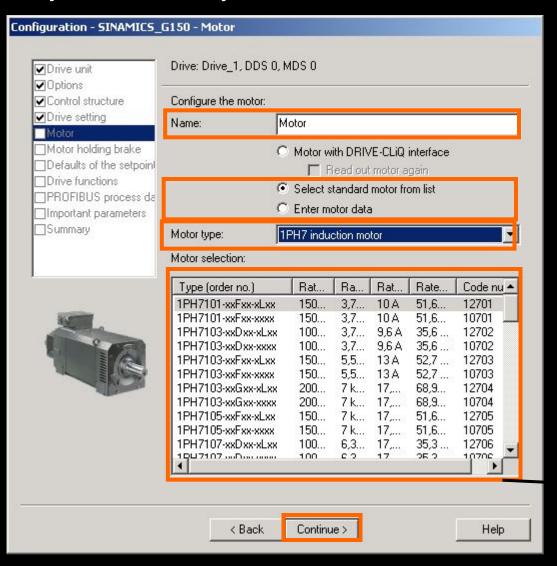






### Ways of selecting motors

You can either select a SIEMENS motor from the list - or you can directly enter the motor data.



Enter a name for the motor, e.g. the equipment code.

Here you can either select a SIEMENS motor from the list – or you can manually enter the motor data (refer to the next page).

If you have decided to enter a motor from the list, then here, select the motor type (e.g. 1PH7 or 1PH6). In the checkbox below, you can specify whether your motor should have an internal brake.

Here, select your standard motor using the Order No. (this is only active if Select standard motor from list is activated).









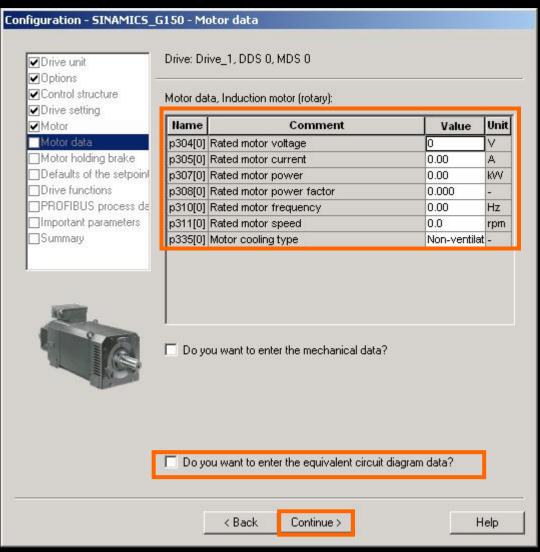






# Entering motor data according to the rating plate

This dialog box is only displayed if Enter motor data is activated in the previous dialog box.



Enter the motor data according to the rating plate.

Activate the checkbox if you also wish to enter equivalent circuit diagram data (motor data sheet). Generally this is not required for standard applications.













# Selecting the default settings for your command and setpoint sources for the standard data set (CDS0)

In addition you can also change the default settings for a second data set (CDS1) (CDS: ControlDataSet).

<b>✓</b> Options	Drive: Drive_1, DDS 0	
Control structure	Select the default macros for your command sources:	
☐ Drive setting  ☐ Motor  ☐ Motor data  ☐ Calculation of the moto  ☐ Motor holding brake  ☐ Defaults of the setpoin  ☐ Drive functions	CDS0 Terminal TM31  Command sources:  CDS1 No selection  All binector inputs (BI) of the corresponding command data set (CDS) will be interconnected accordingly.	•
Important parameters   Summary	Select the default macros for your setpoint sources:	Ţ
	Setpoint sources:  CDS1 No selection	_
The last	All connector inputs (CI) of the corresponding command data set (CDS) will be interconnected accordingly.	
- N		

Here, select a source for your basic drive controls – for example, the power-on command.

Here, select your setpoint source, e.g. analog input on a TM31.





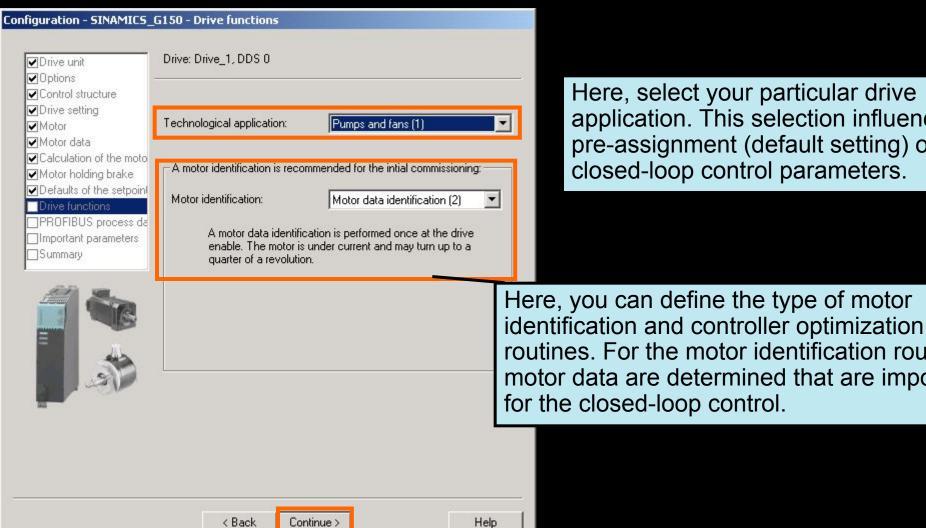








# Make the appropriate control settings and select a Profibus telegram



Here, select your particular drive application. This selection influences the pre-assignment (default setting) of the closed-loop control parameters.

routines. For the motor identification routine, motor data are determined that are important for the closed-loop control.



# Select a Profibus telegram













☑Drive unit	Drive: Drive_1, DDS 0
☑ Options — ☑ Control structure ☑ Drive setting	Select the PROFIBUS message frame type:
✓ Motor ✓ Motor data	PROFIBUS PZD message frame: Free telegram configuration with BI
✓ Calculation of the moto ✓ Motor holding brake ✓ Defaults of the setpoinf ✓ Drive functions ✓ PROFIBUS process de ☐ Important parameters ☐ Summary	Length: Input data (words):  Output data (words):
	Notes:  1. The PROFIBUS process data will be interconnected to BICO parameters in accordance with the selected message frame type. These BICO parameters cannot be subsequently changed.

Click on **Continue** to change to the next window.

Here, you can select the Profibus telegram. You can either select a standard telegram or a freely assigning a telegram.



# **Entering the most important drive parameters**





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✓ Drive setting		ortant parameters:	
✓Motor	Motor current limit:	210.00	Α
✓ Motor data ✓ Calculation of the moto	Minimum speed:	0.000	rpm
✓ Motor holding brake	Maximum speed:	1500.000	rpm
☑Defaults of the setpoin ☑Drive functions	Ramp-up time:	20.000	s
▼PROFIBUS process da	Ramp-down time:	30.000	s
Important parameters Summary	Ramp-down time with OFF3:	10.000	s

Here, enter the most important drive parameters.



# Summary of the settings made



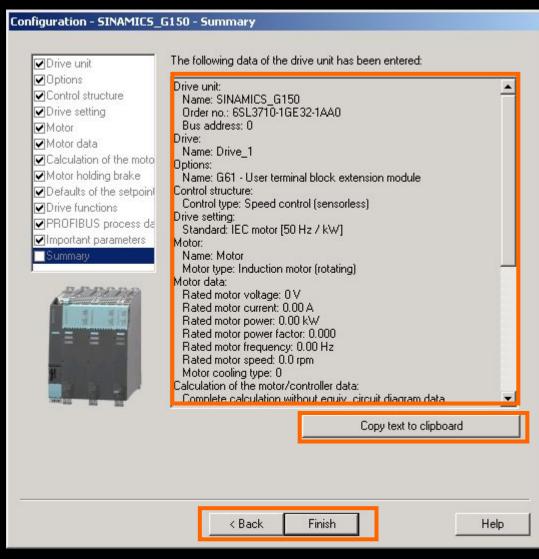












In this window you can see a summary of the settings you made.

You can copy this summary into a buffer with **Copy** so that it can be used in other applications, e.g. to generate a report.

In order to exit the Wizard, click on **Finish**. You can still change the settings with **Back**.



#### The drive unit has now been configured



You can now:



Make additional settings



Download the project into the target system



Save the project and exit Starter





