



MECHANICAL VIBRATIONS

Free vibration damped system

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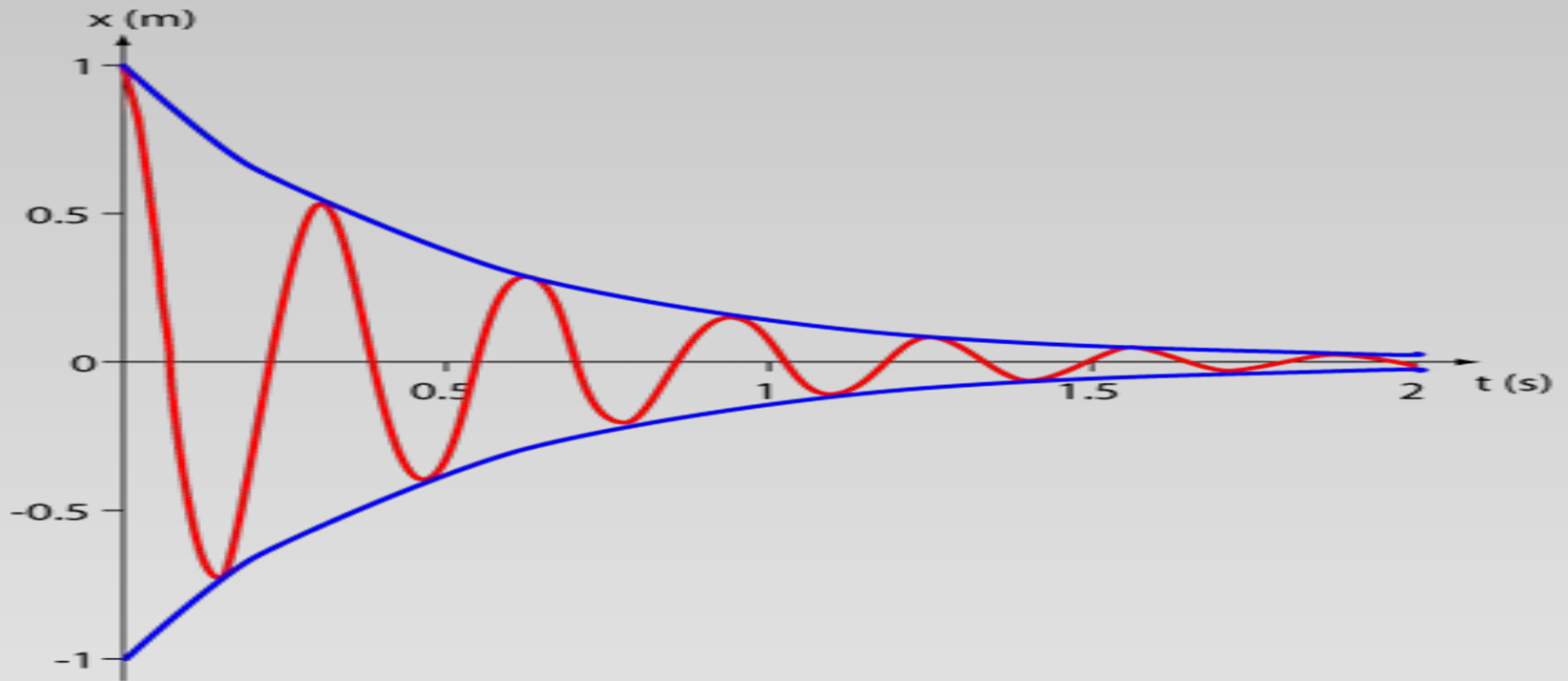
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**Every object, every particle and every system
oscillates in its own natural frequency or set of
frequencies**

Frequency mean...?? what does natural

DAMPED OSCILLATIONS

.Amplitude goes on decreasing with time

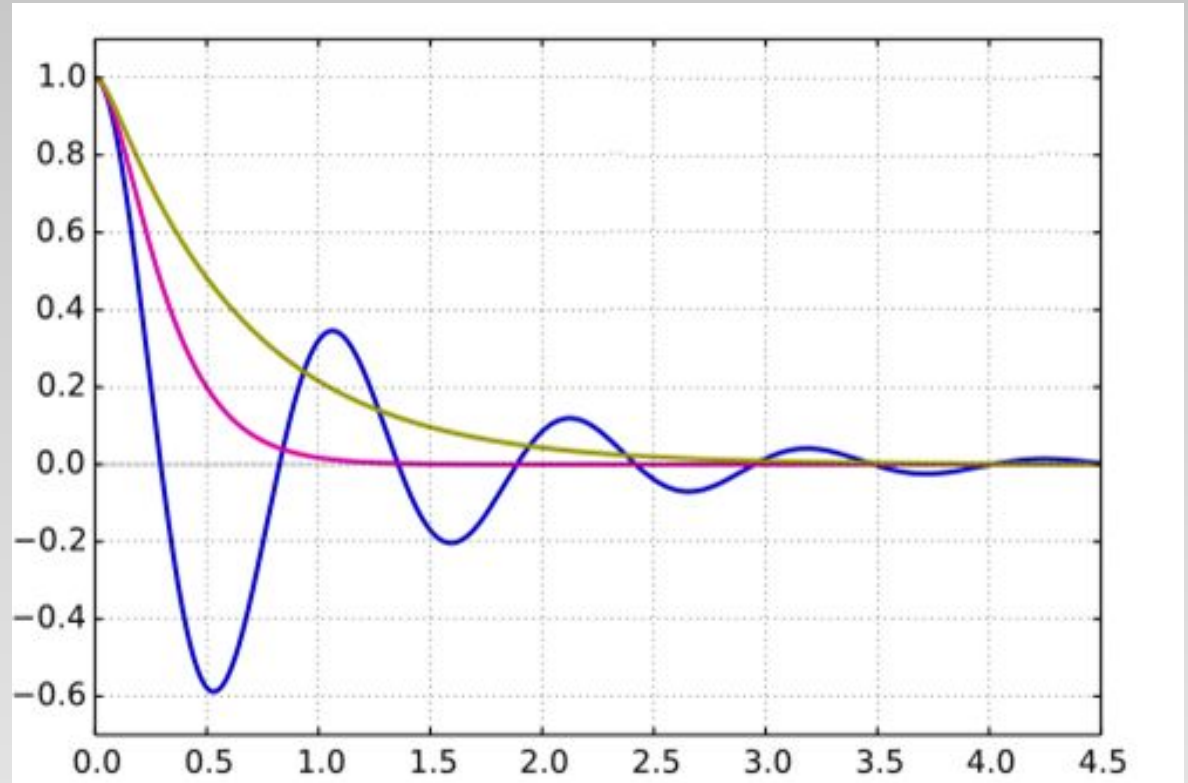


TYPES OF DAMPING OSCILLATIONS

Over-damped

Critically damped

Under damped



TYPES OF DAMPING OSCILLATIONS



Stringed instruments “Under-damped”



Toilet flush button “Over-damped”



Gun “Critical”

TYPES OF DAMPING

Material damping -1

(internal friction, mechanical hysteresis)

Friction at joints -2

Added layers of materials with high loss factors -3

(e.g. viscoelastic materials)

Hydraulic dampers (shock absorbers, hydromounts) -4

Air/oil pumping: squeeze-film damping -5

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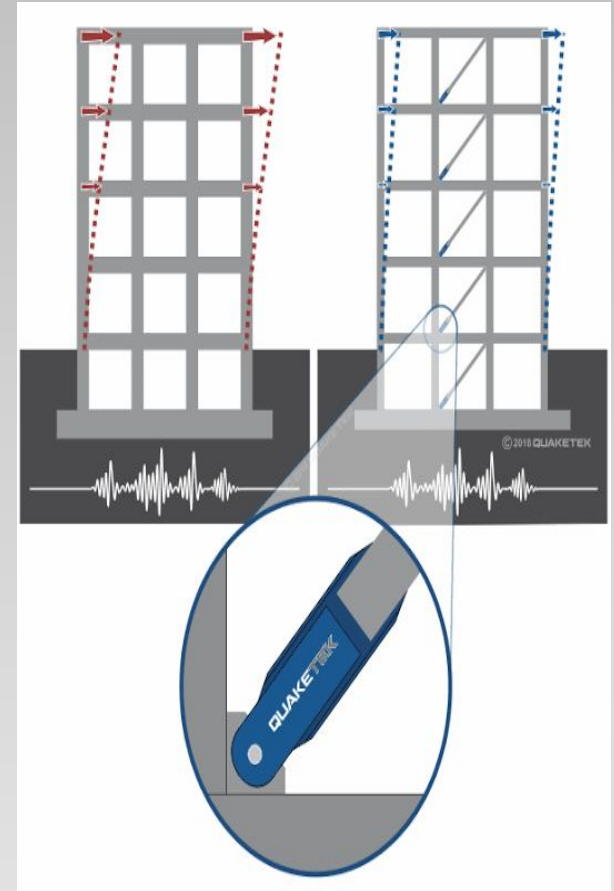
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HYDRAULIC DAMPERS

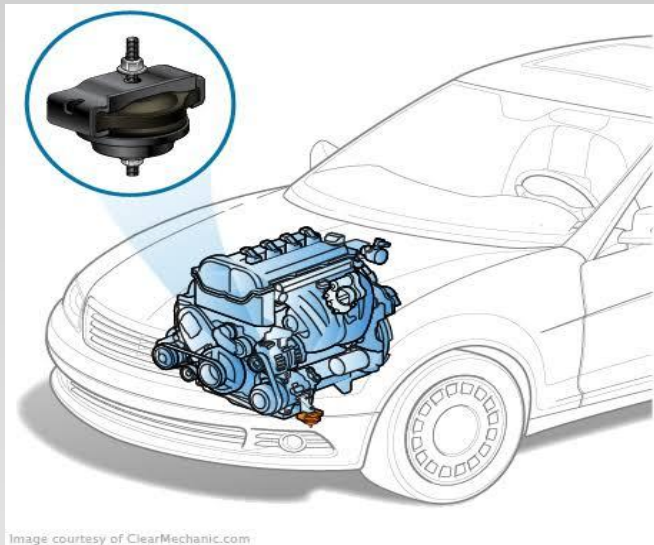
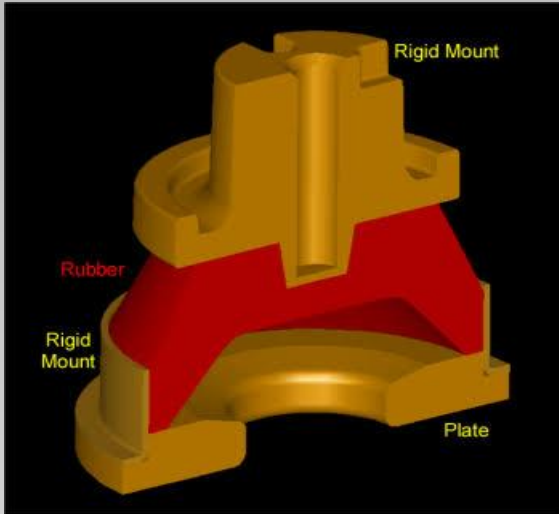
Used for bridges, buildings and cars to absorb the impact from the bumps and earthquakes.



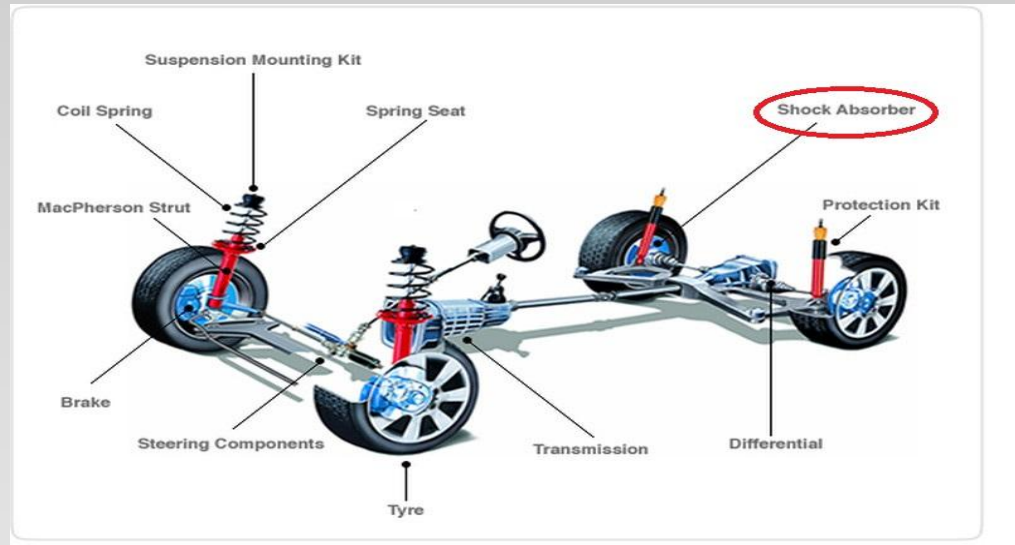
In Bridges

In Buildings

HYDRAULIC DAMPERS

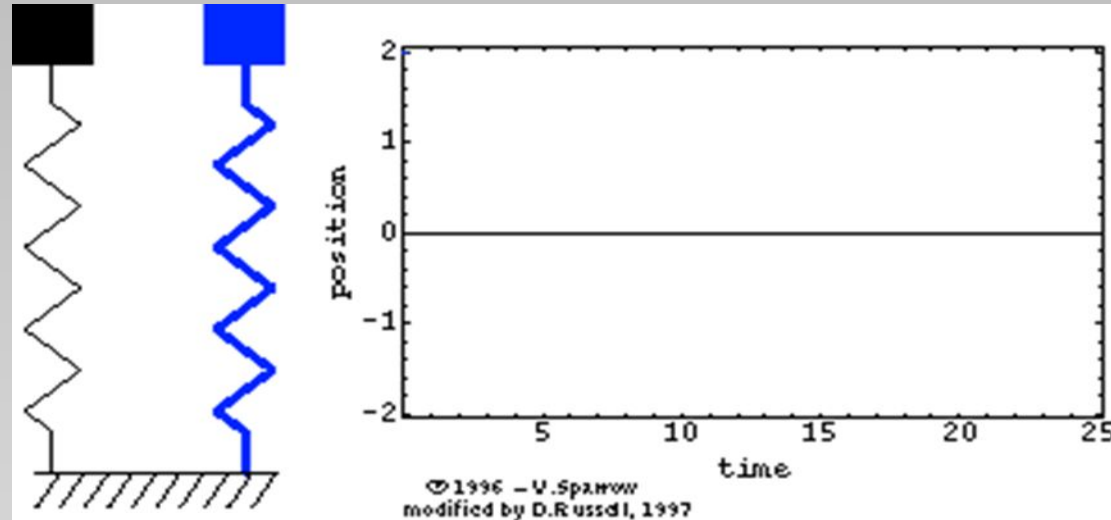
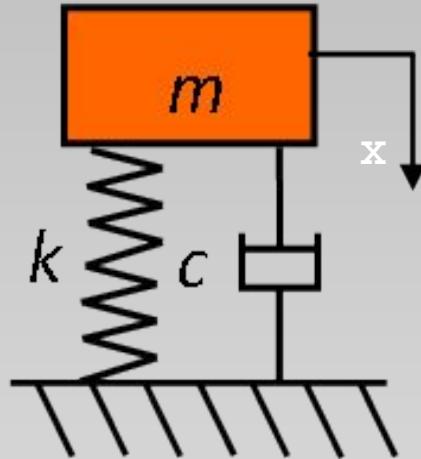


Hydro-mounts in car



Shock absorber in car

REVIEW OF DAMPING MECHANISMS



The equation of motion is

$$m \ddot{x} + c \dot{x} + kx = 0$$

inertia force

damping force

stiffness force

FREE VIBRATION EFFECT OF DAMPING

The under-damped displacement of the mass is given by •

$$x = \underbrace{Xe^{-\zeta\omega_n t}}_{\text{Exponential decay term}} \underbrace{\sin(\omega_d t + \phi)}_{\text{Oscillatory term}}$$

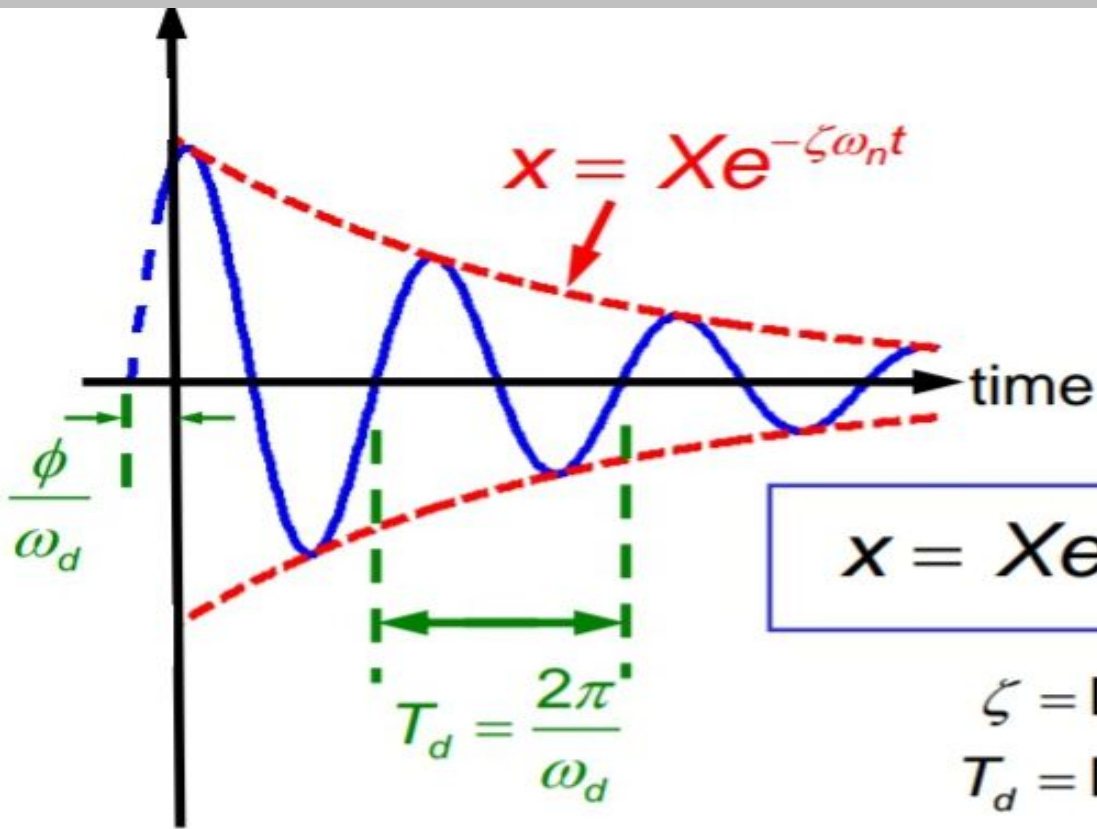
$$\zeta = \text{Damping ratio} = c/(2m\omega_n) \quad (0 < \zeta < 1)$$

$$\omega_n = \text{Undamped natural frequency} = \sqrt{k/m}$$

$$\omega_d = \text{Damped natural frequency} = \omega_n \sqrt{1 - \zeta^2}$$

$$\phi = \text{Phase angle}$$

Free vibration effect of damping



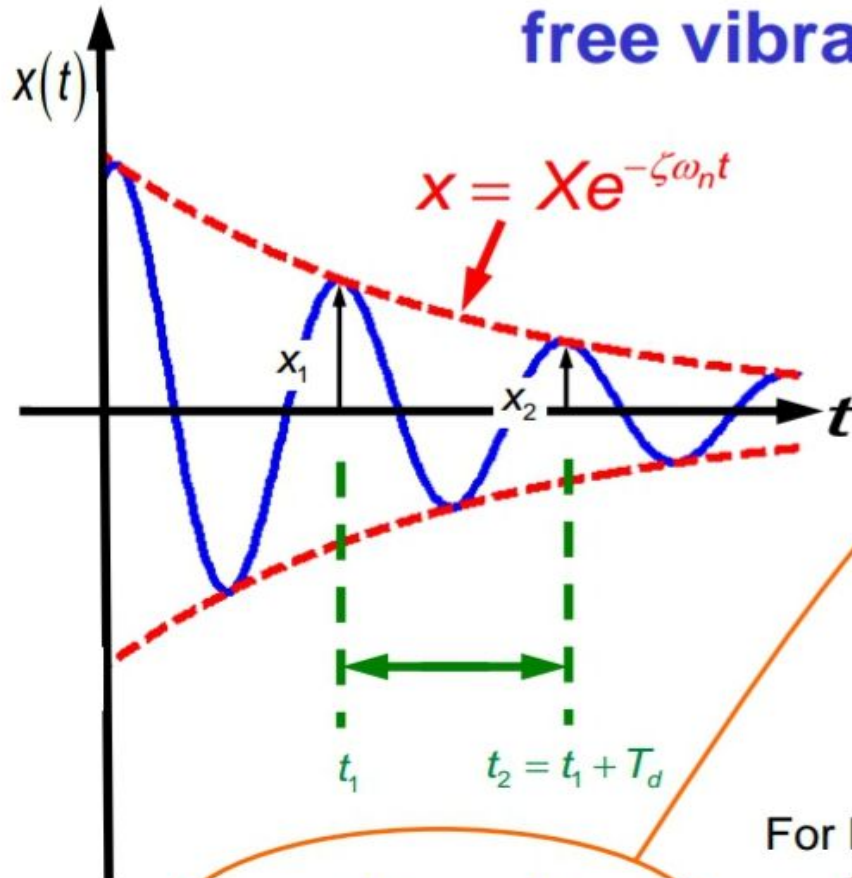
$$x = Xe^{-\zeta\omega_n t} \sin(\omega_d t + \phi)$$

ζ = Damping ratio

T_d = Damping period

ϕ = Phase angle

Measurement of Damping – decay of free vibration



Measure the amplitude of two successive cycles

$$\frac{x_1}{x_2} = e^{\zeta\omega_n T_d}$$

$$\delta = \ln\left(\frac{x_1}{x_2}\right) = \zeta\omega_n T_d$$

Logarithmic decrement

$$\text{So } \delta = \frac{2\pi\zeta}{\sqrt{1-\zeta^2}}$$

For light damping $\delta \approx 2\pi\zeta$

$$\text{So } \zeta \approx \frac{\delta}{2\pi} \leftarrow \text{measured}$$

$$T_d = \frac{2\pi}{\omega_d} = \frac{2\pi}{\omega_n \sqrt{1-\zeta^2}}$$

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THANKS

FOR YOUR TIME