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## Admin

- Homework 1 graded, will post this afternoon

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## Rasterizing Polygons

- In interactive graphics, polygons rule the world
- Two main reasons:
- Lowest common denominator for surfaces
- Can represent any surface with arbitrary accuracy
- Splines, mathematical functions, volumetric isosurfaces...
- Mathematical simplicity lends itself to simple, regular rendering algorithms
- Like those we're about to discuss...
- Such algorithms embed well in hardware


## Rasterizing Polygons

- Triangle is the minimal unit of a polygon - All polygons can be broken up into triangles
- Convex, concave, complex
- Triangles are guaranteed to be:
- Planar
- Convex
- What exactly does it mean to be convex?

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## Convex Shapes

- A two-dimensional shape is convex if and only if every line segment connecting two points on the boundary is entirely contained.


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## Convex Shapes

- Why do we want convex shapes for rasterization?
- One good answer: because any scan line is guaranteed to contain at most one segment or span of a triangle
- Another answer coming up later
- Note: Can also use an algorithm which handles concave polygons. It is more complex than what we'll present here!

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## Decomposing Polys Into Tris

- Any convex polygon can be trivially decomposed into triangles
- Draw it
- Any concave or complex polygon can be decomposed into triangles, too
- Non-trivial!


## Rasterizing Triangles

- Interactive graphics hardware commonly uses edge walking or edge equation techniques for rasterizing triangles
- Two techniques we won't talk about much:
- Recursive subdivision of primitive into micropolygons (REYES, Renderman)
- Recursive subdivision of screen (Warnock)


## Recursive Triangle Subdivision



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## Recursive Screen Subdivision



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## Edge Walking

- Basic idea:
- Draw edges vertically
- Fill in horizontal spans for each scanline
- Interpolate colors down edges
- At each scanline, interpolate edge colors across span


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## Edge Walking: Notes

- Order vertices in x and y
- 3 cases: break left, break right, no break
- Walk down left and right edges
- Fill each span
- Until breakpoint or bottom vertex is reached
- Advantage: can be made very fast
- Disadvantages:
- Lots of finicky special cases
- Tough to get right
- Need to pay attention to fractional offsets

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## Edge Walking: Notes

- Fractional offsets:

- Be careful when interpolating color values!
- Also: beware gaps between adjacent edges

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## Edge Equations

- An edge equation is simply the equation of the line containing that edge
- Q: What is the equation of a $2 D$ line?
- $\mathrm{A}: \boldsymbol{A x}+\boldsymbol{B y}+\boldsymbol{C}=\mathbf{0}$
- Q: Given a point $(\boldsymbol{x}, \boldsymbol{y})$, what does plugging $\boldsymbol{x} \& \boldsymbol{y}$ into this equation tell us?
- A: Whether the point is:
- On the line: $\boldsymbol{A} \boldsymbol{x}+\boldsymbol{B y}+\boldsymbol{C}=\mathbf{0}$
- "Above" the line: $\boldsymbol{A} \boldsymbol{x}+\boldsymbol{B} \boldsymbol{y}+\boldsymbol{C}>0$
- "Below" the line: $\boldsymbol{A} \boldsymbol{x}+\boldsymbol{B} \boldsymbol{y}+\boldsymbol{C}<\mathbf{0}$


## Edge Equations

- Edge equations thus define two half-spaces:


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## Edge Equations

- And a triangle can be defined as the intersection of three positive half-spaces:


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## Edge Equations

- So...simply turn on those pixels for which all edge equations evaluate to $>0$ :


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## Using Edge Equations

- An aside: How do you suppose edge equations are implemented in hardware?
- How would you implement an edge-equation rasterizer in software?
- Which pixels do you consider?
- How do you compute the edge equations?
- How do you orient them correctly?

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## Using Edge Equations

- Which pixels: compute min,max bounding box

- Edge equations: compute from vertices
- Orientation: ensure area is positive (why?)

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## Computing a Bounding Box

- Easy to do
- Surprising number of speed hacks possible
- See McMillan's Java code for an example


## Computing Edge Equations

- Want to calculate A, B, C for each edge from $\left(\boldsymbol{x}_{i}, \boldsymbol{y}_{i}\right)$ and $\left(\boldsymbol{x}_{j}, \boldsymbol{y}_{j}\right)$
- Treat it as a linear system:

$$
\begin{aligned}
& A x_{1}+B y_{1}+C=0 \\
& A x_{2}+B y_{2}+C=0
\end{aligned}
$$

- Notice: two equations, three unknowns
- Does this make sense? What can we solve?
- Goal: solve for A \& B in terms of C

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## Computing Edge Equations

- Set up the linear system:
- Multiply both sides by matrix inverse:

$$
\left[\begin{array}{l}
A \\
B
\end{array}\right]=\frac{-C}{x_{0} y_{1}-x_{1} y_{0}}\left[\begin{array}{l}
y_{1}-y_{0} \\
x_{1}-x_{0}
\end{array}\right]
$$

- Let $C=x_{0} y_{1}-x_{1} y_{0}$ for convenience
- Then $A=y_{0}-y_{1}$ and $B=x_{1}-x_{0}$

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## Computing Edge Equations: Numerical Issues

- Calculating $C=x_{0} y_{1}-x_{1} y_{0}$ involves some numerical precision issues
- When is it bad to subtract two floating-point numbers?
- A: When they are of similar magnitude
- Example: $\underline{1.234} \times 10^{4}-\underline{1.233} \times 10^{4}=\underline{1} .000 \times 10^{1}$
- We lose most of the significant digits in result
- In general, $\left(x_{0} y_{0}\right)$ and $\left(x_{p} y_{l}\right)$ (corner vertices of a triangle) are fairly close, so we have a problem


## Computing Edge Equations: Numerical Issues

- We can avoid the problem in this case by using our definitions of $A$ and $B$ :

$$
A=y_{0}-y_{1} \quad B=x_{1}-x_{0} \quad C=x_{0} y_{1}-x_{1} y_{0}
$$

Thus:

$$
C=-A x_{0}-B y_{0} \quad \text { or } C=-A x_{1}-B y_{1}
$$

- Why is this better?
- Which should we choose?
- Trick question! Average the two to avoid bias:

$$
C=-\left[A\left(x_{0}+x_{1}\right)+\mathrm{B}\left(\mathrm{y}_{0}+\mathrm{y}_{1}\right)\right] / 2
$$

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## Edge Equations

- So...we can find edge equation from two verts.
- Given three corners $\mathbf{C}_{\mathbf{0}}, \mathbf{C}_{1}, \mathbf{C}_{\mathbf{0}}$ of a triangle, what are our three edges?
- How do we make sure the half-spaces defined by the edge equations all share the same sign on the interior of the triangle?
- A: Be consistent (Ex: [C $\left.\left.\mathbf{C}_{\mathbf{0}} \mathbf{C}_{\mathbf{1}}\right],\left[\mathrm{C}_{1} \mathbf{C}_{2}\right],\left[\mathbf{C}_{\mathbf{2}} \mathbf{C}_{\mathbf{0}}\right]\right)$
- How do we make sure that sign is positive?
- A: Test, and flip if needed ( $\boldsymbol{A}=-\boldsymbol{A}, \boldsymbol{B}=-\boldsymbol{B}, \boldsymbol{C}=-\boldsymbol{C}$ )

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## Edge Equations: Code

- Basic structure of code:
- Setup: compute edge equations, bounding box
- (Outer loop) For each scanline in bounding box...
- (Inner loop) ...check each pixel on scanline, evaluating edge equations and drawing the pixel if all three are positive


## Optimize This!

findBoundingBox(\&xmin, \&xmax, \&ymin, \&ymax);
setupEdges ( $\& a 0, \& b 0, \& c 0, \& a 1, \& b 1, \& c 1, \& a 2, \& b 2, \& c 2)$;
/* Optimize this: */
for (int $y=y$ Min; $y<=y M a x ; y++$ ) $\{$
for (int $\mathrm{x}=\mathrm{xMin}$; $\mathrm{x}<=\mathrm{xMax} ; \mathrm{x}++$ ) $\{$
float e0 $=a 0 * x+b 0 * y+c 0$;
float e1 $=a 1 * x+b 1 * y+c 1$;
float e2 $=\mathrm{a} 2 * \mathrm{x}+\mathrm{b} 2 * \mathrm{y}+\mathrm{c} 2$;
if (e0>0 \&\&e1>0\&\&e2>0) setPixel ( $\mathrm{x}, \mathrm{y}$ );
\}
\}

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## Edge Equations: Speed Hacks

- Some speed hacks for the inner loop:
int $x f l a g=0$;
for (int $x=x M i n ; x<=x M a x ; ~ x++$ ) $\{$
if (e0|e1|e2 >0) \{
setPixel ( $\mathbf{x}, \mathrm{y}$ );
xflag++;
\} else if (xflag != 0) break;
e0 += a0; e1 += a1; e2 += a2;
\}
- Incremental update of edge equation values (think DDA)
- Early termination (why does this work?)
- Faster test of equation values

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## Edge Equations: Interpolating Color

- Given colors (and later, other parameters) at the vertices, how to interpolate across?
- Idea: triangles are planar in any space:
- This is the "redness" parameter space
- Note:plane follows form $z=A x+B y+C$
■ Look familiar?


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## Edge Equations: Interpolating Color

- Given redness at the 3 vertices, set up the linear system of equations:

$$
\left[\begin{array}{l}
r_{0} \\
r_{1} \\
r_{2}
\end{array}\right]=\left[\begin{array}{lll}
x_{0} & y_{0} & 1 \\
x_{1} & y_{1} & 1 \\
x_{2} & y_{2} & 1
\end{array}\right]\left[\begin{array}{l}
A_{r} \\
B_{r} \\
C_{r}
\end{array}\right]
$$

- The solution works out to:
$\frac{1}{2 \text { area }}\left[\begin{array}{ccc}y_{1}-y_{2} & y_{2}-y_{0} & y_{0}-y_{1} \\ x_{2}-x_{1} & x_{0}-x_{2} & x_{1}-x_{0} \\ x_{1} y_{2}-x_{2} y_{1} & x_{2} y_{0}-x_{0} y_{2} & x_{0} y_{1}-x_{1} y_{0}\end{array}\right]\left[\begin{array}{l}r_{0} \\ r_{1} \\ r_{2}\end{array}\right]=\left[\begin{array}{c}A_{r} \\ B_{r} \\ C_{r}\end{array}\right]$

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## Edge Equations: Interpolating Color

- Notice that the columns in the matrix are exactly the coefficients of the edge equations!
$\frac{1}{2 \text { area }}\left[\begin{array}{lll}A_{2} & A_{3} & A_{1} \\ B_{2} & B_{3} & B_{1} \\ C_{2} & C_{3} & C_{1}\end{array}\right]\left[\begin{array}{l}r_{0} \\ r_{1} \\ r_{2}\end{array}\right]=\left[\begin{array}{l}A_{r} \\ B_{r} \\ C_{r}\end{array}\right]$
- So the setup cost per parameter is basically a matrix multiply
- Per-pixel cost (the inner loop) cost equates to tracking another edge equation value

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## Triangle Rasterization Issues

- Exactly which pixels should be lit?
- A: Those pixels inside the triangle edges
- What about pixels exactly on the edge? (Ex.)
- Draw them: order of triangles matters (it shouldn't)
- Don't draw them: gaps possible between triangles
- We need a consistent (if arbitrary) rule
- Example: draw pixels on left or top edge, but not on right or bottom edge

