

Mathematics for Economists II Week #12

Review

Predator-prey relationships Solving simultaneous first order differential equations Steady states and their stability Phase portraits of systems

Week 1:

Sets: Unions, intersections, Venn Diagrams Functions: Definition, notation, types Slopes Linear programming

Week 2:

Derivative as a limit Power rule, chain rule, product rule f'(x), slope, f''(x), concavity exponential functions, natural logs, TVM

Weeks 3 and 4:

Solve simultaneous equations Writing equations in matrix form: Ax = BRules for adding, subtracting, multiplying matrices Identity matrix: I_{ii}=1 if i=j, and 0 if i≠j Rank (How many "leading ones"?) **Row operations Transposed matrices Calculating determinants** Testing for invertibility and calculating **A**⁻¹ **Cramer's Rule Eigenvalues**







Now... the vectors. **Example:** i = 1, 3 $\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 1 \begin{bmatrix} x \\ y \end{bmatrix}, \text{ leading to } \mathbf{x} = -\mathbf{y}$ $\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 3 \begin{bmatrix} x \\ y \end{bmatrix}, \text{ leading to } \mathbf{x} = \mathbf{y}$ **Eigenvectors are** $\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Week 5:

Taylor/Maclaurin series

Week 6:

Quadratics in matrix form Positive/negative definite, positive/negative semidefinite, indefinite matrices

Week 8:

Unconstrained optimization The Hessian matrix Determining max/min from the Hessian definiteness

Week 9:

The Lagrange multiplier Using multiple multipliers for multiple constraints

Week 10:

Kuhn-Tucker inequality constrained optimization Jacobian matrix and bordered Hessian

Week 11:

Ordinary differential equations Integrating factors Separable differential equations

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Predator-Prey Relationships

Assume that some prey x grows in population according to the first order differential equation: $\dot{x}/x = A - By$, or $\dot{x} = x(A - By)$ where y is the population of some predator.

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What is the behavior of this system? What can we determine? Let's look at Excel! :-)

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Solving simultaneous equations

Suppose that we want solutions for both variables (meaning explicit functions in terms of t). How could we do that?

We'll skip the process, and focus on a shortcut. Given: $\dot{x} = Ax + By$ $\dot{y} = Cx + Dy$, we find the eigenvalues of: $\begin{bmatrix} A & B \\ C & D \end{bmatrix}$

Solving simultaneous equations $\begin{bmatrix} A & B \\ C & D \end{bmatrix}$ Next, we take the eigenvalues i and calculate the

eigenvectors with |A|v = iv.

Finally, we use these for the general solution: $x(t) = c_1 v_{1,1} e^{i_1 t} + c_2 v_{1,2} e^{i_2 t}$ $y(t) = c_1 v_{2,1} e^{i_1 t} + c_2 v_{2,2} e^{i_2 t}$ (This is just my notation; see SB Chapter 25)



Solving simultaneous equations - Example $\dot{x} = 2x + y$ $\dot{y} = -12x - 5y$ 3. Find the eigenvectors that go with each eigenvalue. i = -1, -2 $\begin{bmatrix} 2 & 1 \\ -12 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = -1 \begin{bmatrix} x \\ y \end{bmatrix}, \text{ leading to } \begin{bmatrix} 2 & 1 \\ -12 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = -2 \begin{bmatrix} x \\ y \end{bmatrix}, \text{ leading to } _$ Next step?

Solving simultaneous equations - Example $\dot{x} = 2x + y$ $\dot{y} = -12x - 5y$ 3. Find the eigenvectors that go with each eigenvalue. i = -1, -2 $\begin{bmatrix} 2 & 1 \\ -12 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = -1 \begin{bmatrix} x \\ y \end{bmatrix}, \text{ leading to } 3x = -y, \text{ so } \begin{bmatrix} 1 \\ -3 \end{bmatrix}$ $\begin{bmatrix} 2 & 1 \\ -12 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = -2 \begin{bmatrix} x \\ y \end{bmatrix}, \text{ leading to } 4x = -y, \text{ so } \begin{bmatrix} 1 \\ -4 \end{bmatrix}$ Next step?

Solving simultaneous equations - Example $\dot{x} = 2x + y$ $\dot{y} = -12x - 5y$ 4. Plug the values into the solution equations. $x(t) = c_1 v_{1,1} e^{i_1 t} + c_2 v_{1,2} e^{i_2 t}$ $\mathbf{y}(t) = c_1 v_{2,1} e^{i_1 t} + c_2 v_{2,2} e^{i_2 t}$ So... $x(t) = c_1 e^{-t} + c_2 e^{-2t}$ $\mathbf{y}(t) = -3c_1e^{-t} + -4c_2e^{-2t}$ DONE! In Excel, this is 25pt1.

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Solving simultaneous first order differential equations

Steady states and their stability

Phase portraits of systems

Steady States

How would we determine a steady state? What's true at that steady state? Again, the derivatives are zero! So, let's look again at the predator/prey equations. $\dot{x} = x(80 - y)$ $\dot{y} = y(-300 + 2x)$

Setting the changes equal to zero, we have one steady state at (0,0) (no predators, no prey).

What else? x = C/D, and y = A/B. Let's look again!

Steady States

How about that example we solved? $\dot{x} = 2x + y$ $\dot{y} = -12x - 5y$

Solve these simultaneously for no change in x and y; what's the steady state?

Steady StatesHow about this one? $\dot{x} = 2 + y$ $\dot{y} = 1 + x - y$

Solve these simultaneously for no change in x and y; what's the steady state?

Now, what happens if we start a little bit away from the steady state. Do we move toward it, or away?

Let's look at what happens with a previous example:

 $\dot{x} = 2x + y$

 $\dot{y} = -12x - 5y$

12PhasePortraitAndFieldDirectionsOfTwoDimensionalLinearSystems.cdf

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Eigenvalues! :-)

If eigenvalues are all negative, the system is stable. If there's a positive eigenvalue, it will pull us away from the steady state.

Test the stability of these two:

 $\dot{x} = x - 4y$

 $\dot{y} = -x + y$ Stable, or unstable? $\dot{x} = -x$

 $\dot{y} = x - y$ Stable, or unstable?

If eigenvalues are all negative, the system is stable. If there's a positive eigenvalue, it will pull us away from the steady state.

> Test the stability of these two: $\dot{x} = x - 4y$ $\dot{y} = -x + y$ $\mathbf{i} = -1, 3; \text{UNSTABLE}$ $\dot{x} = -x$ $\dot{y} = x - y$ $\mathbf{i} = -1; \text{STABLE}$

Stability of nonlinear systems

What about nonlinear system, such as the predator/prey example? $\dot{x} = x(80 - y)$ $\dot{y} = y(-300 + 2x)$ We have already seen that we spiral out. But why? How can we tell? Eigenvalues of the Jacobian!

We don't do this here... but Example 25.2 in SB will show you how to do this if you need it.

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Phase portraits

Let's look at some pictures of past examples:

 $\dot{x} = x + 2y$

 $\dot{y} = -x + y$ i = -1, 3; UNSTABLE

$\dot{x} = -x$ $\dot{y} = x - y$ i = -1; STABLE

12 Phase Portrait And Field Directions Of Two Dimensional Linear Systems. cdf

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Phase portraits

Let's look at some pictures of past examples:

 $\dot{x} = x + 2y$

$\dot{y} = -x + y$ i = -1, 3; UNSTABLE

$\dot{x} = -x$ $\dot{y} = x - y$ i = -1; STABLE

Now let's draw our own! How do we find the "stable arms"? How can we draw arrows?

Phase portraits

How about that nonlinear example of the predator/prey model? $\dot{x} = x(80 - y)$ $\dot{y} = y(-300 + 2x)$

How do we find the "stable arms"? How can we draw arrows?

Mathematics for Economists II COMPLETE!

Homework10.docx due by next Monday Next week: FINAL EXAM!

Dobře se bav! :-)