

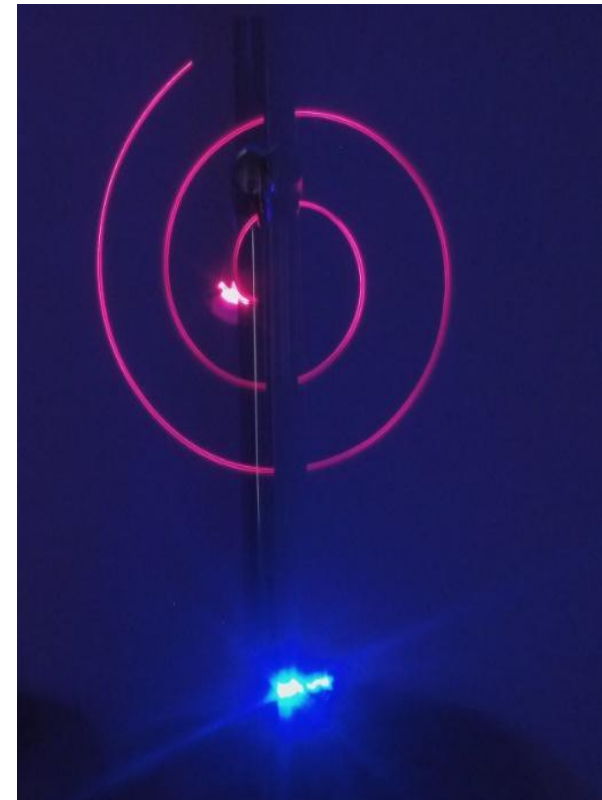
## Problem №14

# Looping pendulum

Connect two loads, one heavy and one light, with a string over a horizontal rod and **lift up the heavy** load by **pulling down the light one**. Release the light load and it will **sweep around** the rod, **keeping the heavy** load from falling to the ground. Investigate this phenomenon.

**Team Russia**

**Reporter: Ivan Polonik**



# *Plan*

Qualitative explanation: Energy transfer



Parametric investigation

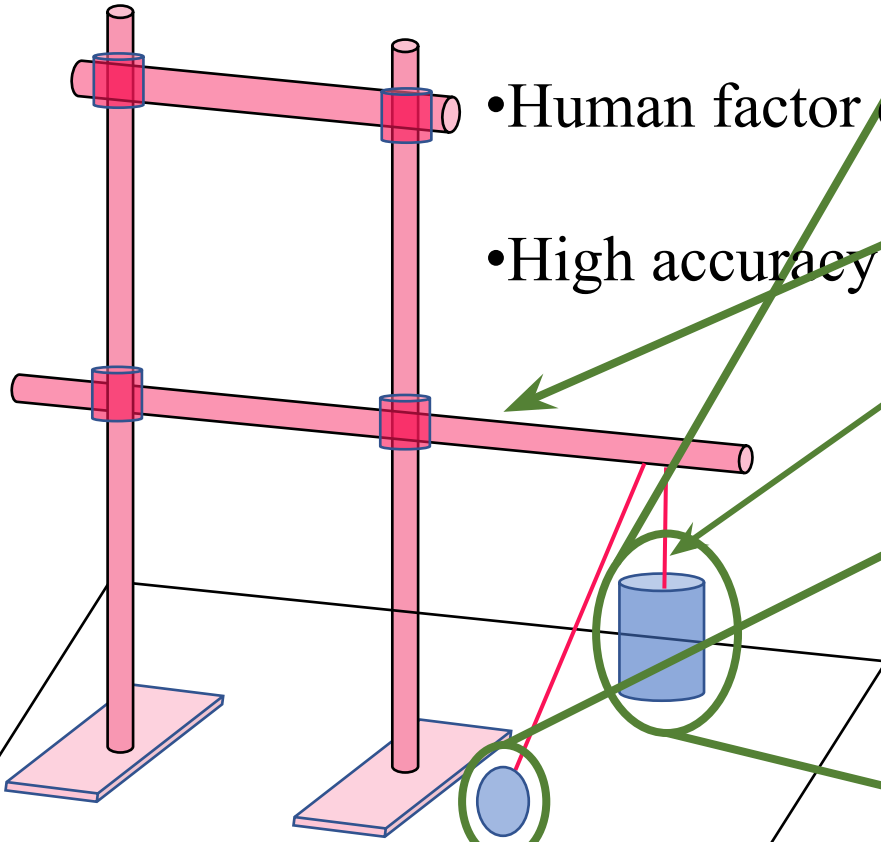


Boundary conditions: Mass, initial angle and length  
relationship

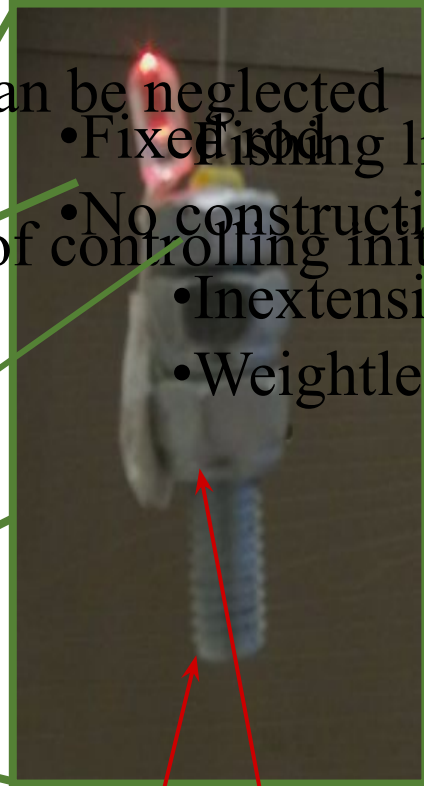


Different mode: step falling

# Setup scheme



- Human factor can be neglected
- Fixed fishing line
- No construction oscillations
- Inextensible
- Weightless
- LED increases the accuracy of measurements
- High accuracy of controlling initial parameters
- LED increases the accuracy of the load location



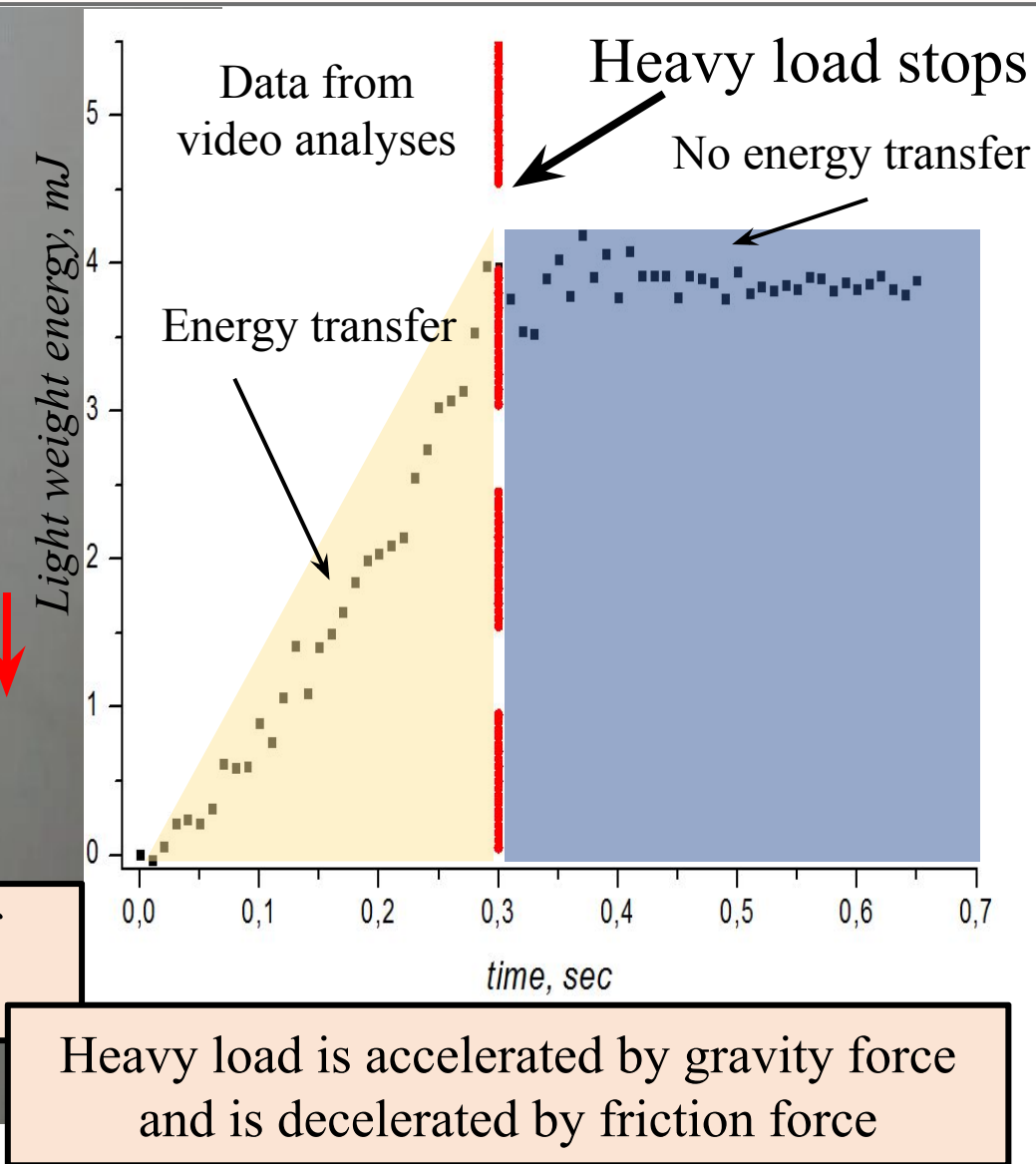
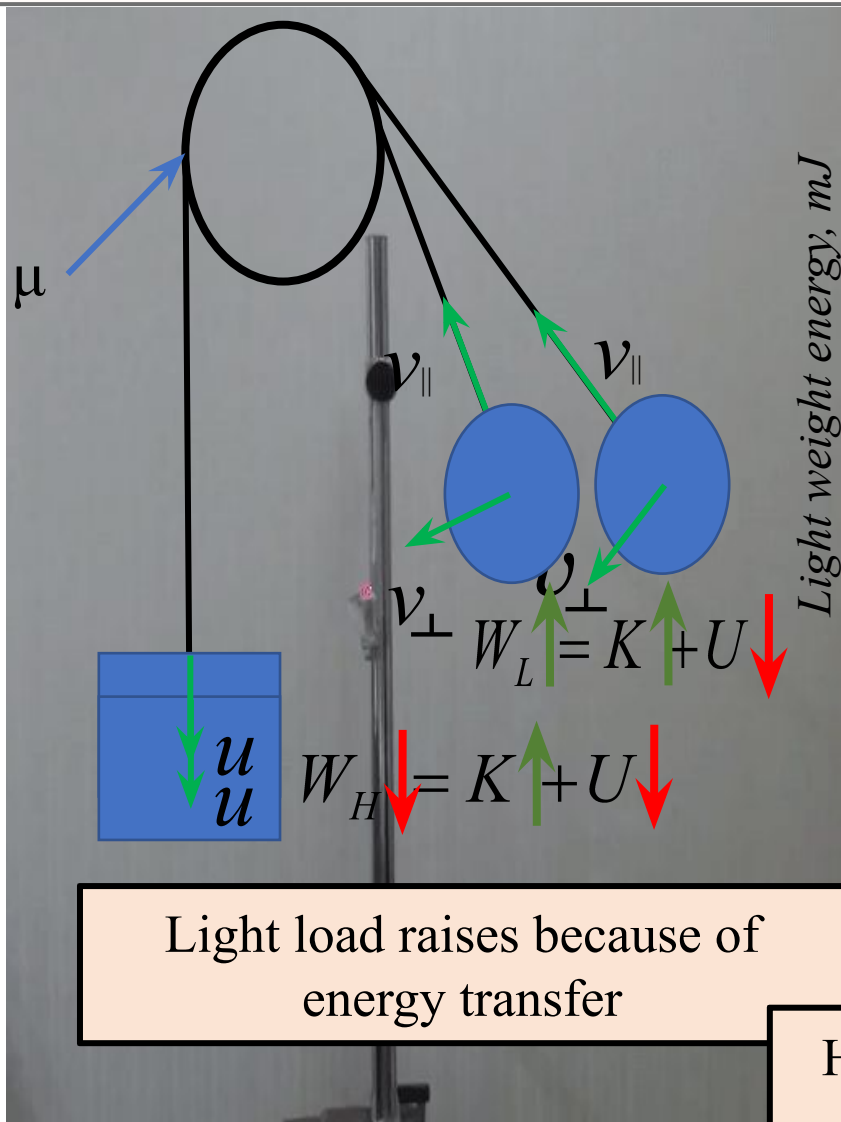
pin

nut



- Mass of heavy load can be increased piece by piece

# Qualitative explanation



Qualitative explanation ●

Quantitative model

Parametric investigation

# Components of the system

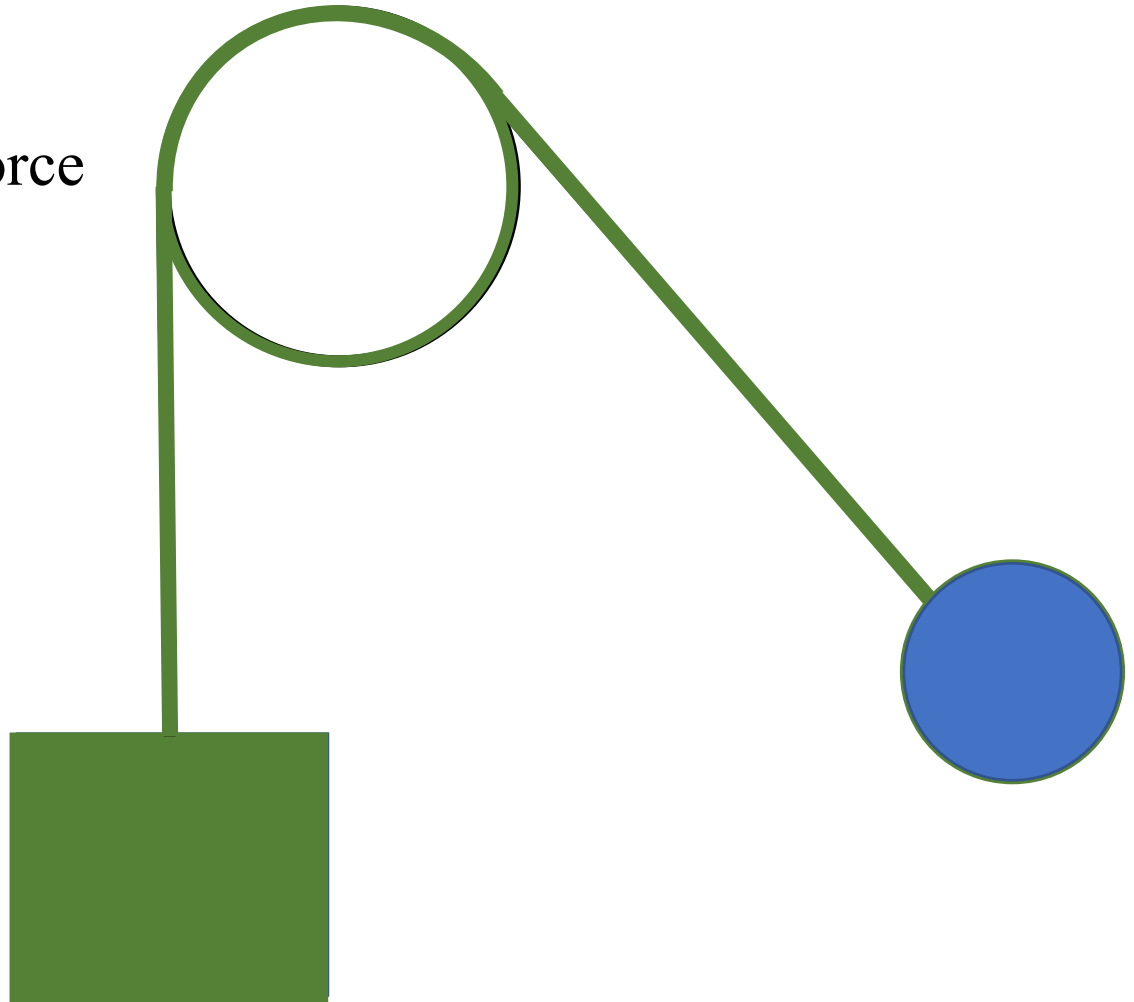
Things to describe

Rod + string – friction force

String – kinematic ratio

Light load – dynamics

Heavy load - dynamics



Qualitative explanation ✓

Quantitative model •

Parametric investigation

# *Mathematical model*

## ***Theory assumptions:***

Drag force is  
neglectable

Heavy load  
falls vertically

String:  
weightless  
inextensible



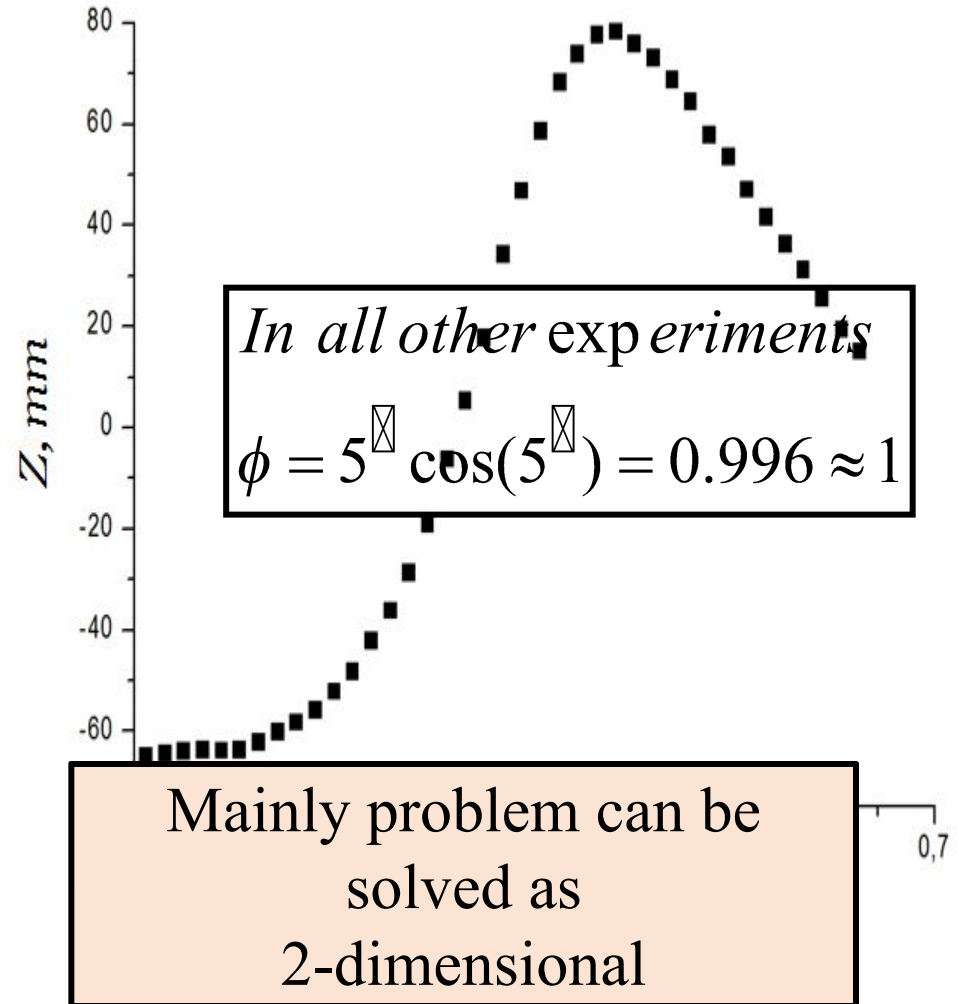
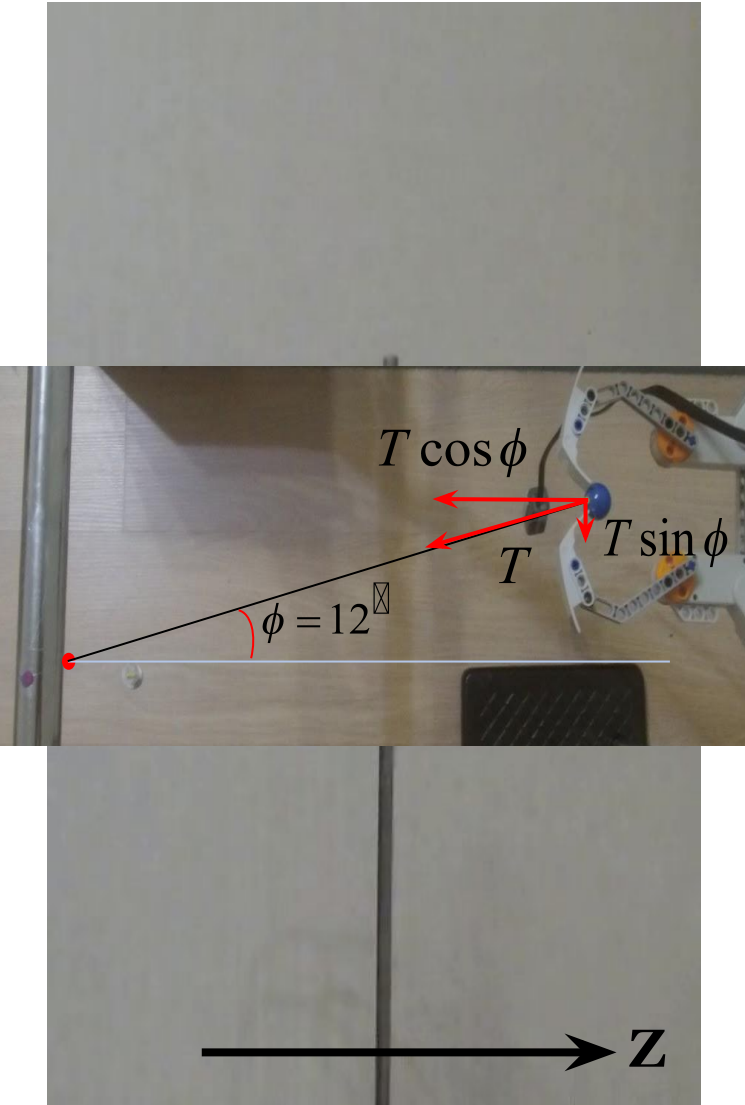
String lays  
turn to turn

Qualitative explanation ✓

Quantitative model ●

Parametric investigation

# 3 - dimensional movement

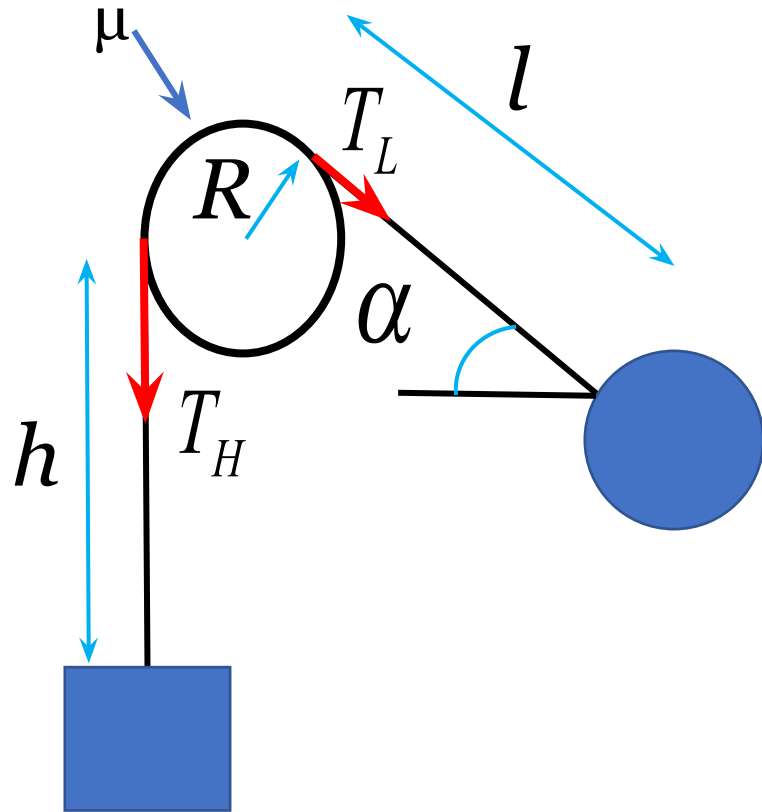


Qualitative explanation ✓

Quantitative model ●

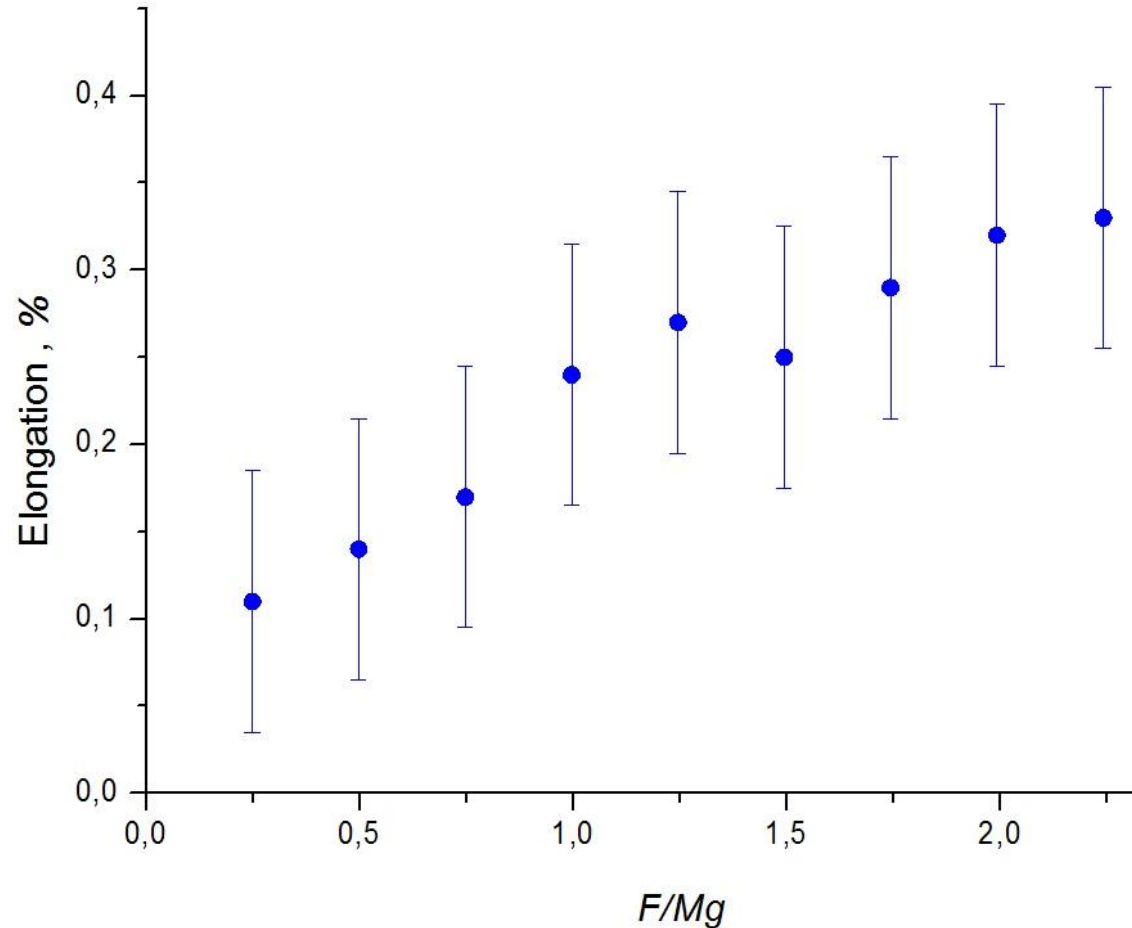
Parametric investigation

# Rod and string description



*Rod – string friction*

*while heavy load falls:*



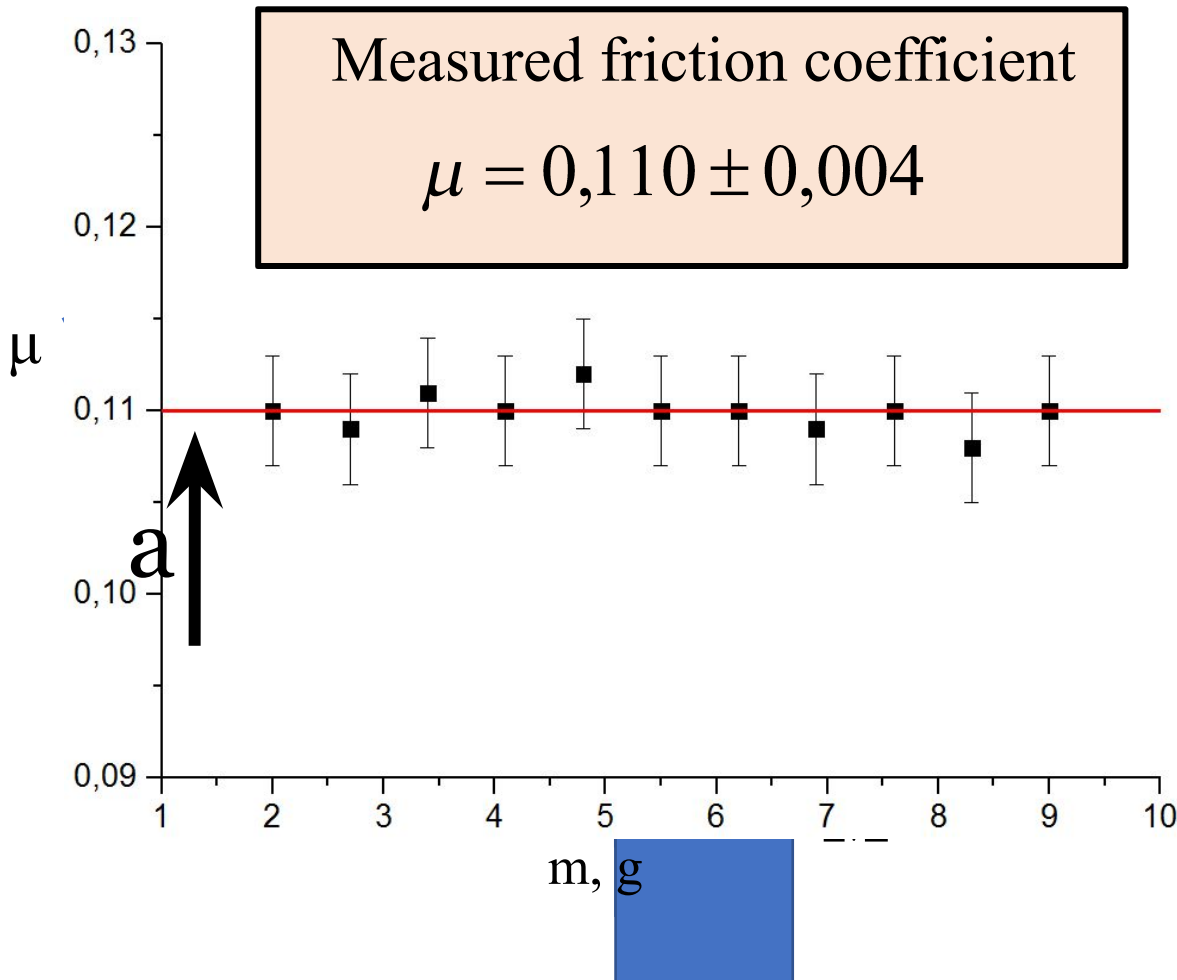
Qualitative explanation ✓

Quantitative model ●

Parametric investigation



# Friction coefficient measurements



Acceleration was found from video analyses

Using Euler's formula

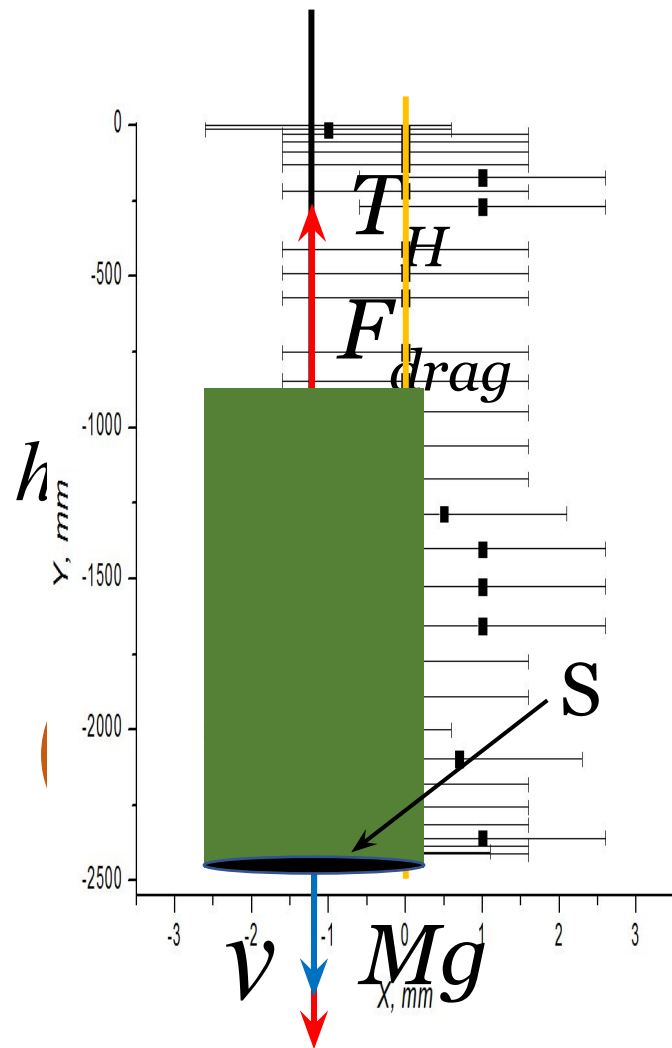
$$\mu = \frac{1}{\pi} \ln \frac{M(g - a)}{m(g + a)}$$

Qualitative explanation ✓

Quantitative model ●

Parametric investigation

# Heavy load movement



$$F_{drag} = \frac{1}{2} C_x \rho v^2 S \quad C_x = 0.85$$

$$F_{drag} \approx 7 \times 10^{-5} \text{ N} \quad Mg \approx 3 \times 10^{-1} \text{ N}$$

Heavy load falls vertically

$$\frac{Mg}{F_{drag}^{\max}} \approx 4000$$

*Drag force can be neglected*

*II Newton law*

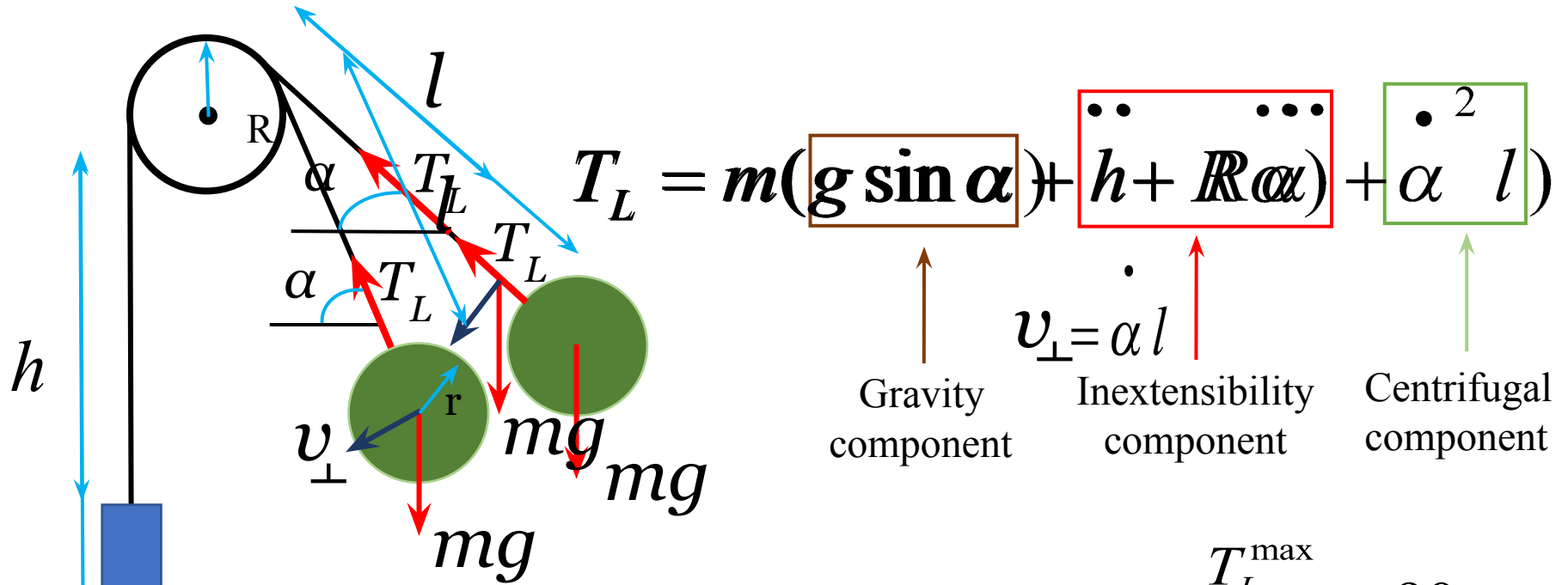
*on vertical axis :  $M \ddot{h} = Mg - T_H$*

Qualitative explanation ✓

Quantitative model ●

Parametric investigation

# Tension force acting on the light load



$$T_L = m(g \sin \alpha) + \ddot{h} + R\ddot{\alpha} + \alpha \dot{l}^2$$

Gravity component

$v_{\perp} = \alpha l$   
Inextensibility component

Centrifugal component

$$F_{drag} = \frac{1}{2} C_x \rho v^2 S \quad C_x = 0.47 \quad S = 4\pi r^2$$

$$\frac{T_L^{\max}}{F_{drag}^{\max}} \approx 90$$

Drag force can be neglected

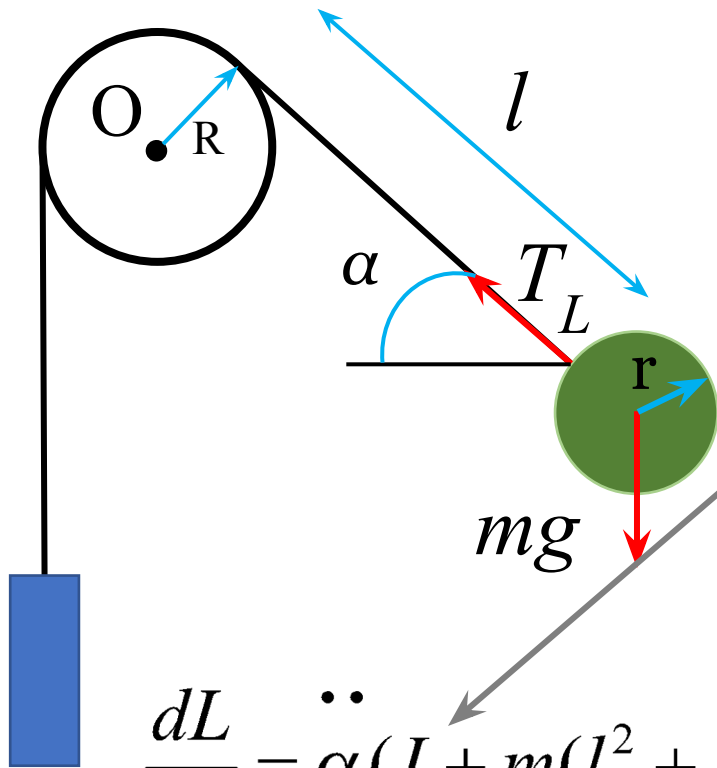
Found value of Tension force

Qualitative explanation ✓

Quantitative model ●

Parametric investigation

# Rotation of light load



Torque equation about point O :

$$I = \frac{2}{5}mr^2$$

Inconstant moment of inertia

Tension force torque

$$\frac{dL}{dt} = \ddot{\alpha}(I + m(l^2 + R^2)) + \boxed{2ml\dot{l}\dot{\alpha}} = mg(l + R)\cos\alpha - \boxed{T_L R}$$

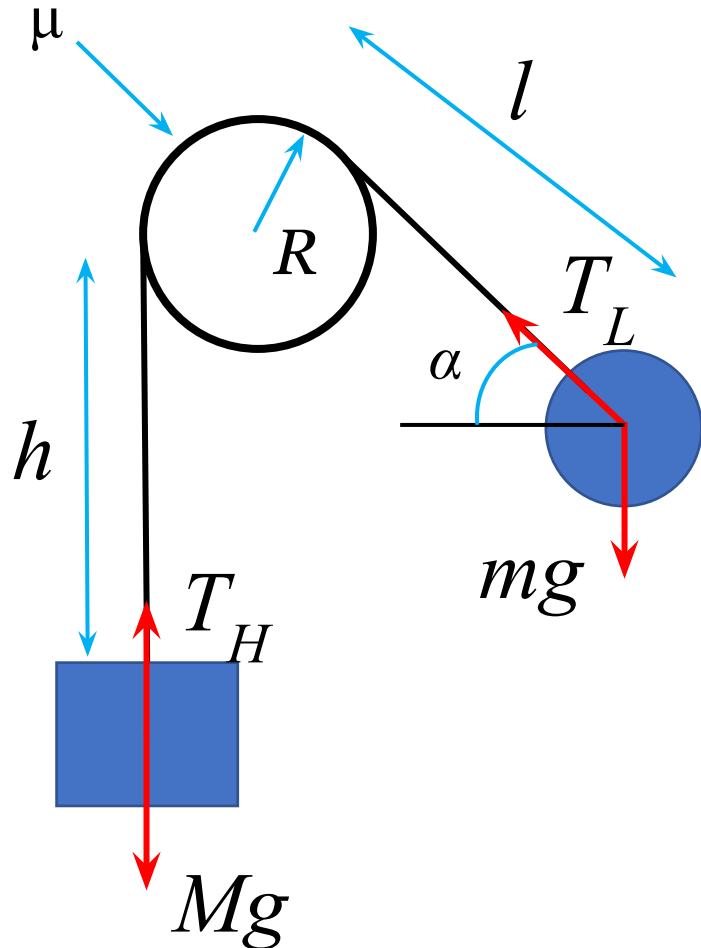
Described light load movement

Qualitative explanation ✓

Quantitative model ●

Parametric investigation

# Numerical solution



$$T_L = m((\dot{\alpha})^2 l + \ddot{h} + R\ddot{\alpha} + g \sin \alpha)$$

$$\ddot{\alpha} = \frac{m((l + R)g \cos \alpha - 2l\dot{\alpha}^2) - T_L R}{m(l^2 + R^2) + I}$$

$$T_L(t = 0) = 0$$

$$\ddot{h} = g - \frac{T_L e^{\mu(\alpha + \frac{\pi}{2})}}{M}$$

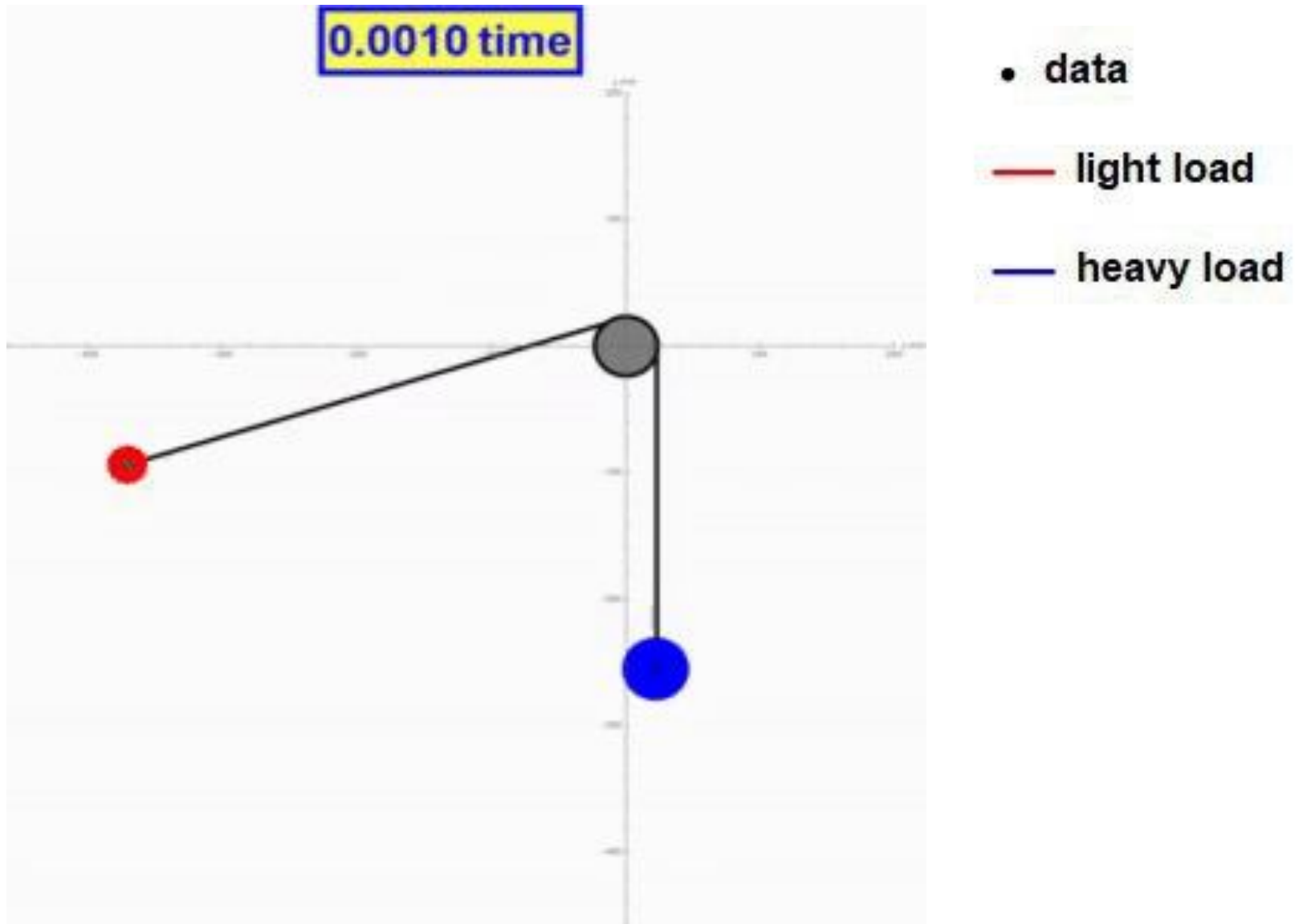
Set of equations was solved numerically (iteratively)

Qualitative explanation ✓

Quantitative model ●

Parametric investigation

# Comparing the dynamics of the system

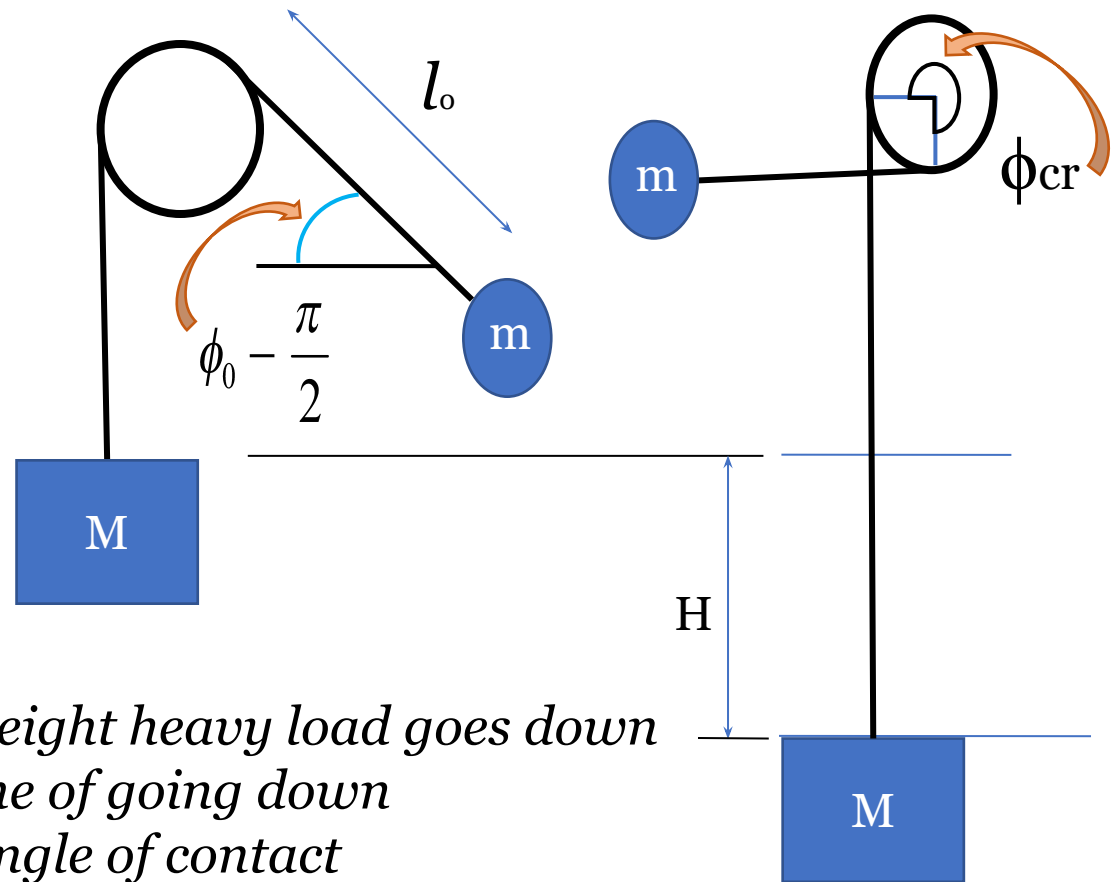


Qualitative explanation ✓

Quantitative model ✓

Parametric investigation •

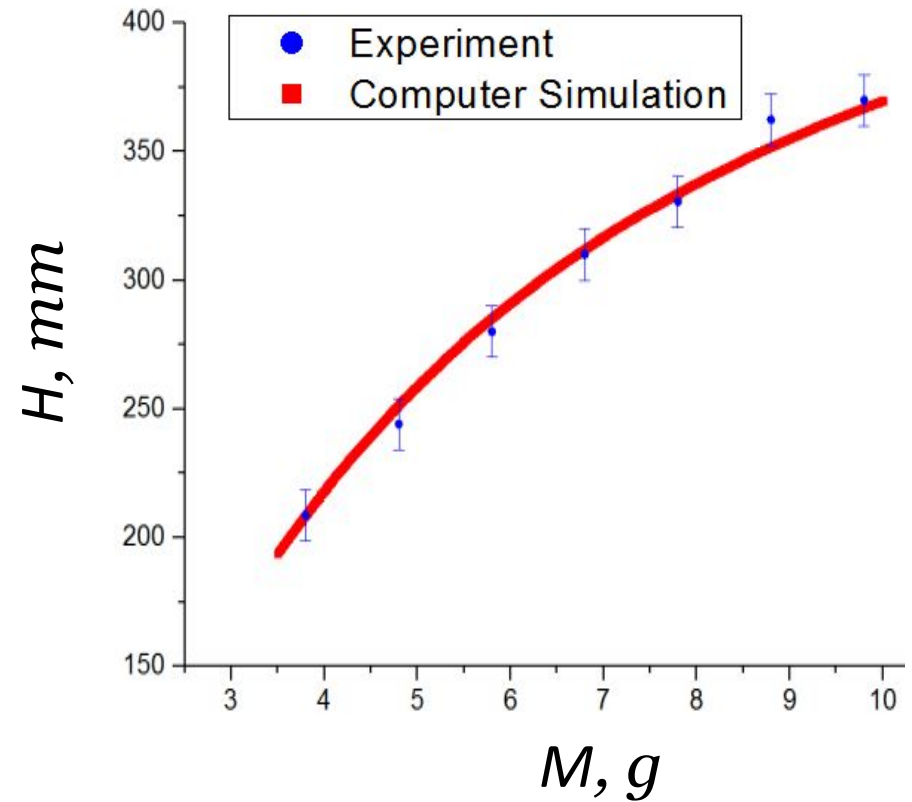
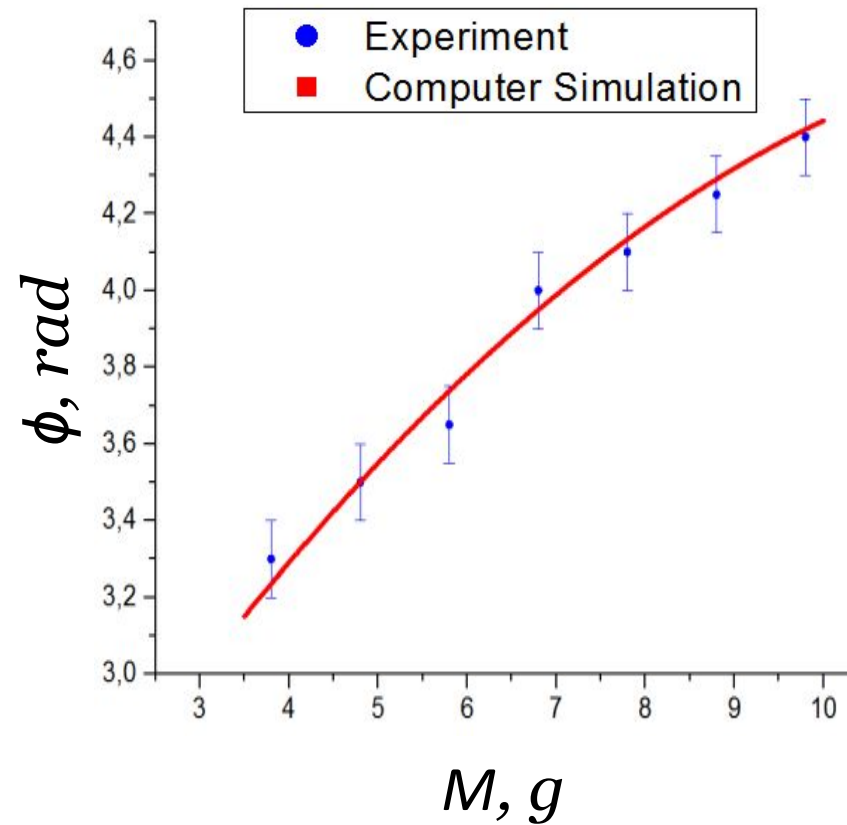
# Legend



$m$  – mass of light load  
 $M$  – mass of heavy load  
 $l$  – distance between light Load and the rod  
 $\mu$  – friction coefficient

$H$ - height heavy load goes down  
 $t$ - time of going down  
 $\varphi$ - angle of contact between string and rod  
 $\varphi_{crit}$ -  $\varphi$  at the moment of heavy load stopping

# Heavy load mass influence



The higher heavy load mass  
the higher critical angle.

The higher heavy load mass  
the higher  $H$ .

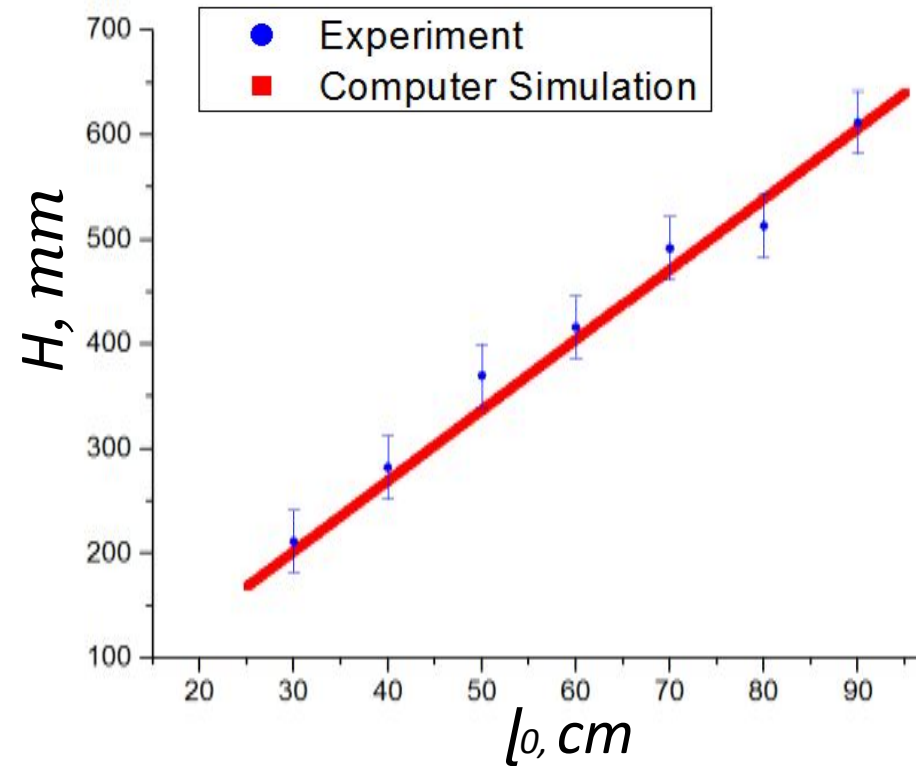
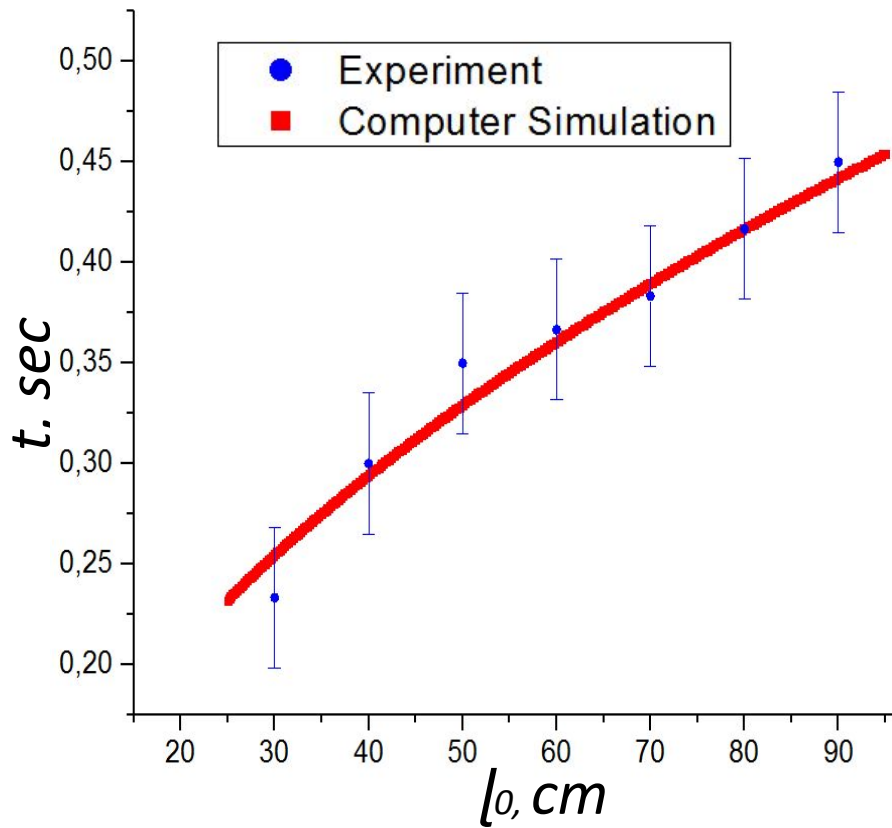
Qualitative explanation ✓

Quantitative model ✓

Parametric investigation ●



# Initial length of the string influence



The higher initial distance between light load and rod the higher time of falling

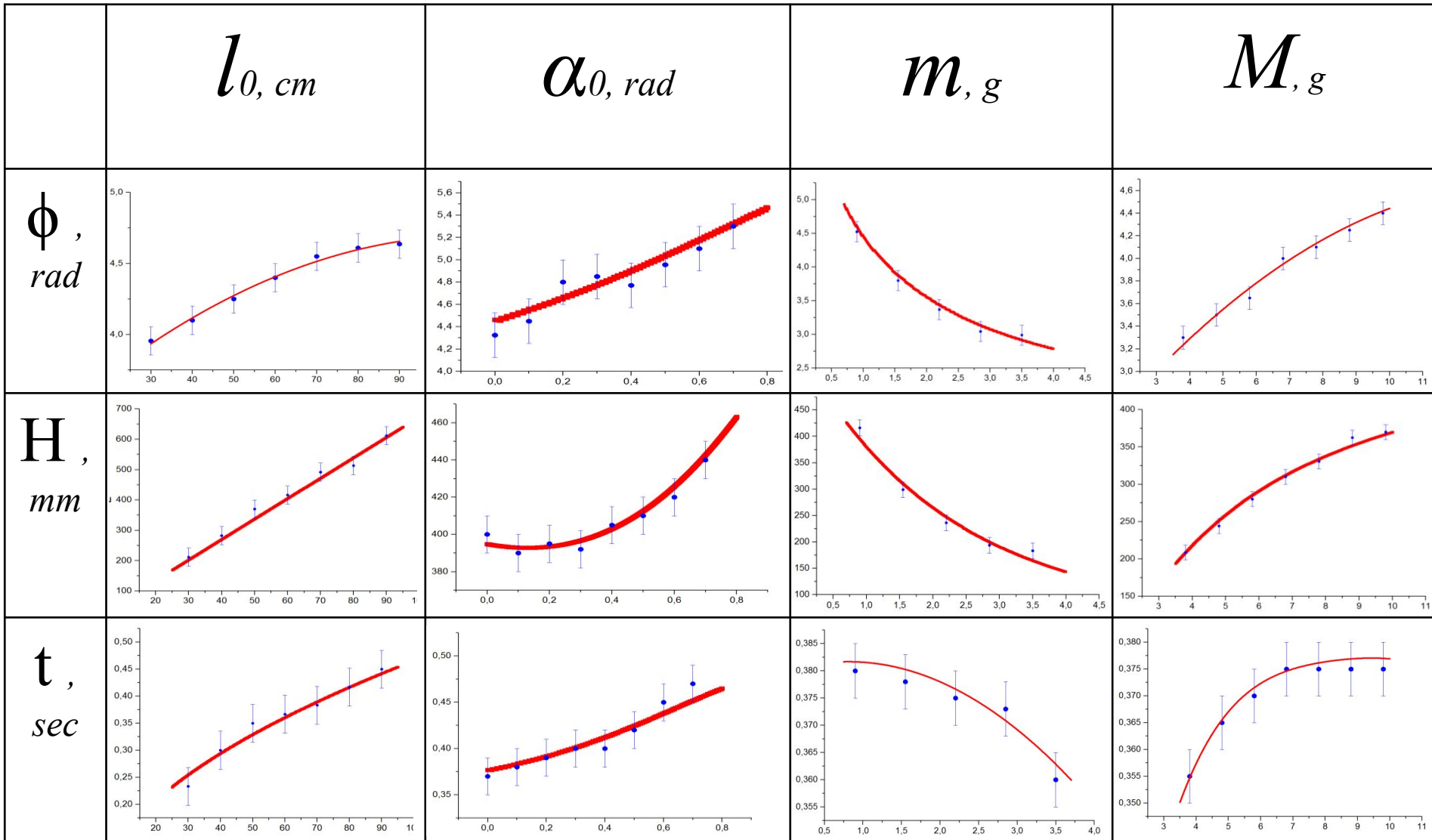
The higher initial distance between light load and rod the higher H

Qualitative explanation ✓

Quantitative model ✓

Parametric investigation ●

# Whole parametric investigation

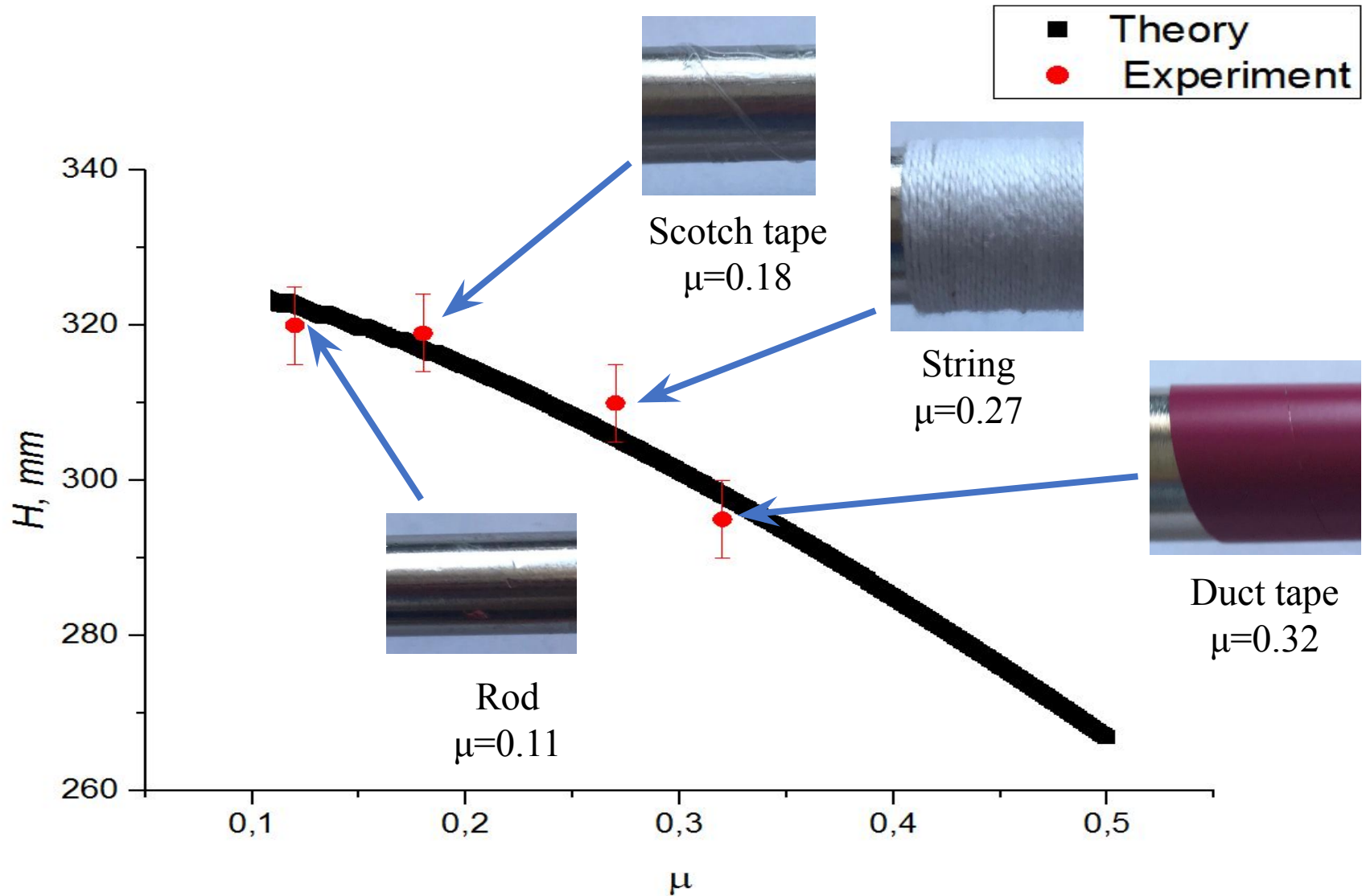


Qualitative explanation ✓

Quantitative model ✓

Parametric investigation ●

# Influence of the friction coefficient



Qualitative explanation ✓

Quantitative model ✓

Parametric investigation ●

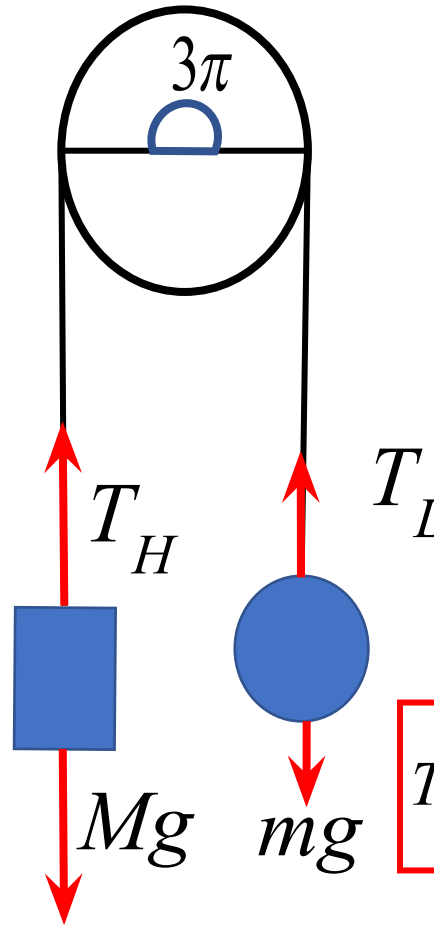
# Boundary conditions



$$M/m=2.75$$



$$M/m=2.95$$



$$T_H = Mg$$

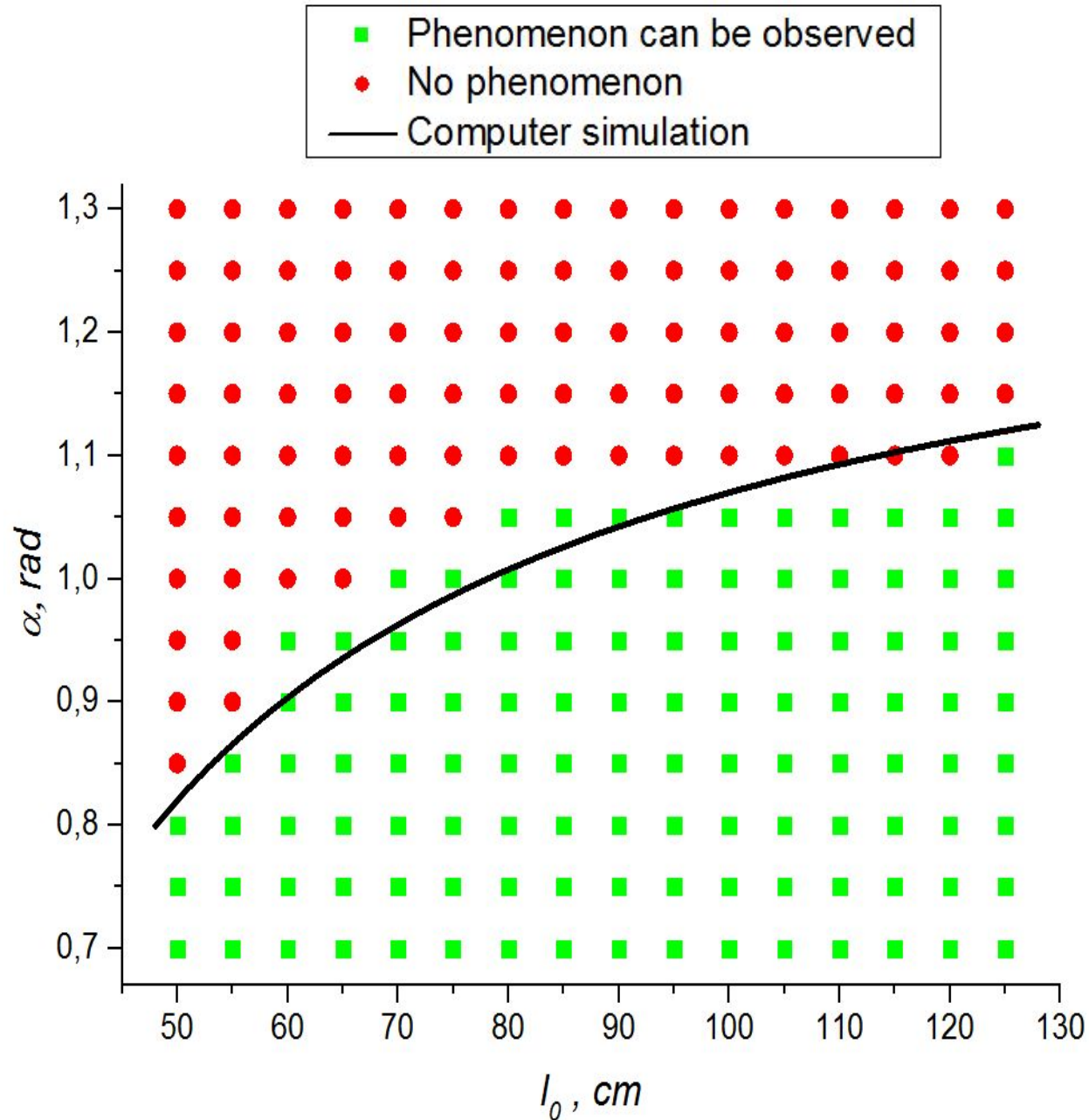
$$T_L = mg$$

$$\frac{M}{m} \geq e^{3\pi\mu}$$

$$\text{Theory prediction} - \frac{M}{m} \geq 2.82$$

$$\frac{M}{m} \leq 2.82 - \text{no phenomenon}$$

# Boundary conditions

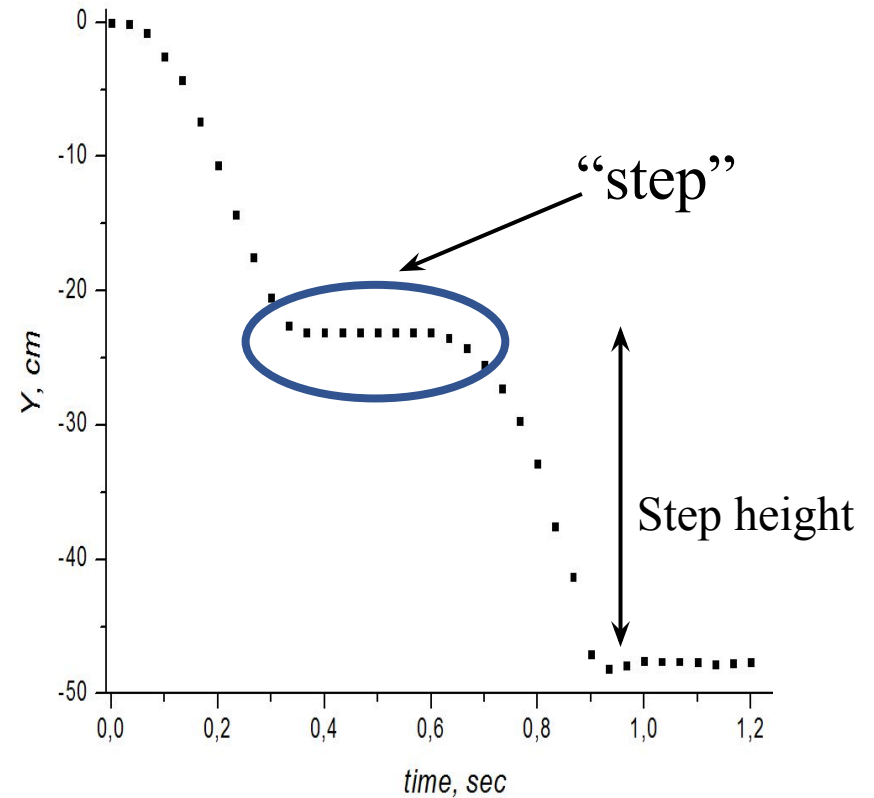


$$\frac{M}{m} = 3.57$$

# «Step» falling of heavy load



*Heavy load  $Y(t)$*

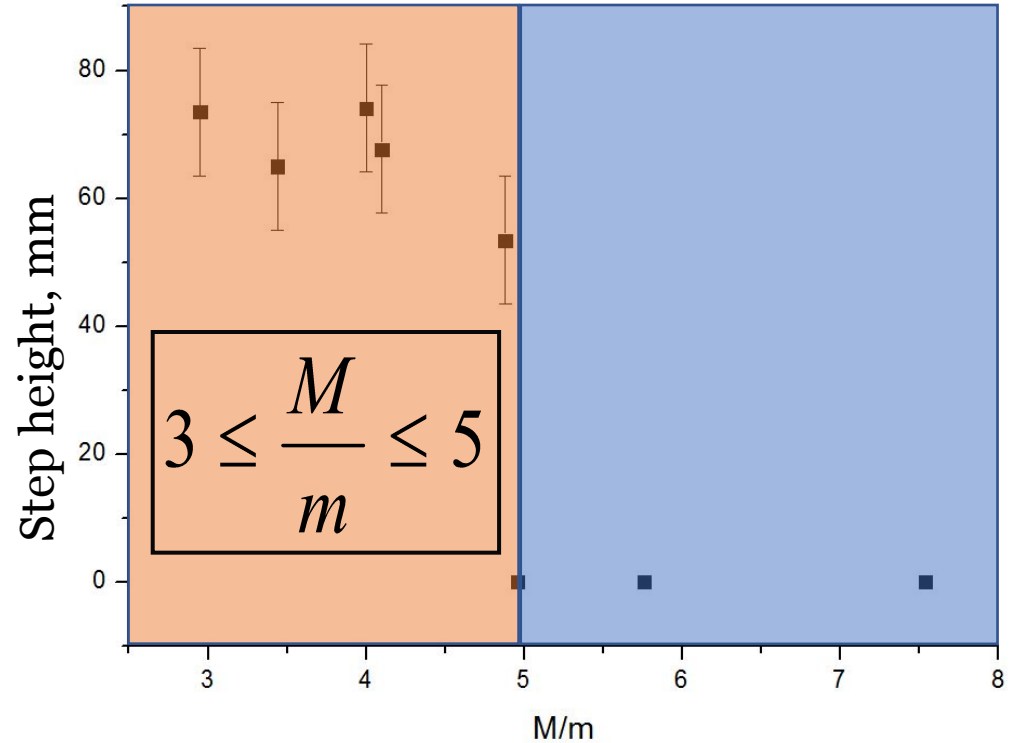
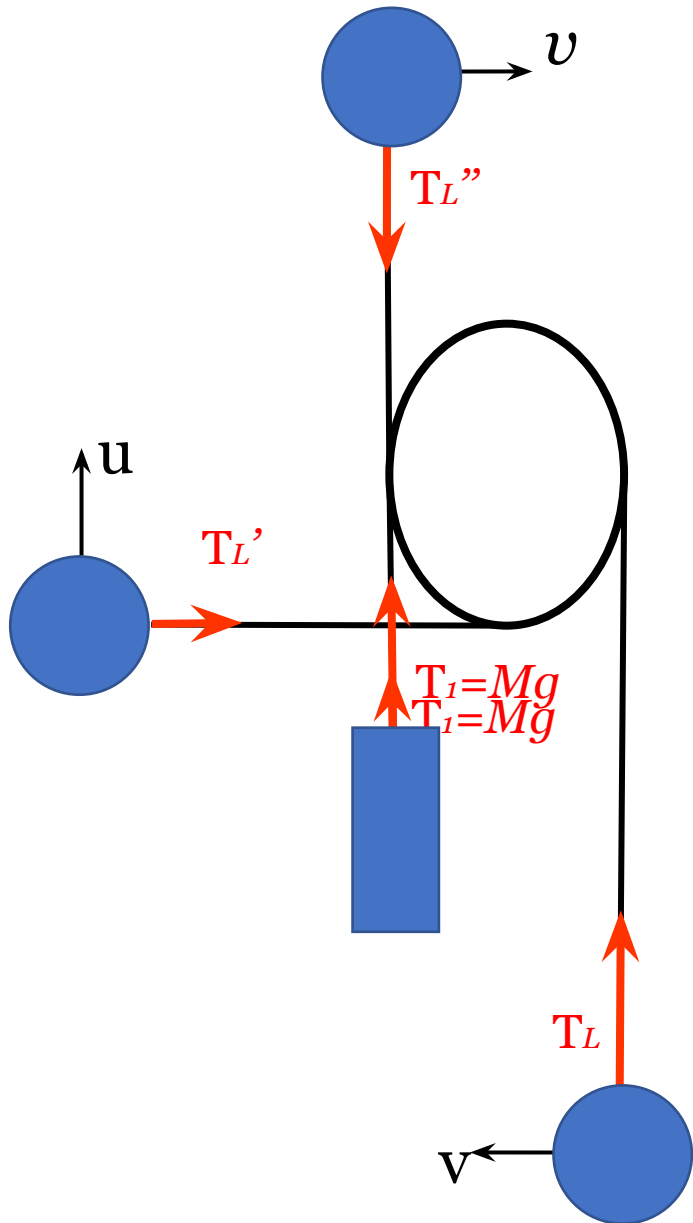


Qualitative explanation ✓

Quantitative model ✓

Parametric investigation ●

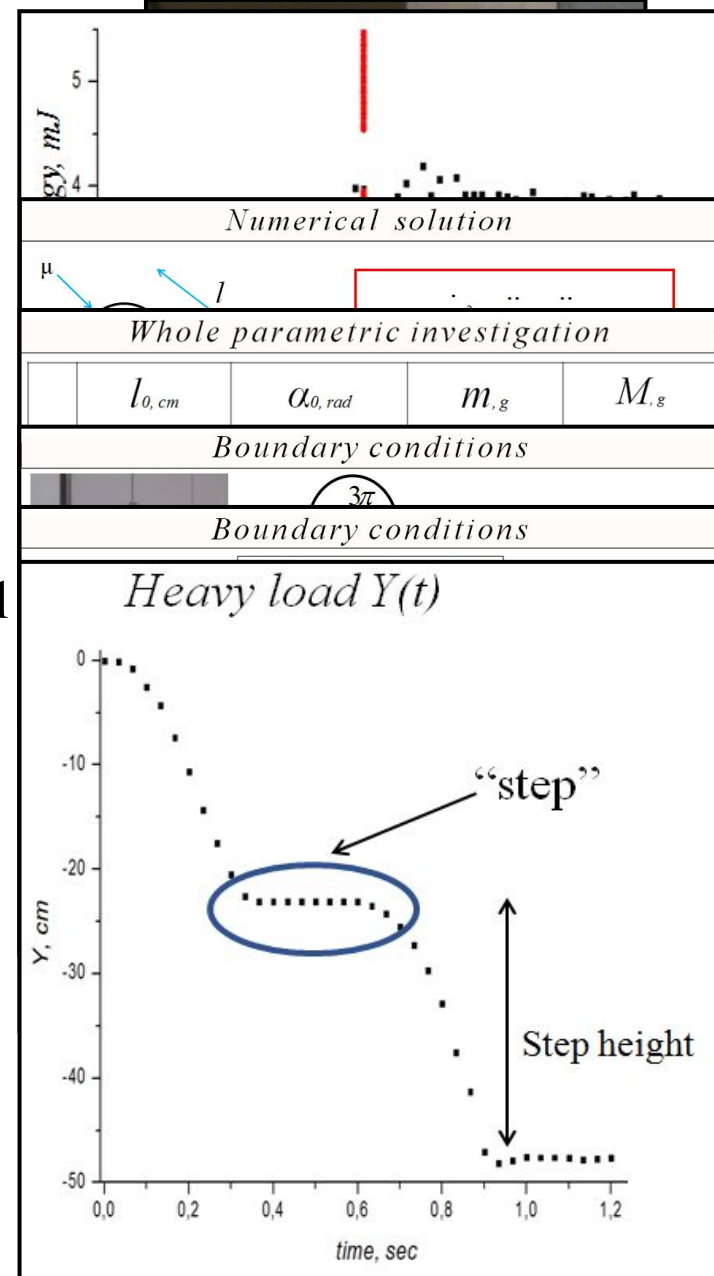
# «Step» falling



Step falling can be observed with small mass relationship

# Conclusion

- Was built experimental setup excluding human factor and control of 3-dimensional effect
- Light load sweeps around because of the energy transfer
- Heavy load stops by friction force
- Built mathematical model based on inextensibility of the string, friction between string and cylindrical rod, 2-nd Newton's laws and torque equation.
- Theory has a good agreement with experiment
- Found out minimal relationship between masses needed for phenomenon observation and relationship between
- Such mode as «step falling» was explained





# *Thank you for your attention!*

Connect two loads, one heavy and one light, with a string over a horizontal rod and **lift up the heavy** load by **pulling down the light one**. Release the light load and it will **sweep around** the rod, **keeping the heavy** load from falling to the ground. Investigate this phenomenon.

Also was investigated:

- Massive string
- Back sweeping
- Rod strike of light load
- Swinging of heavy load



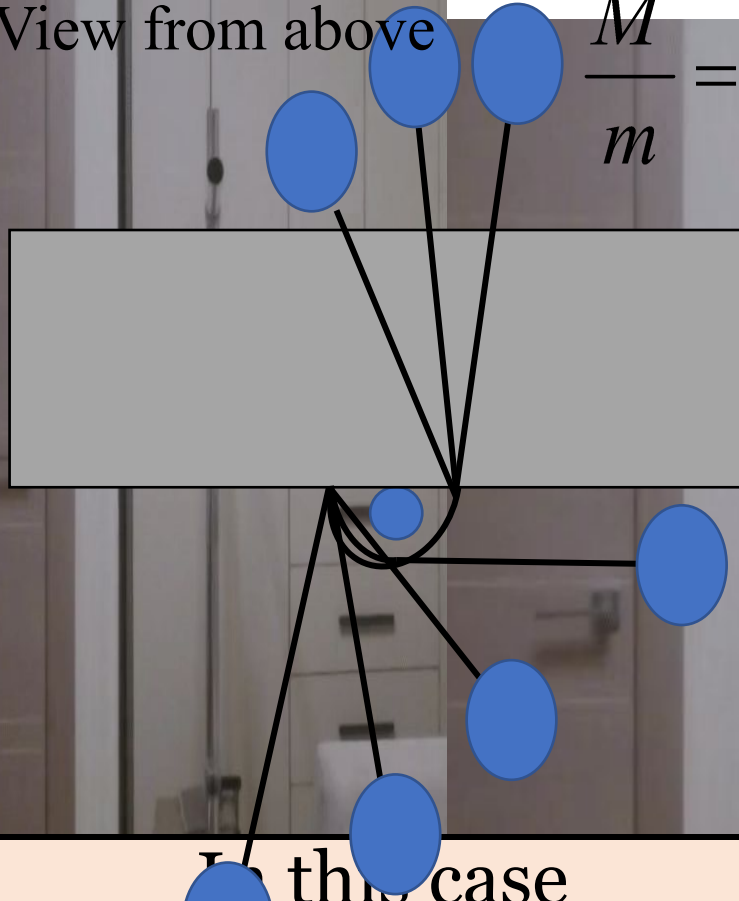
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Additional slides

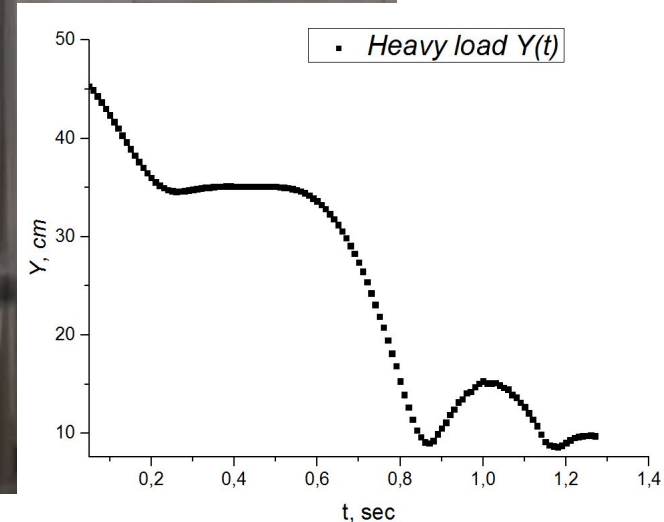
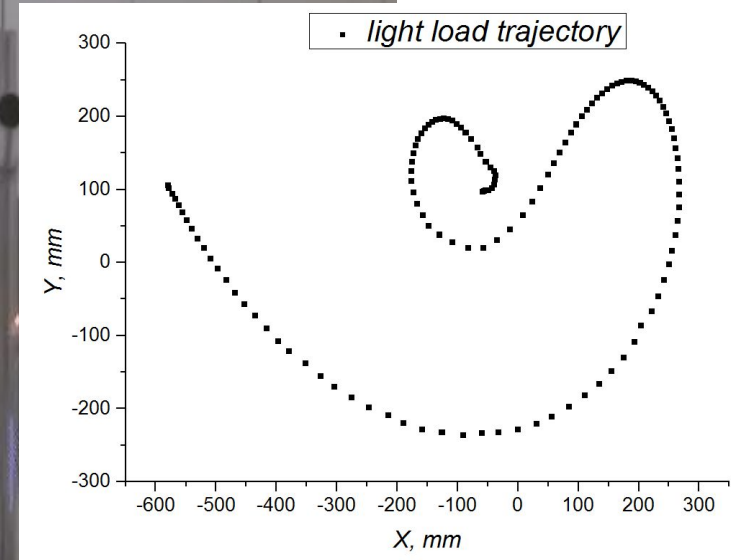
# Back sweeping

View from above

$$\frac{M}{m} = 1.6 < 2.82$$

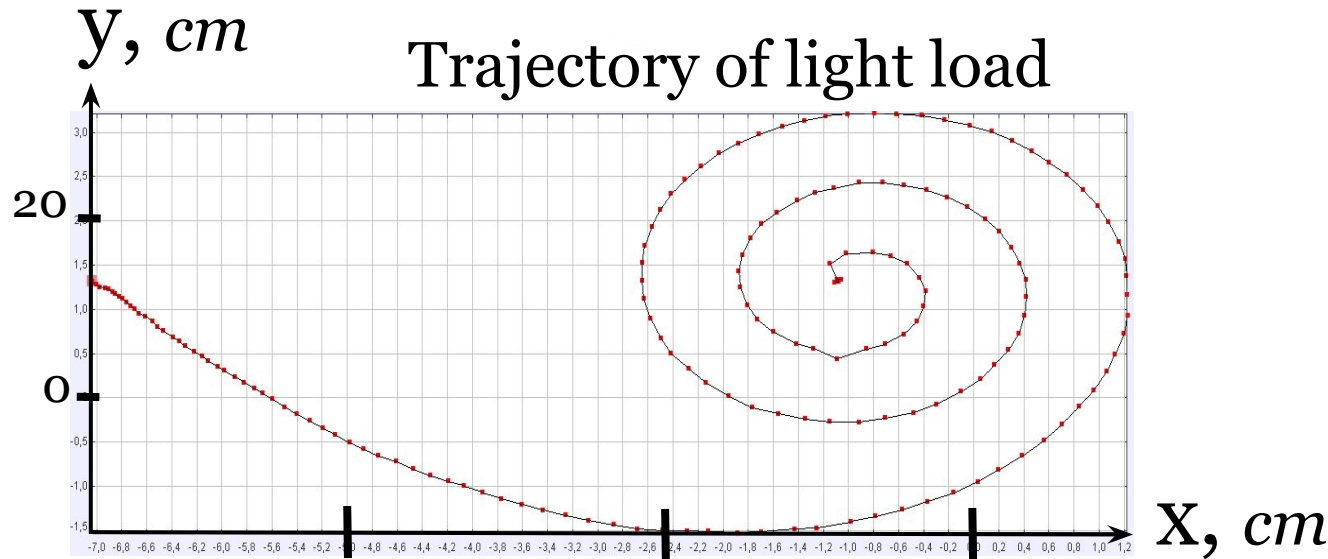


In this case  
3-dimensional of the  
problem **can't** be  
neglected





Key observation



Parameters

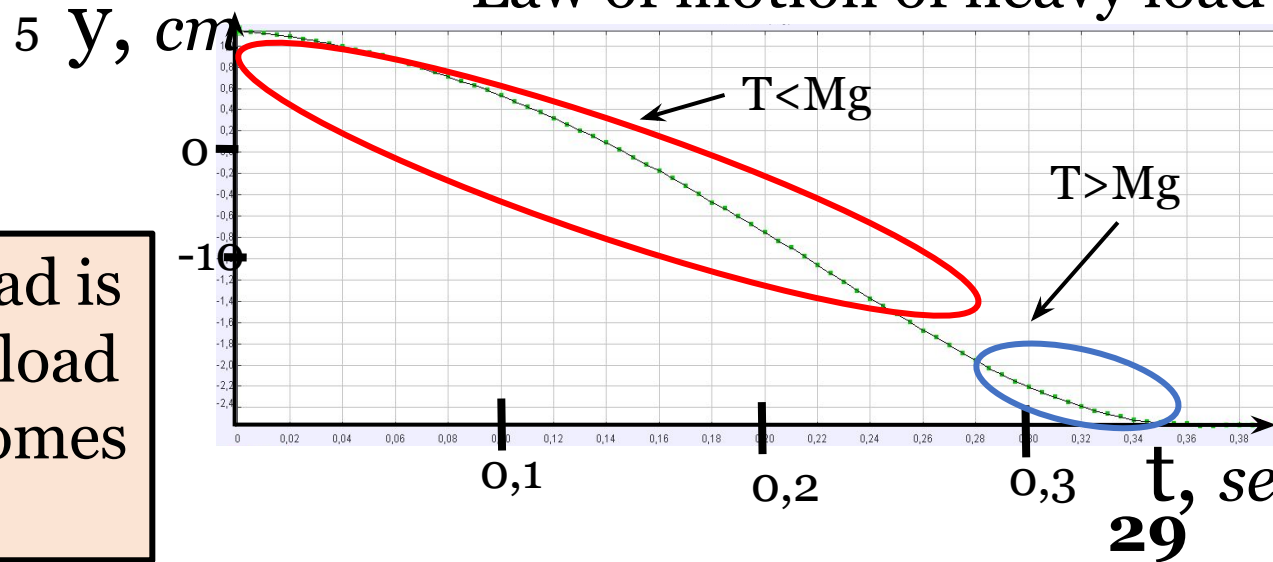
$m = 1 \text{ g}$

$M = 10 \text{ g}$

$l = 65 \text{ cm}$

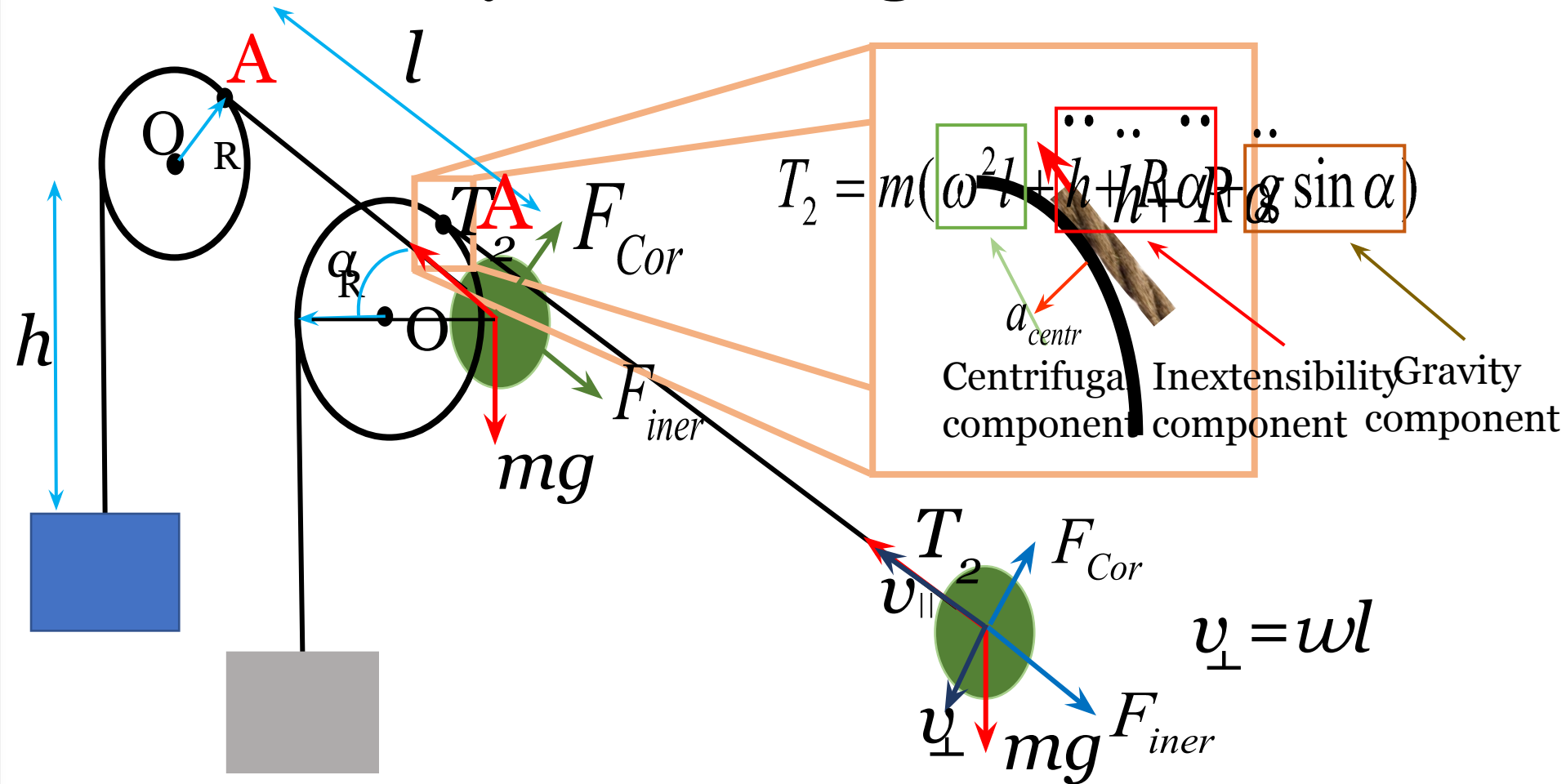
$\phi_0 = 90^\circ$

Law of motion of heavy load

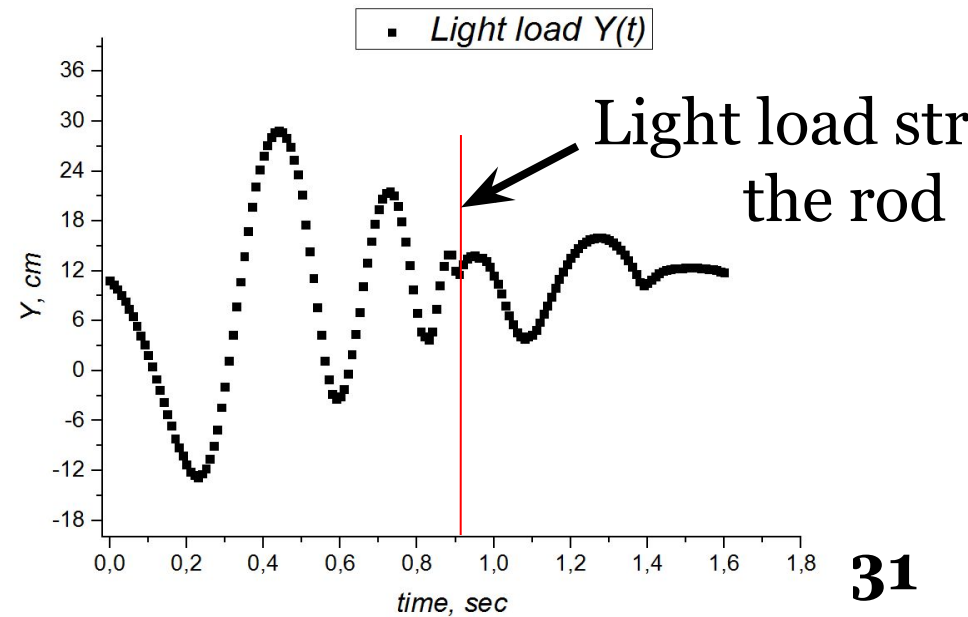
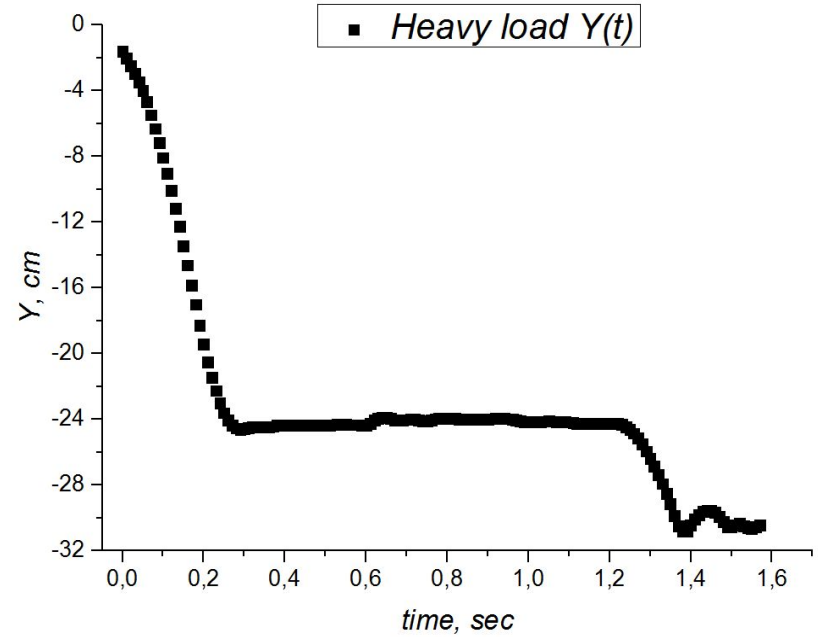


Trajectory of light load is a spiral. After heavy load stop spiral pitch becomes constant

# Dynamics of light load



# Rod strike



# Numerical solution error

$$\Delta \approx \overset{\cdot}{h} dt$$

$$\text{Total error} = \sum \Delta_i$$

*Iteration error – 3,4mm*

*Value – 350mm*

*Solution error  $\approx 1\%$*

$$\Delta \approx \overset{\cdot}{\alpha} dt$$

$$\text{Total error} = \sum \Delta_i$$

*Iteration error – 0,03*

*Value – 3,33*

*Solution error  $\approx 1\%$*



# Setup scheme

Massive string N°1



$$\rho_1 = (0,80 \pm 0,02) \frac{\text{g}}{\text{m}} \quad \mu_1 = 0,110 \pm 0,004$$

Massive string N°2



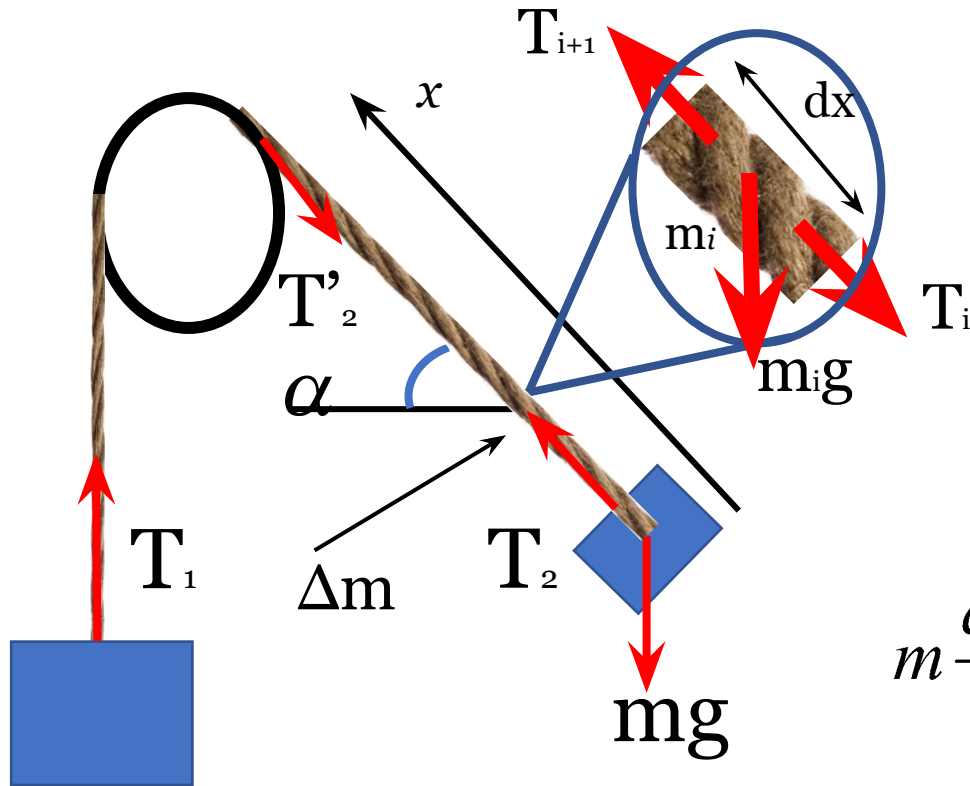
$$\rho_2 = (1,80 \pm 0,02) \frac{\text{g}}{\text{m}} \quad \mu_2 = 0,100 \pm 0,004$$



Electronic scale  
measurements error = 0,01g

$\rho$  – linear density  
of string

# Corrections caused by massive string



$$m_i = m \frac{dx}{l}$$

2-nd Newton law

$$m \frac{dx}{l} \omega^2 x = T_{i+1} - T_i - m \frac{dx}{l} g \sin \alpha$$

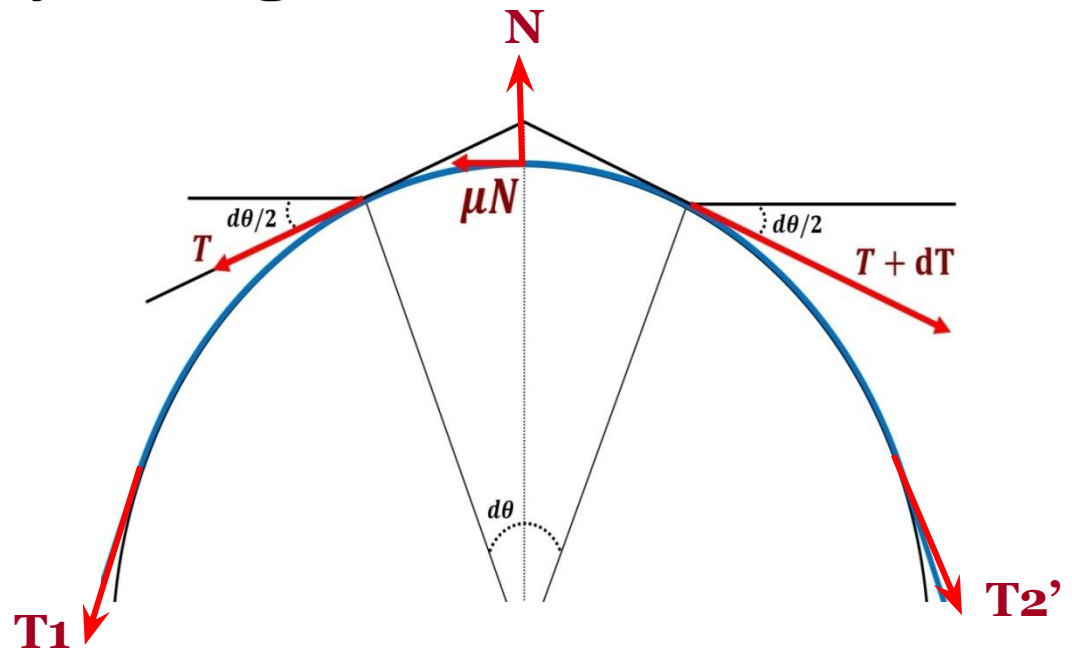
$$\Delta T_2 = l\rho(\omega^2 l + h + R\alpha + g \sin \alpha)$$

# Corrections caused by massive string

$\rho$  – linear density of string

**ВЫВОД ФОРМУЛЫ**

$$\frac{T_1 - \rho v^2}{T_2' - \rho v^2} = e^{\mu\theta}$$



D. J. Dunn 2005  
«Solid mechanics. Dynamics. Tutorial –  
pulley drive system»

# Correction in Euler's formula caused by massive string

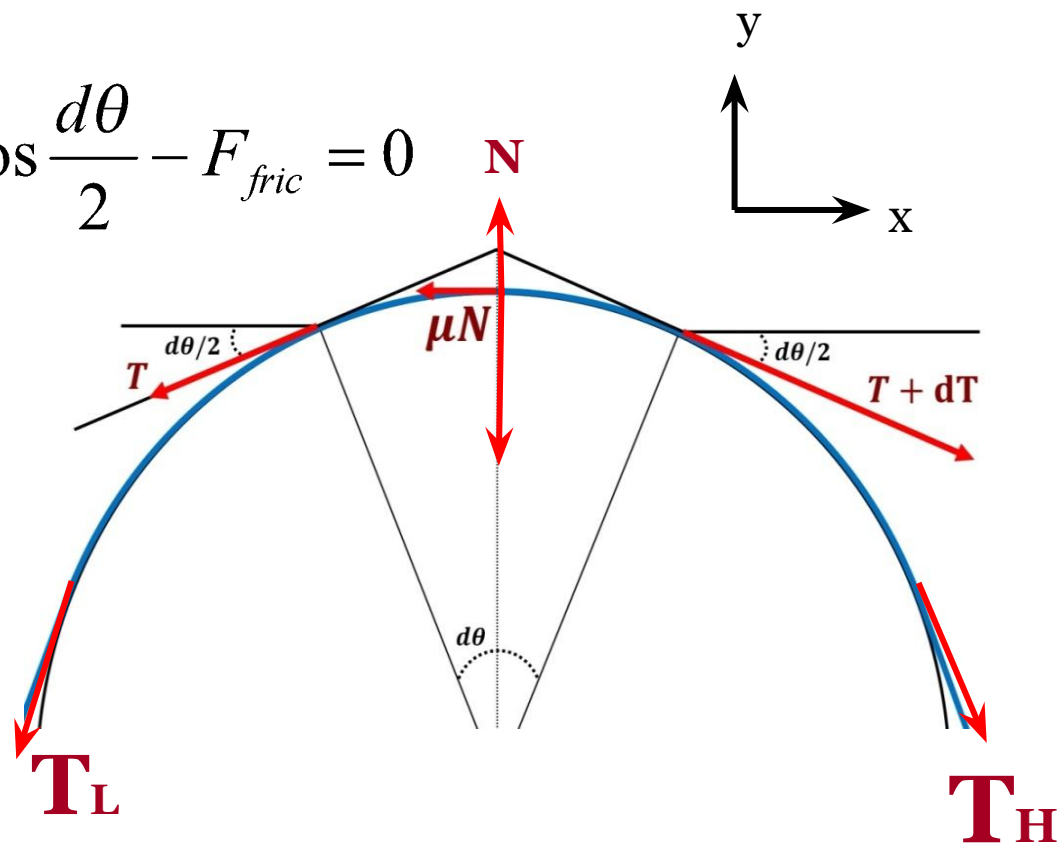
$$Y \text{ axis : } N + \rho d\theta v^2 = T d\theta$$

$$X \text{ axis : } (T + dT) \cos \frac{d\theta}{2} - T \cos \frac{d\theta}{2} - F_{fric} = 0$$

$$N = T d\theta - \rho d\theta v^2$$

$$dT = F_{fric} = \mu N$$

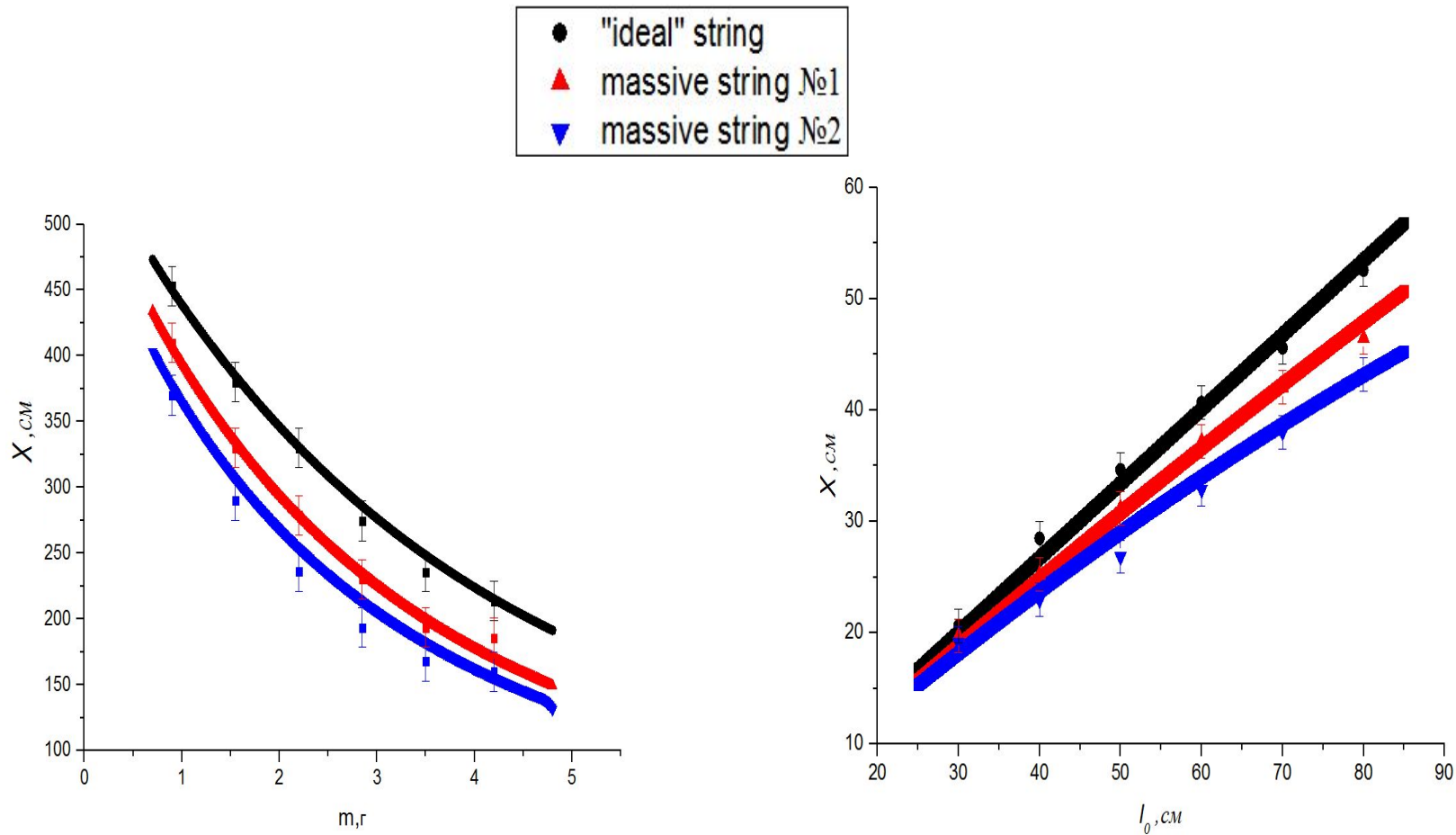
$$dT = \mu d\theta (T - \rho v^2)$$



$\rho$  – linear density of string

$$\frac{T_1 - \rho v^2}{T_2' - \rho v^2} = e^{\mu\theta}$$

# Comparing theory with experiment for massive string

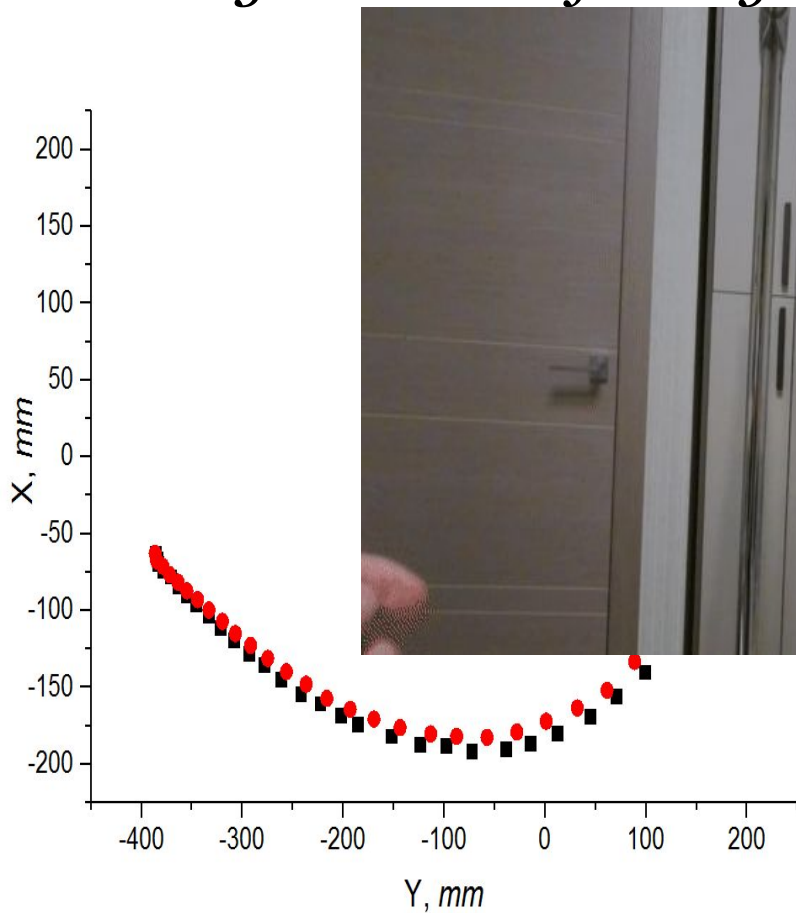


The theory agrees with the experiment!  
The greater the mass of the thread, the  
smaller the value of  $X$

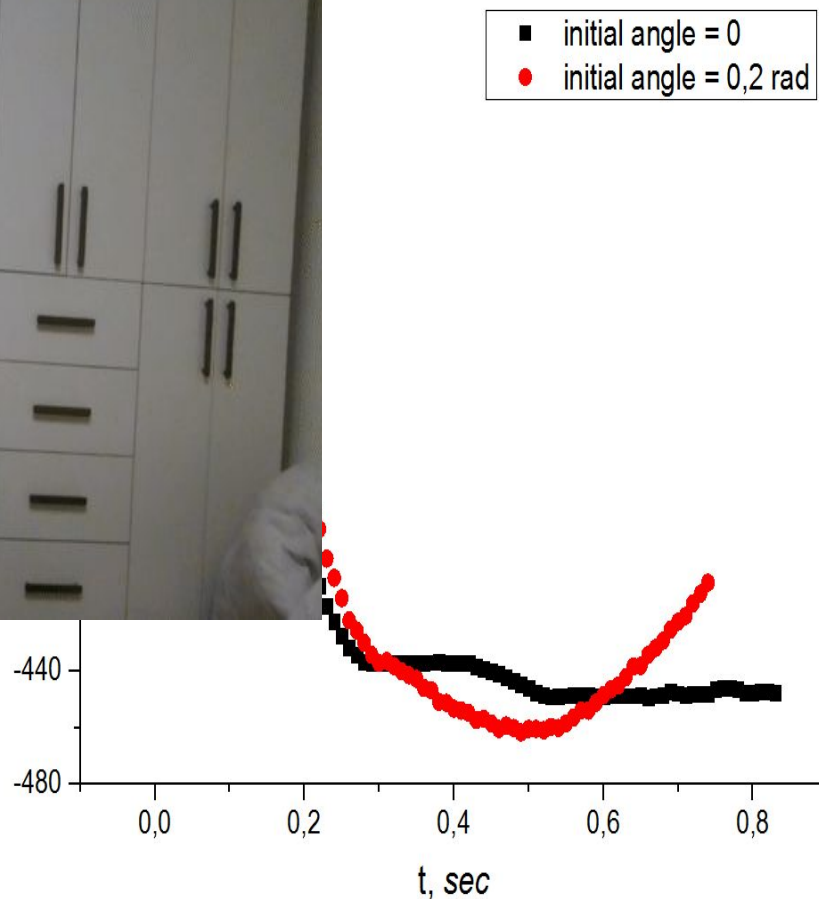


## Swinging heavy load

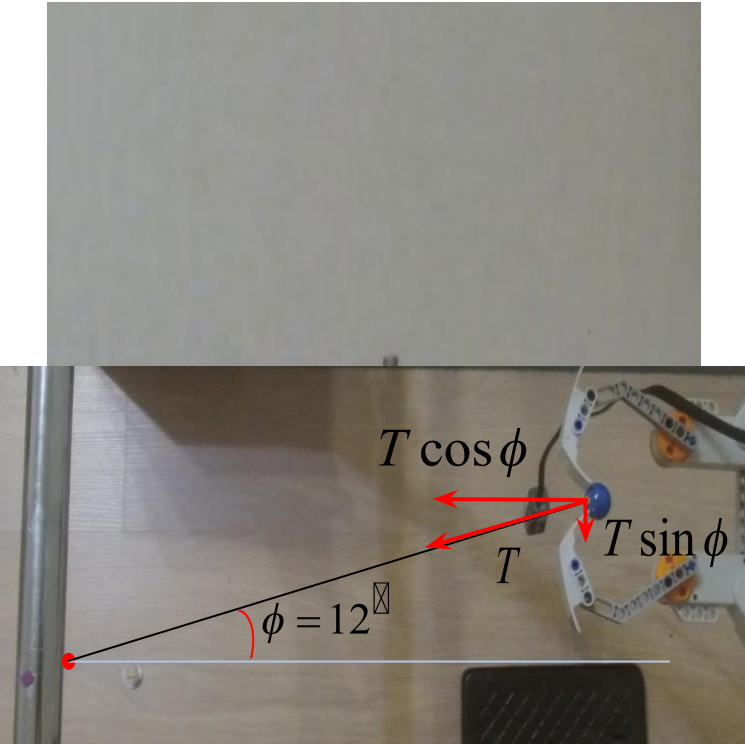
*Light load trajectory*



*Heavy load  $Y(t)$*

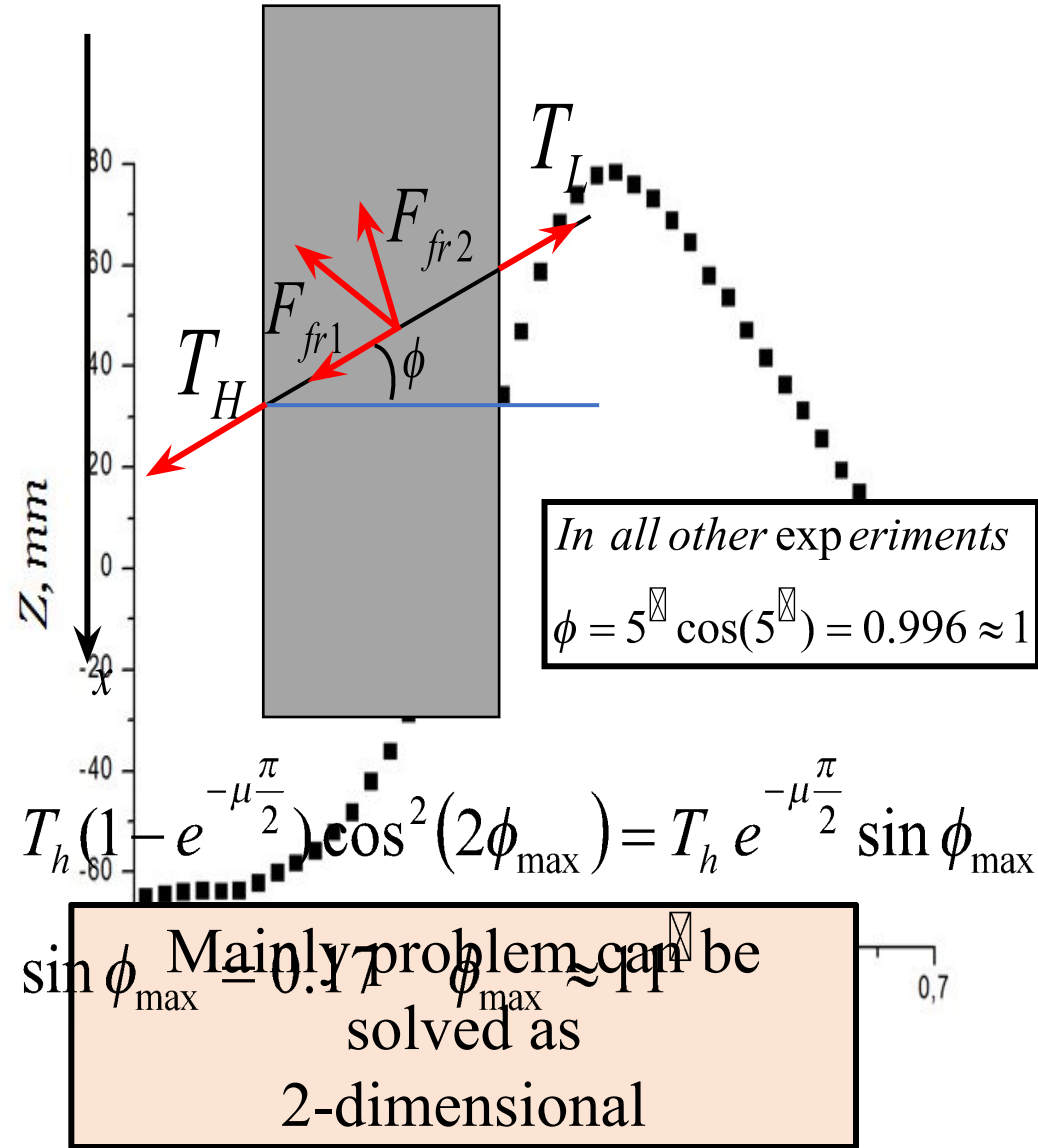


# 3 - dimensional movement



2 - nd Newton law in projection on x axe :

Maximal angle  $\phi$  can be predicted very well

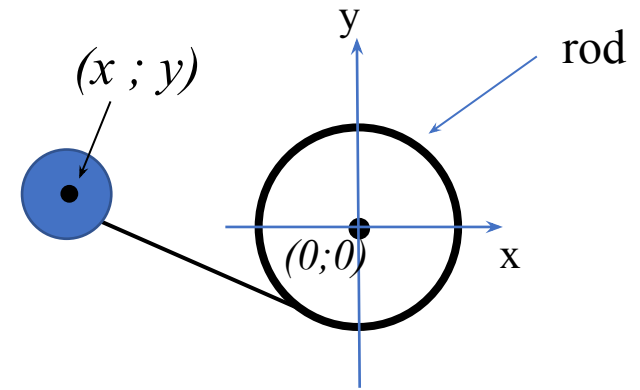
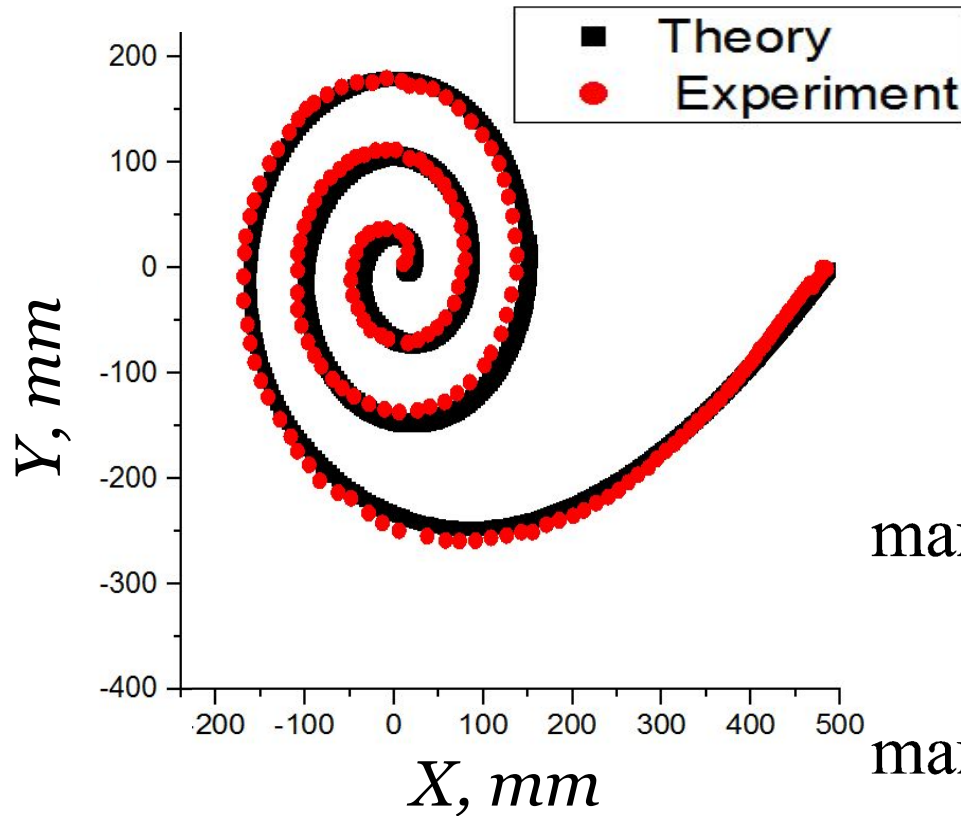


Qualitative explanation ✓

Quantitative model ●

Parametric investigation

# Light load trajectory



$$\max\left(\frac{X_{teor}}{X_{prac}}\right) = 5.5\%$$

$$\max\left(\frac{Y_{teor}}{Y_{prac}}\right) = 4.5\%$$

$$M=18 \text{ g}$$

$$m=3 \text{ g}$$

$$l_0=50 \text{ cm}$$

$$\alpha=0$$

It's good agreement between theory and experiment

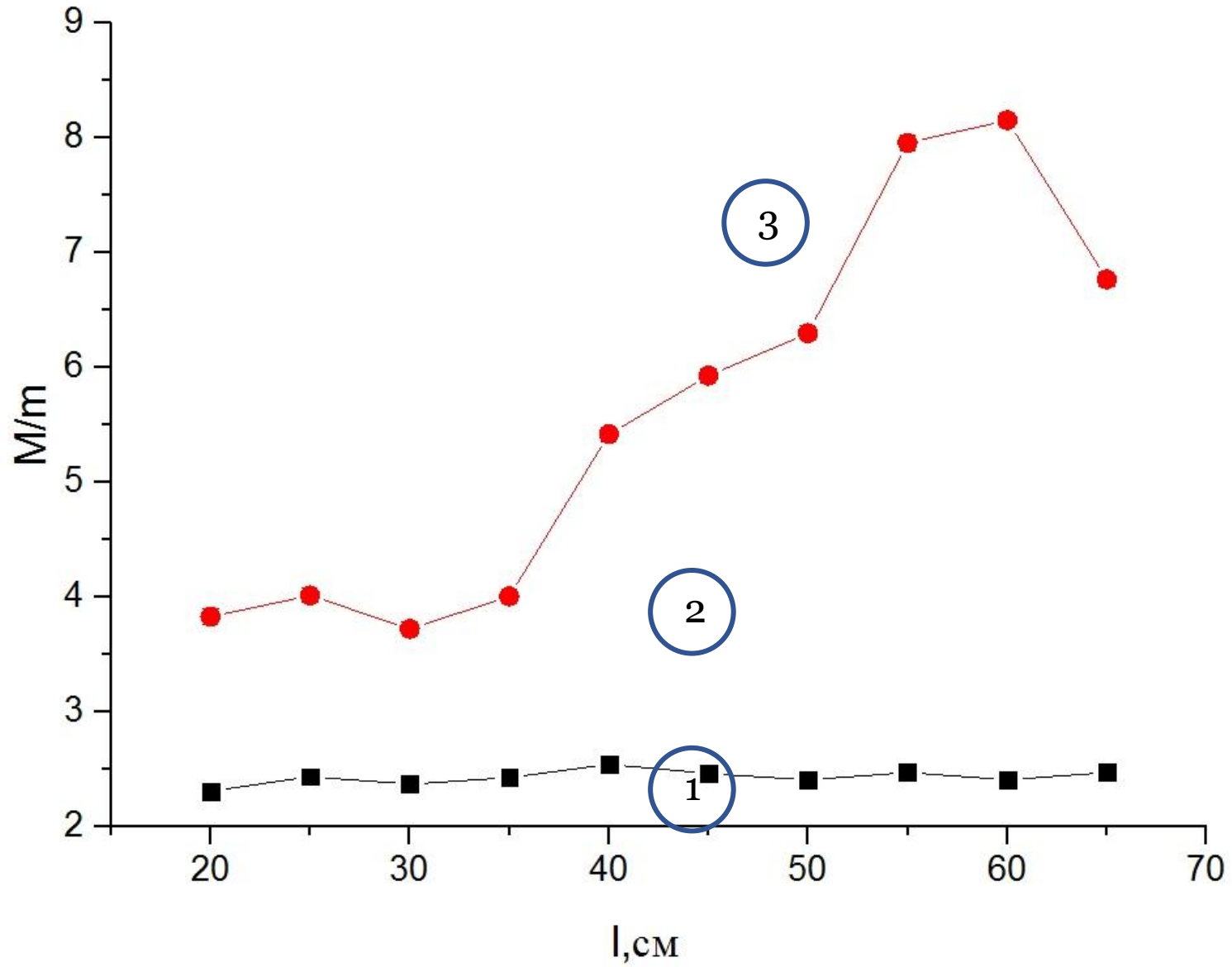
Qualitative explanation ✓

Quantitative model ✓

Parametric investigation ●



**Режимы запусков**



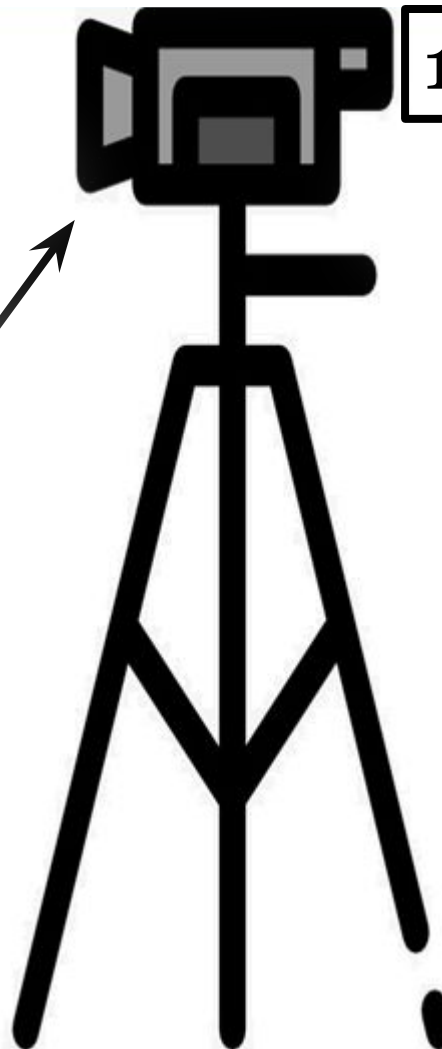
# Setup scheme (переделать)

Горизонтальный стержень



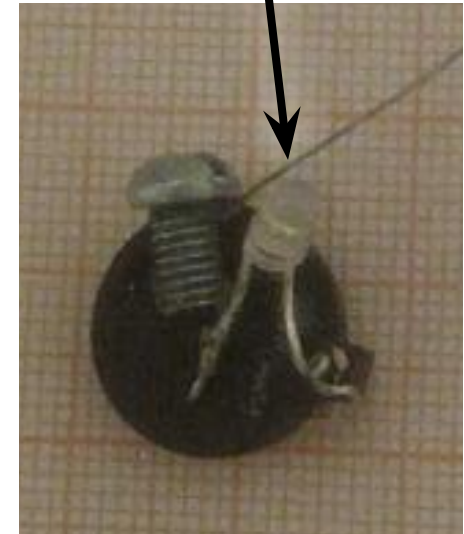
Лёгкий рыболовный грузик на леске

Камера



100 fps

Светодиод



Качественное объяснение



Мат. модель



Параметрическое исследование

