# **Уравнения умнее тех, кто их вывел.**

Генрих Герц (1857-1894)

# НЕГИПЕРБОЛИЧНОСТЬ СИСТЕМЫ ГИДРОДИНАМИЧЕСКИХ УРАВНЕНИЙ КЛИМАТИЧЕСКОЙ МОДЕЛИ АТМОСФЕРЫ

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# Гидротермодинамические уравнения для атмосферы

$$\frac{\mathrm{d}\rho}{\mathrm{d}t} = -\frac{1}{\rho} \left( \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) - \text{уравнение сохранения массы}$$

$$\rho \frac{\mathrm{d}v_x}{\mathrm{d}t} = -\frac{\partial p}{\partial x} + \rho f_x^{(\mathrm{cor})} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z}$$

$$\rho \frac{\mathrm{d}v_y}{\mathrm{d}t} = -\frac{\partial p}{\partial y} + \rho f_y^{(\mathrm{cor})} + \frac{\partial \tau_{yx}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{yz}}{\partial z}$$

$$\rho \frac{\mathrm{d}v_z}{\mathrm{d}t} = -\frac{\partial p}{\partial z} + \rho f_z^{(\mathrm{cor})} - \rho g + \frac{\partial \tau_{zx}}{\partial x} + \frac{\partial \tau_{zy}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z}$$

$$\rho \frac{\mathrm{d}T}{\mathrm{d}t} = \frac{Q^*}{c_v} + \frac{p}{\rho c_v} \frac{\mathrm{d}\rho}{\mathrm{d}t} - \text{уравнение притока тепла} - \frac{1}{\rho} \frac{\mathrm{d}\rho}{\mathrm{d}t} = \frac{1}{\gamma p} \frac{\mathrm{d}p}{\mathrm{d}t} - \frac{\gamma - 1}{\gamma} \frac{Q^*}{p}$$

$$Q^* = -\frac{\partial q}{\partial z} + Q - J^{(*)} l^{(*)} - J^{(m)} l^{(m)}$$

Уравнения состояния совершенного газа

$$p = R \rho T$$
  $u = c_v T + \text{const}$   $c_v = R / (\gamma - 1)$ 

# ДЛЯ ЗАМЫКАНИЯ СИСТЕМЫ УРАВНЕНИЯ НЕОБХОДИМЫ УРАВНЕНИЯ:

- для вертикального теплового потока *q* (турбулентная теплопроводность).
- для выделения тепла из-за поглощения радиации Q, определяемого уравнениями для потоков коротковолновой радиации G, длинноволновой радиации U.
- для интенсивности испарения (конденсации)  $J^{(e)}$ , плавления льда или снега)  $J^{(m)}$ , и тепла  $J^{(e)}l^{(e)} + J^{(m)}l^{(m)}$  фазовых переходов.

## КЛИМАТИЧЕСКИЕ и МЕТЕОРОЛОГИЧЕСКИЕ МАСШТАБЫ

$$au > 10^2 \text{ s}$$
 $V_{\text{hor}} < 30 \text{ m/s}, \ L_{\text{hor}} \sim V_{\text{hor}} \tau > 10^3 \text{ m}$ 
 $V_{\text{ver}} < 3 \text{ m/s}, \ L_{\text{ver}} \sim V_{\text{ver}} \tau > 10^2 \text{ m}$ 

$$au\sim 10^0~{
m s}$$
  $V_{
m hor}\sim 10^2~{
m m/s},~L_{
m hor}\sim 10^2~{
m m},$   $V_{
m ver}\sim 30~{
m m/s},~L_{
m ver}\sim 10^2~{
m m},$ 

ТАЙФУН, ШТОРМ,

# КЛИМАТ, ПОГОДА

$$\frac{\partial v_x}{\partial t} \sim \frac{\partial v_y}{\partial t} \sim \frac{V_{\text{hor}}}{\tau}$$

$$\frac{\partial v_z}{\partial t} \sim \frac{V_{\text{ver}}}{\tau}$$

$$\frac{\partial v_x}{\partial x} \sim \frac{\partial v_x}{\partial y} \sim \frac{\partial v_x}{\partial y} \sim \frac{\partial v_y}{\partial x} \sim \frac{V_{\text{hor}}}{L_{\text{hor}}}$$

$$\frac{\partial v_z}{\partial x} \sim \frac{\partial v_z}{\partial y} \sim \frac{V_{\text{ver}}}{L_{\text{hor}}} \qquad \frac{\partial v_z}{\partial z} \sim \frac{V_{\text{ver}}}{L_{\text{ver}}}$$

$$\overline{t} \equiv \frac{t}{\tau}, \quad \overline{x} \equiv \frac{x}{L_{\text{hor}}}, \quad \overline{y} \equiv \frac{y}{L_{\text{hor}}}, \quad \overline{z} \equiv \frac{z}{L_{\text{ver}}},$$

$$\overline{v}_x \equiv \frac{v_x}{V_{\text{hor}}}, \quad \overline{v}_y \equiv \frac{v_x}{V_{\text{hor}}}, \quad \overline{v}_z \equiv \frac{v_z}{V_{\text{ver}}} = O(1)$$

$$\frac{\mathrm{d} v_x}{\mathrm{d} t} = \frac{V_{\mathrm{hor}}}{\tau} \left( \frac{\partial \overline{v}_x}{\partial \overline{t}} + \overline{v}_x \frac{\partial \overline{v}_x}{\partial \overline{x}} + \overline{v}_y \frac{\partial \overline{v}_x}{\partial \overline{y}} + \overline{v}_z \frac{\partial \overline{v}_x}{\partial \overline{z}} \right) = A_{\mathrm{hor}} \frac{\mathrm{d} \overline{v}_x}{\mathrm{d} \overline{t}} \quad = A_{\mathrm{hor}} \mathsf{O} \big( 1 \big)$$

$$\frac{\mathrm{d} v_y}{\mathrm{d} t} = \frac{V_{\mathrm{hor}}}{\tau} \left( \frac{\partial \overline{v}_y}{\partial \overline{t}} + \overline{v}_x \frac{\partial \overline{v}_y}{\partial \overline{x}} + \overline{v}_y \frac{\partial \overline{v}_y}{\partial \overline{y}} + \overline{v}_z \frac{\partial \overline{v}_y}{\partial \overline{z}} \right) = A_{\mathrm{hor}} \frac{\mathrm{d} \overline{v}_y}{\mathrm{d} \overline{t}} \quad = A_{\mathrm{hor}} \mathrm{O} \big( 1 \big)$$

$$\frac{\mathrm{d} v_z}{\mathrm{d} t} = \frac{V_{\mathrm{ver}}}{\tau} \left( \frac{\partial \overline{v}_z}{\partial \overline{t}} + \overline{v}_x \frac{\partial \overline{v}_z}{\partial \overline{x}} + \overline{v}_y \frac{\partial \overline{v}_z}{\partial \overline{y}} + \overline{v}_z \frac{\partial \overline{v}_z}{\partial \overline{z}} \right) = A_{\mathrm{ver}} \frac{\mathrm{d} \overline{v}_z}{\mathrm{d} \overline{t}} \quad = A_{\mathrm{ver}} O(1)$$

$$\left| -\mathbf{a}^{(\text{cor})} \right| = f^{(\text{cor})} = \left| \mathbf{f}^{(\text{cor})} \right| = \left| 2 \left[ \mathbf{\Omega} \times \mathbf{v} \right] \right| = 2V_{\text{cor}} \Omega \left| \left[ \mathbf{e}_{\text{o}}^{\mathbb{N}} \times \mathbf{v} \right] \right|$$

$$\Omega = \frac{2\pi}{84c} \approx 0,727 \times 10^{-4} \quad ^{-1}2 \qquad A_{\text{cor}} = V_{\text{cor}} \Omega \quad \sim \frac{V_{\text{hor}}}{\tau}$$

## Безразмерные функции

$$\left(\overline{v}_i, \frac{\mathrm{d}\overline{v}_i}{\mathrm{d}\overline{t}}\right) = \mathrm{O}(1)$$

# Масштабы ускорений

$$A_{\rm hor} = \frac{V_{\rm hor}}{\tau} = \frac{V_{\rm hor}^2}{L_{\rm hor}} < 10^{-1} \, {\rm m} \, / \, {\rm c}^2 \, , \qquad A_{\rm ver} = \frac{V_{\rm ver}}{\tau} = \frac{V_{\rm ver}^2}{L_{\rm verr}} < 10^{-2} \, {\rm m} \, / \, {\rm c}^2 \, ,$$

$$A_{
m ver} = rac{V_{
m ver}}{ au} = rac{V_{
m ver}^2}{L_{
m verr}} < 10^{-2} \, {
m m} \, / \, {
m c}^2$$
 ,

$$A_{\rm cor} = 2\Omega V_{\rm hor} < 1,4 \times 10^{-3} \,\mathrm{m} \,/\,\mathrm{c}^2$$

$$\varepsilon = \left(\frac{A_{\text{hor}}}{g}, \frac{A_{\text{ver}}}{g}, \frac{A_{\text{cor}}}{g}\right) < (10^{-2}, 10^{-3}, 10^{-4})$$

$$\varepsilon = \left(\frac{A_{\text{hor}}}{g}, \frac{A_{\text{ver}}}{g}, \frac{A_{\text{cor}}}{g}\right) \longrightarrow 0$$

$$\tau > 10^2 \,\mathrm{s}$$

$$V_{\text{hor}} < 30 \text{ m/s}, \quad L_{\text{hor}} \sim V_{\text{hor}} \tau > 10^3 \text{ m}$$
  
 $V_{\text{ver}} < 3 \text{ m/s}, \quad L_{\text{ver}} \sim V_{\text{ver}} \tau > 10^2 \text{ m}$ 

#### ТАЙФУН, ШТОРМ, БОРА

$$\tau \sim 10^0 \text{ s}$$

$$V_{\rm hor} \sim 10^2 \,{\rm m/s}, \, L_{\rm hor} \sim 10^2 \,{\rm m},$$

$$V_{
m ver} \sim 10^1\,{
m m/s},~~L_{
m ver} \sim 10^2\,{
m m},$$

$$V_{\text{ver}} \sim 10^{1} \,\text{m/s}, \quad L_{\text{ver}} \sim 10^{2} \,\text{m},$$
 $A_{\text{ver}} \sim \frac{V_{\text{ver}}}{\tau} \sim 10^{1} \,\text{m/s}^{2} \sim g, \qquad \frac{A_{\text{ver}}}{g} \sim 10^{0}$ 

$$au > 10^2 \text{ s}$$
  $V_{\text{hor}} < 30 \text{ m/s}, \ L_{\text{hor}} \sim V_{\text{hor}} \tau > 10^3 \text{ m}$   $V_{\text{ver}} < 3 \text{ m/s}, \ L_{\text{ver}} \sim V_{\text{ver}} \tau > 10^2 \text{ m}$ 

$$\tau \sim 10^{-4} \text{ s}, \ \delta \sim 10^{-5} \text{ m}$$

$$V \sim 10^{-1} \, \text{m/s},$$

$$L \sim C \tau \sim 3 \times 10^{-2} \,\mathrm{m}$$

$$m Aкустика 
m$$
  $au \sim 10^{-4} \ s, \ \delta \sim 10^{-5} \ m \ V \sim 10^{-1} \ m/s, \ L \sim C \ \tau \sim 3 \times 10^{-2} \ m, \ A \sim V/\tau \sim 10^3 \ m/s^2 >> g \$ 

#### Аэродинамика

$$V_{
m hor} \sim 10^2 \ 
m m/s, \ \ L_{
m hor} \sim 10^0 \ 
m m, \ V_{
m ver} \sim 10^1 \ 
m m/s$$
  $au \sim L_{
m hor}/V \sim 10^{-2} \ 
m s,$   $A \sim V_{
m ver}/ au \sim 10^3 \ 
m m/s^2 >> \ g$ 

$$\tau \sim L_{\rm hor}/V \sim 10^{-2} \, \mathrm{s}$$

$$A \sim V_{\rm var} / \tau \sim 10^3 \text{ m/s}^2 >> g$$

### УРАВНЕНИЯ МПУЛЬСА

$$\rho \left( \frac{\mathrm{d} v_x}{\mathrm{d} t} + a_x^{(\mathrm{cor})} \right) = -\frac{\partial p}{\partial x}$$

$$\rho \left( \frac{\mathrm{d}v_y}{\mathrm{d}t} + a_y^{(\mathrm{cor})} \right) = -\frac{\partial p}{\partial y}$$

$$\rho \left( \frac{\mathrm{d}v_{z}}{\mathrm{d}t} - a_{z}^{(\mathrm{cor})} \right) = -\frac{\partial p}{\partial z} - \rho g$$

$$\frac{\partial p}{\partial x} = \rho O(A_{\text{hor}} + A_{\text{cor}})$$

$$\frac{\partial p}{\partial y} = \rho O(A_{\text{hor}} + A_{\text{cor}})$$

$$\frac{\partial p}{\partial z} = -\rho g \left( 1 + O(\varepsilon) \right)$$

$$p(t, x, y, z) \underset{\varepsilon \to 0}{\longrightarrow} \int_{z}^{\infty} \rho g \, dz' = g \int_{z}^{H} \rho \, dz' = gM$$

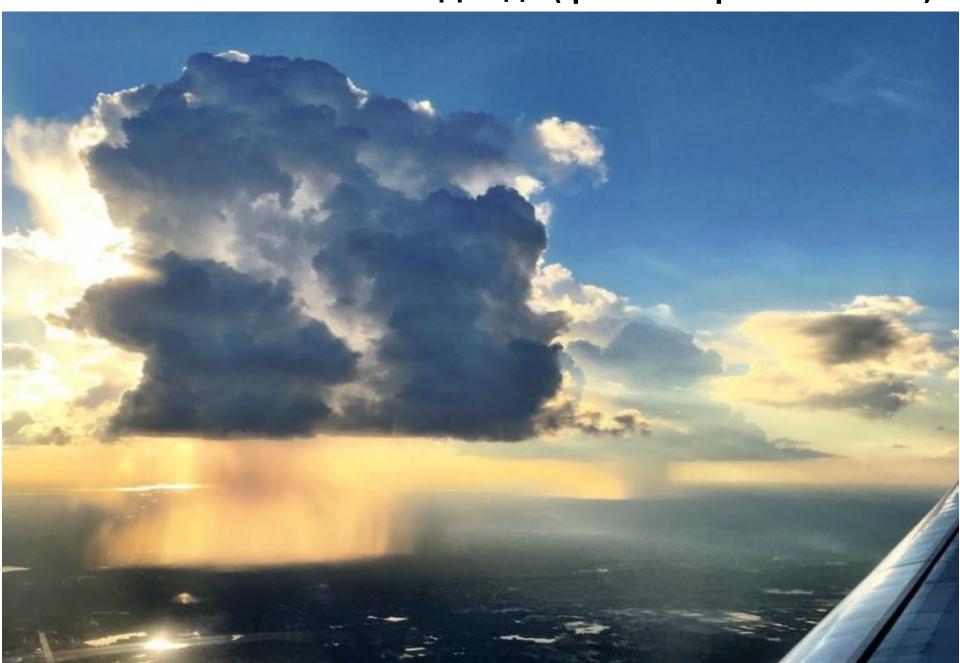
$$\frac{\partial p}{\partial x} \underset{\varepsilon \to 0}{\longrightarrow} g \frac{\partial M}{\partial x} = g \int_{H}^{H} \frac{\partial \rho}{\partial x} dz'$$

$$\frac{\partial p}{\partial y} \underset{\varepsilon \to 0}{\longrightarrow} g \frac{\partial M}{\partial y} = g \int_{z}^{H} \frac{\partial \rho}{\partial y} dz'$$

$$M(t, x, y, z) = \int_{z}^{H} \rho(t, x, y, z') dz'$$

# Как рассчитать вертикальную

# ВЕРТИКАЛЬНЫЕ ПОТОКИ. Дождь (фото с борта самолета)



ВЕРТИКАЛЬНЫЕ ПОТОКИ. Образование грозы (фото с борта самолета на высоте 11 000 м).



#### УРАВНЕНИЕ СОХРАНЕНИЯ МАССЫ

$$\frac{1}{\rho} \frac{\mathrm{d}\rho}{\mathrm{d}t} = \mathrm{div} \mathbf{v} \equiv -\left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}\right)$$

$$\frac{\partial v_z}{\partial z} = -\left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y}\right) + \frac{1}{\rho} \frac{\mathrm{d}\rho}{\mathrm{d}t}$$

Уравнение для распределения вертикальной скорости по вертикали

# **OKEAH:** $\Delta \rho / \rho \sim 10^{-4} - 10^{-3}$

$$\frac{1}{\rho} \frac{\mathrm{d}\rho}{\mathrm{d}t} = \frac{1}{\rho} \left( \frac{\partial \rho}{\partial p} \right)_{S,T} \frac{\mathrm{d}p}{\mathrm{d}t} + \frac{1}{\rho} \left( \frac{\partial \rho}{\partial S} \right)_{p,T} \frac{\mathrm{d}S}{\mathrm{d}t} + \frac{1}{\rho} \left( \frac{\partial \rho}{\partial T} \right)_{S,T} \frac{\mathrm{d}T}{\mathrm{d}t} < \left[ \frac{\partial v_x}{\partial x}, \frac{\partial v_y}{\partial y}, \frac{\partial v_z}{\partial z} \right]$$

$$\frac{\partial v_z}{\partial z} = -\left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y}\right) + \frac{\mathbf{1} \cdot d\rho}{\rho \, dt}.$$

$$\frac{\partial v_z}{\partial z} = - \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y}$$
 - Квазинесжимаемость

Обыкновенное дифференциальное уравнение для распределения вертикальной скорости по вертикали в океане

Хотя океанские течения происходят именно из-за переменности плотности: ho(p, T, S)

# Атмосфера: $\Delta \rho / \rho \sim 10^{\circ}$

$$\frac{1}{\rho} \frac{d\rho}{dt} = \frac{1}{\gamma p} \frac{dp}{dt} - \frac{\gamma - 1}{\gamma p} Q^*$$
 - уравнение притока тепла для совершенного газа
$$\frac{\partial v_x}{\partial v_y} = \frac{\partial v_y}{\partial v_y} = \frac{1}{1} \frac{d\rho}{d\rho}$$

$$\frac{\partial v_z}{\partial z} = -\left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y}\right) - \frac{1}{\rho} \frac{d\rho}{dt}$$

$$\frac{\partial v_z}{\partial z} = -\left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y}\right) - \frac{1}{\gamma p} \frac{\mathrm{d}p}{\mathrm{d}t} + \frac{\gamma - 1}{\gamma p} Q^*$$

$$p(t, x, y, z) = g \int_{z}^{H} \rho dz' = Mg$$

$$\frac{\mathrm{d}p}{\mathrm{d}t} = \frac{\partial p}{\partial t} + v_z \frac{\partial p}{\partial z} + v_x \frac{\partial p}{\partial x} + v_y \frac{\partial p}{\partial y} = -g \int_z^H \left( \frac{\partial (\rho v_x)}{\partial x} + \frac{\partial (\rho v_y)}{\partial y} \right) \mathrm{d}z' + \left( v_x \frac{\partial p}{\partial x} + v_y \frac{\partial p}{\partial y} \right) \frac{\partial v_z}{\partial z} = -\left( \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} \right) - \frac{1}{\gamma p} \frac{\mathrm{d}p}{\mathrm{d}t} + \frac{\gamma - 1}{\gamma p} Q^*$$

$$p = gM = g \int_z^H \rho(t, x, y, z') \mathrm{d}z'$$

$$p = g\mathbf{M} \equiv g \int_{z}^{H} \rho(t, x, y, z') dz'$$

$$\frac{\partial \boldsymbol{v}_{z}}{\partial \boldsymbol{z}} = -\left(\frac{\partial \boldsymbol{v}_{x}}{\partial \boldsymbol{x}} + \frac{\partial \boldsymbol{v}_{y}}{\partial \boldsymbol{y}}\right) - \frac{1}{\gamma} \frac{\dot{\boldsymbol{M}}}{\boldsymbol{M}} + \frac{\gamma - 1}{\gamma} \frac{\boldsymbol{Q}^{*}}{\boldsymbol{g} \boldsymbol{M}}$$

$$\left(M = \int_{z}^{H} \rho(t, x, y, z') dz', \quad \dot{M} \equiv -\int_{z}^{H} \left(\frac{\partial (\rho v_{x})}{\partial x} + \frac{\partial (\rho v_{y})}{\partial y}\right) dz' = \frac{\partial M}{\partial t} - \rho v_{z}\right)$$

$$\frac{\partial M}{\partial z} = -\rho(z), \qquad \frac{\partial \dot{M}}{\partial z} = \left(\frac{\partial(\rho v_x)}{\partial x} + \frac{\partial(\rho v_y)}{\partial y}\right)$$

### Уравнения сохранения для атмосферы с вертикальной квазистатикой (относительно р,

$$\frac{\partial}{\partial t} = -v_x \frac{\partial \rho}{\partial x} - v_y \frac{\partial \rho}{\partial y} - v_z \frac{\partial \rho}{\partial z} + \frac{1}{\gamma} \frac{\rho \dot{M}}{\dot{M}} \frac{x}{\gamma} \frac{\gamma}{g} \frac{1}{y} \rho Q^* \qquad Q^* \equiv -\frac{\partial q}{\partial z} + Q - J l$$

$$\frac{\partial v_x}{\partial t} = -v_x \frac{\partial v_x}{\partial x} - v_y \frac{\partial v_x}{\partial y} - v_z \frac{\partial v_x}{\partial z} - \frac{g}{\rho} \frac{\partial \dot{M}}{\partial x} + f_x^{(cor)} \qquad \frac{\partial \rho}{\partial x} = \frac{\partial \rho}{\partial \rho} \frac{\partial \rho}{\partial x} = C^2 \frac{\partial \rho}{\partial x}$$

$$\frac{\partial v_y}{\partial t} = -v_x \frac{\partial v_y}{\partial x} - v_y \frac{\partial v_y}{\partial y} - v_z \frac{\partial v_y}{\partial z} - \frac{g}{\rho} \frac{\partial \dot{M}}{\partial y} + f_y^{(cor)} \qquad \frac{\partial \rho}{\partial y} = \frac{\partial \rho}{\partial \rho} \frac{\partial \rho}{\partial y} = C^2 \frac{\partial \rho}{\partial y}$$

$$\frac{\partial v_y}{\partial t} = -v_x \frac{\partial v_y}{\partial x} - v_y \frac{\partial v_y}{\partial y} - v_z \frac{\partial v_y}{\partial z} - \frac{g}{\rho} \frac{\partial M}{\partial y} + f_y^{\text{(cor)}}$$

$$Q^* \equiv -\frac{\partial q}{\partial z} + Q - J l$$

$$\frac{\partial p}{\partial x} = \frac{\partial p}{\partial \rho} \frac{\partial \rho}{\partial x} = C^2 \frac{\partial \rho}{\partial x}$$

$$\frac{\partial p}{\partial y} = \frac{\partial p}{\partial \rho} \frac{\partial \rho}{\partial y} = C^2 \frac{\partial \rho}{\partial y}$$

$$\frac{\partial \mathbf{M}}{\partial z} = -\rho$$

$$\frac{\partial \dot{\mathbf{M}}}{\partial z} = -\frac{\partial(\rho v_x)}{\partial x} - \frac{\partial(\rho v_y)}{\partial y}$$

$$\frac{\partial v_z}{\partial z} = -\left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y}\right) - \frac{1}{\gamma} \frac{\dot{\mathbf{M}}}{\mathbf{M}} + \frac{\gamma - 1}{\gamma} \frac{Q^*}{g M}$$

$$\frac{\partial v_z}{\partial z} = -\left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y}\right) - \frac{1}{\gamma} \frac{\dot{M}}{M} + \frac{\gamma - 1}{\gamma} \frac{Q^*}{gM}$$

$$p = gM, \qquad T = \frac{g}{R} \frac{M}{\rho} \qquad \left( M = \int_{z}^{H} \rho(t, x, y, z') \, \mathrm{d}z', \qquad \dot{M} = -\int_{z}^{H} \left( \frac{\partial (\rho v_{x})}{\partial x} + \frac{\partial (\rho v_{y})}{\partial y} \right) \mathrm{d}z' \right)$$

$$oldsymbol{arepsilon} oldsymbol{arepsilon} = egin{pmatrix} A_{
m ver} = A_{
m ver} \\ g \end{pmatrix}, \quad eta_{
m hor} = A_{
m hor} \\ g \end{pmatrix}, \quad eta_{
m cor} = A_{
m cor} \\ g \end{pmatrix}, \quad eta_{
m C} = oldsymbol{M}^2$$

$$\left(A_{\text{ver}} = \frac{V_{\text{ver}}}{\tau} + \frac{V_{\text{ver}}^2}{L_{\text{ver}}}, \quad A_{\text{hor}} = \frac{V_{\text{hor}}}{\tau} + \frac{V_{\text{hor}}^2}{L_{\text{hor}}}, \quad A_{\text{cor}} = \frac{V_{\text{hor}}}{\tau}, \quad \mathbf{M}^2 = \frac{V_{\text{ver}}^2}{C^2}\right)$$

**Теорема.** Уравнения (⊗) асимптотически точные уравнения

$$\epsilon_{\text{ver}} \to 0, \quad \epsilon_{\text{hor}} \to 0, \quad \epsilon_{\text{cor}} \to 0, \quad \epsilon_C \to 0$$

$$\varepsilon_{\rm hor} \to 0$$
,

$$\varepsilon_{\rm cor} \to 0$$

$$\varepsilon_C \to 0$$

$$\frac{\partial \mathbf{v}_{z}}{\partial \mathbf{z}} = -\left(\frac{\partial \mathbf{v}_{x}}{\partial \mathbf{x}} + \frac{\partial \mathbf{v}_{y}}{\partial \mathbf{y}}\right) - \frac{1}{\gamma} \frac{\dot{\mathbf{M}}}{\mathbf{M}} + \frac{\gamma - 1}{\gamma} \frac{\mathbf{Q}^{*}}{\mathbf{g} \mathbf{M}} + \frac{1}{\gamma p} \left(\frac{\mathbf{v}_{x}}{\mathbf{p}} \frac{\partial \mathbf{p}}{\partial \mathbf{x}} + \mathbf{v}_{y} \frac{\partial \mathbf{p}}{\partial \mathbf{y}}\right) \right\}$$

#### **Edward Lorenz (1967)**

$$+\left\{\frac{1}{\gamma p}\left(v_{x}\frac{\partial p}{\partial x}+v_{y}\frac{\partial p}{\partial y}\right)\right\}$$

$$O(\mathbf{M}^{2})=O(\varepsilon)$$

$$O(M^2) = O(\varepsilon)$$

$$\frac{\partial \boldsymbol{v}_{z}}{\partial \boldsymbol{z}} = -\left(\frac{\partial \boldsymbol{v}_{x}}{\partial \boldsymbol{x}} + \frac{\partial \boldsymbol{v}_{y}}{\partial \boldsymbol{y}}\right) - \frac{1}{\gamma} \frac{\dot{\boldsymbol{M}}}{\boldsymbol{M}} + \frac{\gamma - 1}{\gamma} \frac{\boldsymbol{Q}^{*}}{\boldsymbol{g} \boldsymbol{M}}\right) + \left\{\frac{1}{\gamma p} \left(\boldsymbol{v}_{x} \frac{\partial p}{\partial x} + \boldsymbol{v}_{y} \frac{\partial p}{\partial y}\right)\right\}$$

+ 
$$\left\{ \frac{1}{\gamma p} \left( v_x \frac{\partial p}{\partial x} + v_y \frac{\partial p}{\partial y} \right) \right\}_{y}$$

$$\frac{\left\{v_{x}\left(\frac{\partial p}{\partial x}\right)+v_{y}\left(\frac{\partial p}{\partial y}\right)\right\}\frac{1}{\gamma p}}{\dot{M}/\gamma}=$$

$$\frac{1}{\gamma p} \left( v_x \frac{\partial p}{\partial x}, v_y \frac{\partial p}{\partial y} \right) = \frac{V_{\text{hor}}}{\gamma p} \times \rho O \left( \frac{V_{\text{hor}}}{\tau} + \frac{V_{\text{hor}}^2}{L_{\text{hor}}} + \frac{V_{\text{cor}}^2}{L_{\text{cor}}} \right) = \frac{V_{\text{hor}} \rho}{\gamma p} O \left( A_{\text{hor}} + A_{\text{cor}} \right)$$

$$\frac{\dot{M}}{\gamma M} = \frac{\int_{z}^{H} \left(\frac{\partial(\rho v_{x})}{\partial x} + \frac{\partial(\rho v_{y})}{\partial y}\right) dz'}{\int_{\gamma}^{H} \rho(t, x, y, z') dz'} \sim \frac{\hat{\rho} V_{\text{hor}}(H - z)}{\frac{\hat{\rho} V_{\text{hor}}(H - z)}{\hat{\gamma} \rho(H - z)}} = O\left(\frac{V_{\text{hor}}}{L_{\text{hor}}}\right)$$

$$\frac{\left\{ v_{x} \left( \frac{\partial p}{\partial x} \right) + v_{y} \left( \frac{\partial p}{\partial y} \right) \right\} \frac{1}{\gamma p}}{\left( \frac{\partial p}{\partial x} \right) + v_{y} \left( \frac{\partial p}{\partial y} \right) \right\} \frac{1}{\gamma p}} = \frac{\rho V_{\text{hor}}}{\gamma p} \times O\left( \frac{V_{\text{hor}}}{\tau} + \frac{V_{\text{hor}}^{2}}{L_{\text{hor}}} + \frac{V_{\text{hor}}^{2}}{L_{\text{cor}}} \right)}{O\left( \frac{V_{\text{hor}}}{L_{\text{hor}}} \right)} = \frac{\rho V_{\text{hor}}}{\gamma p} \times O\left( \frac{V_{\text{hor}}}{\tau} + \frac{V_{\text{hor}}^{2}}{L_{\text{hor}}} + \frac{V_{\text{hor}}^{2}}{L_{\text{hor}}} + \frac{V_{\text{hor}}^{2}}{L_{\text{hor}}} \right)}{O\left( \frac{V_{\text{hor}}}{L_{\text{hor}}} \right)} = \frac{\rho V_{\text{hor}}}{\rho p} \times O\left( \frac{V_{\text{hor}}}{\tau} + \frac{V_{\text{hor}}^{2}}{L_{\text{hor}}} + \frac{V_{\text{hor}}^{2}}{L_{\text{hor}}} + \frac{V_{\text{hor}}^{2}}{L_{\text{hor}}} \right)$$

$$\frac{\rho V_{\text{hor}}}{\gamma p} \times O\left(\frac{V_{\text{hor}}}{\tau} + \frac{V_{\text{hor}}^2}{L_{\text{hor}}} + \frac{V_{\text{hor}}^2}{L_{\text{cor}}}\right) = O\left(\frac{V_{\text{hor}}}{L_{\text{hor}}}\right)$$

$$= \frac{L_{\text{hor}}}{C^2} O \left( \frac{V_{\text{hor}}^2}{L_{\text{hor}}} + \frac{V_{\text{hor}}^2}{L_{\text{cor}}} \right) = \frac{V_{\text{hor}}^2}{C^2} O \left( \frac{L_{\text{hor}}}{V_{\text{hor}} \tau} + 1 + \frac{L_{\text{hor}}}{\tau_{\text{cor}}} \right) = O \left( 2 + \frac{L_{\text{hor}}}{L_{\text{cor}}} \right) O \left( \mathbf{M}^2 \right)$$

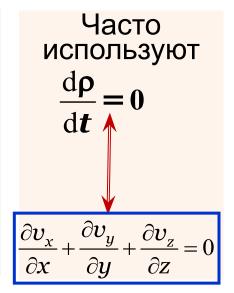
$$\left(\mathbf{M} = \frac{V_{\text{hor}}}{C} \mathbf{M} \quad \mathbf{c} \ C = \left(\frac{\gamma p}{\rho}\right)^{\frac{1}{2}} = 300 - 350 \quad / \quad \right)$$

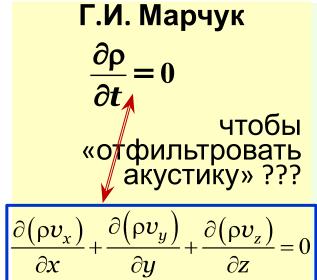
$$\mathbf{M}^{2} = \frac{V_{\text{hor}}^{2}}{C^{2}} = \frac{L_{\text{hor}}g}{C^{2}} \times \left(\frac{V_{\text{hor}}^{2}}{gL_{\text{hor}}}\right) = \frac{L_{\text{hor}}g}{C^{2}} \times \varepsilon$$

$$\frac{\mathrm{d}p}{\mathrm{d}t} = -g \int_{z}^{H} \left( \frac{\partial (\rho v_{x})}{\partial x} + \frac{\partial (\rho v_{y})}{\partial y} \right) \mathrm{d}z'$$

Часто использую т

$$v_z = 0$$





Учебник Дж. Холтона 
$$\frac{\partial \boldsymbol{p}}{\partial t} = 0$$
 
$$\frac{\mathrm{d}\boldsymbol{p}}{\mathrm{d}t} = -g\rho v_z$$

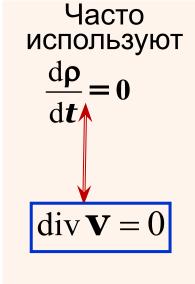
$$\frac{\mathrm{d}p}{\mathrm{d}t} = -g \int_{z}^{H} \left( \frac{\partial (\rho v_{x})}{\partial x} + \frac{\partial (\rho v_{y})}{\partial y} \right) \mathrm{d}z'$$

$$\frac{\partial \boldsymbol{v}_{z}}{\partial z} = -\left(\frac{\partial \boldsymbol{v}_{x}}{\partial x} + \frac{\partial \boldsymbol{v}_{y}}{\partial y}\right) - \frac{1}{\gamma} \frac{\dot{\boldsymbol{M}}}{\boldsymbol{M}} + \frac{\gamma - 1}{\gamma} \frac{\boldsymbol{Q}^{*}}{\boldsymbol{g} \boldsymbol{M}}$$

Часто использую т

$$v_z = 0$$

$$v_z = 0$$



 $\partial v_x$ 

 $\partial x$ 

 $\partial v_{\underline{z}}$ 

 $\partial Z$ 

 $\partial v_y$ 

 $\partial y$ 

Г.И. Марчук

$$\frac{\partial \rho}{\partial t} = 0$$
чтобы чтобы «отфильтровать акустику» ???

$$\operatorname{div}(\rho \mathbf{V}) = 0$$

$$\frac{\partial (\rho v_z)}{\partial z} = -\frac{\partial (\rho v_x)}{\partial x} - \frac{\partial (\rho v_y)}{\partial y}$$

Дж. Холтон (учебник) 
$$\frac{\partial \boldsymbol{p}}{\partial t} = 0$$
 
$$\frac{\mathrm{d}\boldsymbol{p}}{\mathrm{d}t} = -g\rho v_z$$

$$\rho v_z = \int_z^H \left( \frac{\partial (\rho v_x)}{\partial x} + \frac{\partial (\rho v_y)}{\partial y} \right) dz'$$

# Схема распределения параметров в тропосфере над межфазной поверхностью



$$\mathbf{B}_{t} \frac{\partial \overline{\mathbf{U}}}{\partial \overline{t}} + \mathbf{B}_{x} \frac{\partial \overline{\mathbf{U}}}{\partial \overline{x}} + \mathbf{B}_{y} \frac{\partial \overline{\mathbf{U}}}{\partial \overline{y}} + \mathbf{B}_{z} \frac{\partial \overline{\mathbf{U}}}{\partial \overline{z}} + \mathbf{B} = 0,$$

$$\mathbf{\bar{U}} = \mathbf{\bar{v}}_{x} \mathbf{\bar{v}$$

$$\mathbf{B} = \begin{pmatrix} \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{v}_x \tau f \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \vdots \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \vdots \ddot{\exists} \\ \overline{Q}\gamma = \overline{M} \end{pmatrix} = \begin{pmatrix} \overline{Q}\gamma - \overline{M} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists} \\ \overline{Q}\gamma - \overline{M} \end{pmatrix} / (\gamma \overline{M}) \ddot{\exists}$$

$$\mathbf{B}_{z} = \begin{pmatrix} \overline{v}_{z} & 0 & 0 & 0 & 0 & 0 \\ 0 & \overline{v}_{z} & 0 & 0 & 0 & 0 \\ 0 & 0 & \overline{v}_{z} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\mathbf{B}_{x} = \begin{pmatrix} \overline{v}_{y} & 0 & 0 & 0 & 0 & 0 \\ 0 & \overline{v}_{y} & 0 & 0 & 0 & 0 \\ 0 & 0 & \overline{v}_{y} & 0 & 0 & \overline{g} / \overline{\rho} \\ 0 & 0 & 1 & 0 & 0 & 0 \\ -\overline{v}_{y} & 0 & -\overline{\rho} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$B_{11} = \frac{\overline{Q}}{\overline{M}} - \frac{\overline{M}}{\gamma \overline{M}}, \qquad B_{21} = \frac{1}{\overline{\rho}} \left( \frac{\mathrm{d}\overline{v}_x}{\mathrm{d}\overline{t}} - \overline{v}_y \tau f \right), \qquad B_{31} = \frac{1}{\overline{\rho}} \left( \frac{\mathrm{d}\overline{v}_y}{\mathrm{d}\overline{t}} + \overline{v}_x \tau f \right),$$

1. В дифференциальном операторе системы уравнений квазистатического по вертикали движения нет скорости звука C, даже в уравнениях горизонтального движения,

**т.е. уже «акустика отфильтрована»** (выражение Г.И. Марчука).

2. Система уравнений только с вертикальной квазистатичностью негиперболична  $(C o \infty)$  даже при отсутствии теплопроводности, т.е. при отсутствии параб  $\partial \left(\lambda \frac{\partial T}{\partial L}\right)$  члена

Некоторое решение

$$\bar{\mathbf{U}} = \bar{\mathbf{U}}(\bar{t}, \bar{x}, \bar{y}, \bar{z})$$

Другое решение, отличающееся 🗗 малым возмущением

$$\overline{\mathbf{U}}^{(d)} = \overline{\mathbf{U}} + \overline{\mathbf{U}}$$
  $(|\overline{\mathbf{U}}|: 1, |\overline{\mathbf{U}}$   $(|\overline{\mathbf{U}}|: 1, |\overline{\mathbf{U}}$ 

$$\mathbf{B}_{t} \frac{\partial \overline{\mathbf{U}'}}{\partial \overline{t}} + \mathbf{B}_{x} \frac{\partial \overline{\mathbf{U}'}}{\partial \overline{x}} + \mathbf{B}_{y} \frac{\partial \overline{\mathbf{U}'}}{\partial \overline{y}} + \mathbf{B}_{z} \frac{\partial \overline{\mathbf{U}'}}{\partial \overline{z}} + \mathbf{B'} \overline{\mathbf{U}'} = \mathbf{F'}$$

$$\mathbf{\bar{U}} = \mathbf{\bar{Q}} \mathbf{\dot{\varphi}} / \mathbf{\bar{M}} \mathbf{\ddot{Q}} \mathbf{\dot{\varphi}} \mathbf{\dot{\varphi}}$$

Исходное гармоническое возмущение

Коротковолновые возмущения с Q' = 0:

#### Коротковолновые возмущения

#### 

 $\mathbf{B}_{t}, \mathbf{B}_{x}, \mathbf{B}_{y}, \mathbf{B}_{z}, \mathbf{B}$  const,  $\mathbf{F} = 0$ 

$$\overline{v}_{\mathcal{X}}^{\varsigma} = A_{*}^{(vx)} E_{*}, \quad \overline{v}_{\mathcal{Y}}^{\varsigma} = A_{*}^{(vy)} E_{*}, \quad \overline{v}_{\mathcal{Z}}^{\varsigma} = A_{*}^{(vz)} E_{*}$$

$$\overline{\rho} = A_{*}^{(\rho)} E_{*}, \quad \overline{M}^{\varsigma} = A_{*}^{(M)} E_{*}, \quad \overline{M}^{\varsigma} = A_{*}^{(M)} E_{*}$$

$$E_{\star} = \exp\left(i\left(\overline{k}_{x}\overline{x} + \overline{k}_{y}\overline{y} + \overline{k}_{z}\overline{z} - \overline{\omega}_{\star}\overline{t}\right)\right) = \exp\left(\overline{\omega}_{\star\star}\overline{t}\right) \times \exp\left(i\left(\overline{k}_{x}\overline{x} + \overline{k}_{y}\overline{y} + \overline{k}_{z}\overline{z} - \overline{\omega}\overline{t}\right)\right),$$

$$\overline{\omega}_{\star} = \overline{\omega} + i\overline{\omega}_{\star\star}, \quad \overline{\omega}_{\star} = \omega_{\star} \times \tau$$

 $\overline{\omega}_{**}$  > 0 - неустойчивость (коротковолновая) решения  $\overline{\mathrm{U}}(\overline{t},\overline{x},\overline{y},\overline{z})$ 

 $\overline{\omega}_{**}$   $\overset{\mathbb{B}}{\bar{k}^{\$}}$  +  $\overset{\mathsf{+}}{\mathsf{+}}$  абсолютная неустойчивость решения  $\overline{\mathsf{U}}(\overline{t},\overline{x},\overline{y},\overline{z})$  некорректно поставленная задача

$$\mathbf{D}\mathbf{A}_{\star} = 0, \qquad \mathbf{A}_{\star} = \left(A_{\star}^{(\rho)}, A_{\star}^{(vx)}, A_{\star}^{(vy)}, A_{\star}^{(vz)}, A_{\star}^{(NT)}, A_{\star}^{(MT)}\right)^{\mathrm{T}}.$$

$$\mathbf{D} = i\left(-\overline{\omega}_{*}\mathbf{B}_{t} + \overline{k}_{x}\mathbf{B}_{x} + \overline{k}_{y}\mathbf{B}_{y} + \overline{k}_{z}\mathbf{B}_{z}\right) + \mathbf{B}'$$

 $\det \mathbf{D} = 0$ 

$$\overline{\omega}_*^3 + b\overline{\omega}_*^2 + c\overline{\omega}_* + d = 0$$

b,c,d — определяется значениями компонент  ${f U},$ 

а именно 
$$\overline{\rho}, \overline{v}_x, \overline{v}_y, \overline{v}_z, \frac{\partial \overline{v}_x}{\partial x}, \frac{\partial \overline{v}_y}{\partial x}, \dots$$

#### Устойчивость покоя

$$\overline{v}_x = \overline{v}_y = \overline{v}_z = 0, \quad \frac{\partial \overline{\rho}}{\partial \overline{x}} = \frac{\partial \overline{\rho}}{\partial \overline{u}} = 0, \quad \overline{M} = 0, \quad \overline{Q} = 0$$

$$\frac{\partial \overline{v}_x}{\partial \overline{t}} = \frac{\partial \overline{v}_y}{\partial \overline{t}} = 0, \quad \frac{\partial \overline{v}_x}{\partial \overline{x}} = \frac{\partial \overline{v}_x}{\partial \overline{y}} = \frac{\partial \overline{v}_x}{\partial \overline{z}} = \frac{\partial \overline{v}_y}{\partial \overline{z}} = 0,$$

fewarrangeтандартная а тмосфера  $\rho(z)$ ,  $\frac{\partial \overline{\rho}}{\partial \overline{z}}$  и  $\frac{\rho}{p}$ 

$$\overline{\omega}_* \left[ \overline{\omega}_*^2 - \left( (\overline{N}^2 - \overline{G}^2) \frac{\overline{k}_{\text{hor}}^2}{\overline{k}_{\text{ver}}^2} + \overline{f}^2 - \frac{\overline{N}^2 \overline{G}^2}{\overline{g}} \frac{\overline{k}_{\text{hor}}^2}{\overline{k}_{\text{ver}}^3} \cdot i \right) \right] = 0,$$

$$ar{N}^2 = -rac{\overline{g}}{\overline{
ho}} rac{\partial \overline{
ho}}{\partial \overline{z}} = \left(rac{L_{
m ver} au}{L_{
m hor}}
ight)^2 N^2 \qquad \qquad \left(N^2 = -rac{g}{
ho} rac{\partial 
ho}{\partial z}
ight),$$

$$ar{G}^2 = rac{\overline{
ho}\overline{g}}{\gamma \overline{M}} = \left(rac{L_{
m ver} au}{L_{
m hor}}g
ight)^2 rac{
ho}{\gamma p} \qquad \qquad \left(G^2 = \left(rac{g}{C}
ight)^2 = rac{g^2
ho}{\gamma p}
ight),$$

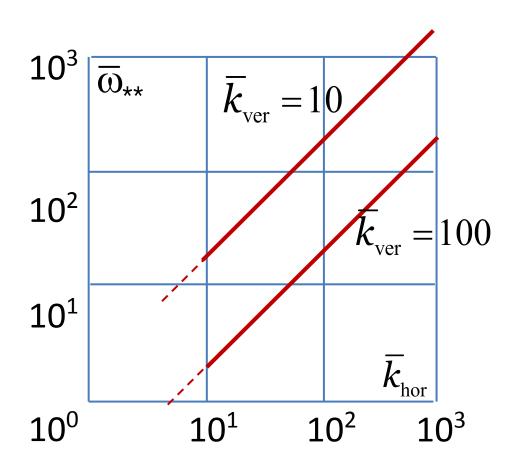
$$\overline{\omega}_* \left[ \overline{\omega}_*^2 - \left( (\overline{N}^2 - \overline{G}^2) \frac{\overline{k}_{\text{hor}}^2}{\overline{k}_{\text{ver}}^2} + \overline{f}^2 - \frac{\overline{N}^2 \overline{G}^2}{\overline{g}} \frac{\overline{k}_{\text{hor}}^2}{\overline{k}_{\text{ver}}^3} \cdot i \right) \right] = 0,$$

$$ar{f} \ll \sqrt{ar{N}^2 - ar{G}^2} rac{ar{k}_{ ext{hor}}}{ar{k}_{ ext{ver}}}, \quad ar{oldsymbol{\omega}}_{**}^{(2,3)} = \pm A_1 \kappa_1 \mathop{\sim}_{\kappa_1 o \infty} \pm \infty, \ ar{f} ? \sqrt{ar{N}^2 - ar{G}^2} rac{ar{k}_{ ext{hor}}}{ar{k}_{ ext{ver}}}, \quad ar{oldsymbol{\omega}}_{**}^{(2,3)} = \pm A_2 \kappa_2 \mathop{\sim}_{\kappa_2 o \infty} \pm \infty,$$

$$\mathbf{E}_{\mathbf{k}_{1}}^{\mathbf{E}} = \frac{\overline{k}_{\text{hor}}}{\overline{k}_{\text{ver}}^{2}} \mathbf{E}_{\mathbf{k}_{2}}^{\mathbf{E}}$$

$$\mathbf{E}_{\mathbf{k}_{2}}^{\mathbf{E}} = \frac{\overline{k}_{\text{hor}}^{2}}{\overline{k}^{3}} \mathbf{E}_{\mathbf{k}_{3}}^{\mathbf{E}}$$

## Устойчивость покоя

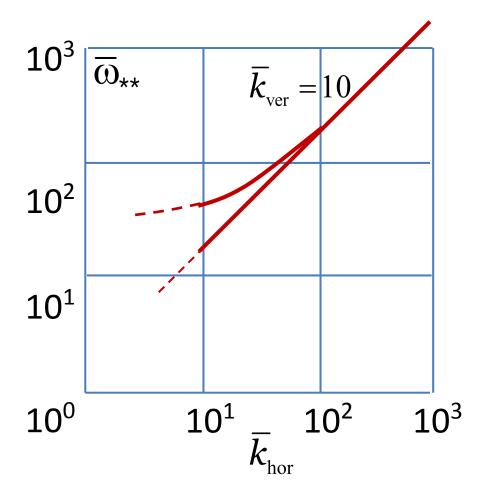


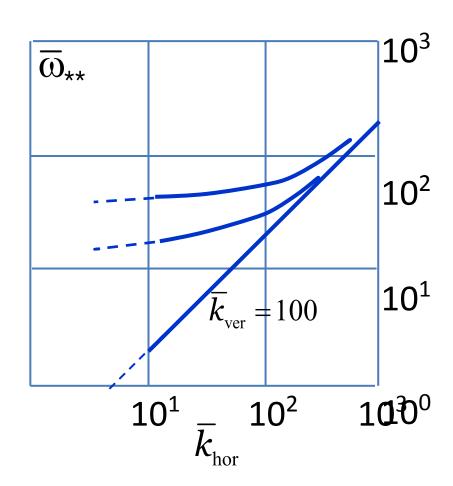
$$\overline{k}_{\text{ver}} = 10$$

$$\overline{k}_{\text{ver}} = 40$$

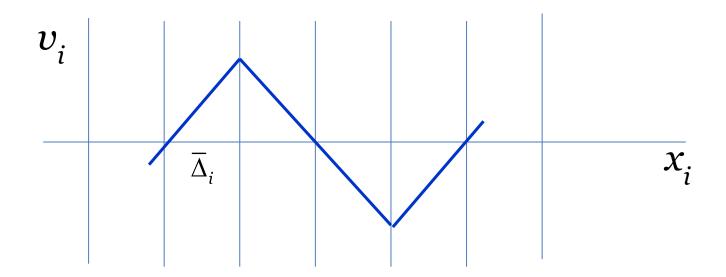
$$\overline{k}_{\text{ver}} = 100$$

$$\frac{\partial \overline{v}_y}{\partial \overline{x}} = \frac{\partial \overline{v}_x}{\partial \overline{y}} = 0.5, \quad \frac{\partial \overline{v}_x}{\partial \overline{x}} = \frac{\partial \overline{v}_y}{\partial \overline{y}} = -0.5,$$





#### РАЗНОСТНАЯ СЕТКА



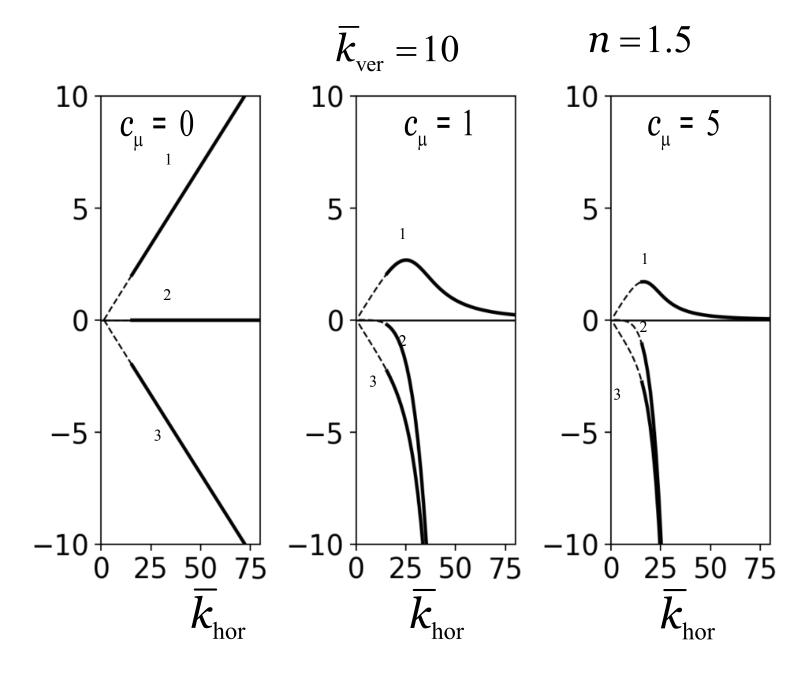
$$\overline{l}_i^{\, ext{min}} = 4\overline{\Delta}_i, \qquad \overline{k}_i^{\, ext{max}} \overline{l}_i^{\, ext{min}} = 2\pi, \qquad \overline{k}_i^{\, ext{max}} = k_i^{\, ext{max}} L_i = \frac{1}{2}\pi N_i$$
 
$$\left(\overline{\Delta}_i = \Delta \overline{x}, \Delta \overline{y}, \Delta \overline{z}, \qquad N_i = \frac{L_i}{\Delta_i}, \qquad i = x, y, z\right),$$

$$k_i < \overline{k}_i^{\text{max}} = \frac{1}{2} \pi N_i$$

#### ИСКУССТВЕННАЯ ВЯЗКОСТЬ

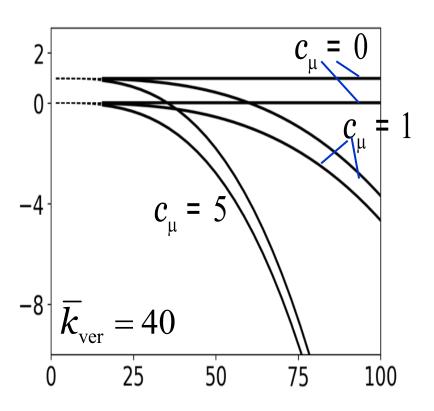
$$\overline{\mu} = c_{\mu}\overline{\mu}_{a}\left(\overline{k}_{x}\overline{k}_{y}\overline{k}_{z}\right)^{n}, \qquad \overline{\lambda} = c_{\lambda}\overline{\mu}_{a}\left(\overline{k}_{x}\overline{k}_{y}\overline{k}_{z}\right)^{m},$$

$$\overline{\mu}_{a} = \frac{\mu_{a}}{\rho V_{\text{ver}} L_{\text{ver}}} \qquad (\pi \mu_{a} + M.8) 1.0^{-5} / \cdot$$



$$\overline{\omega}_* \left( \overline{\omega}_*^2 + b_1(\overline{\mu}) \overline{\omega}_* + c_1(\overline{\mu}) \right) = 0$$

$$\overline{\omega}_* \Big( \overline{\omega}_*^2 + b_1(\overline{\mu}) \overline{\omega}_* + c_1(\overline{\mu}) \Big) = 0$$
  $\left( \frac{\partial \rho}{\partial t} = 0 - \text{приближение Марчука} \right)$ 



$$c_{\mu} = 0$$

$$c_{\mu} = 1$$

$$c_{\mu} = 5$$

$$\overline{k}_{\text{ver}} = 100$$

$$0 \quad 25 \quad 50 \quad 75 \quad 100$$

$$\overline{v}_x = \overline{v}_y = \overline{v}_z = 1, \quad \overline{Q} = 0,$$

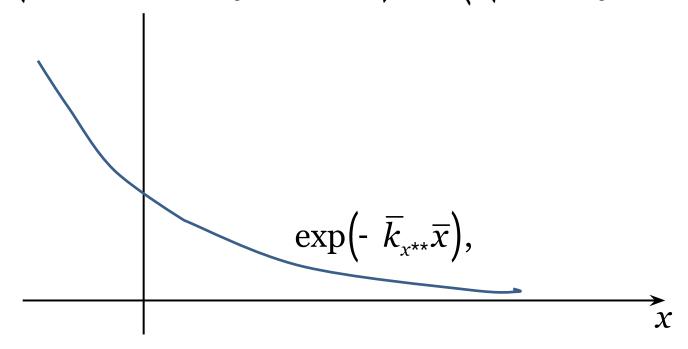
$$\frac{\partial \overline{v}_x}{\partial \overline{z}} = \frac{\partial \overline{v}_y}{\partial \overline{z}} = \frac{\partial \overline{v}_z}{\partial \overline{z}} = 0, \quad \frac{\partial \overline{\rho}}{\partial \overline{x}} = \frac{\partial \overline{\rho}}{\partial \overline{y}} = 0,$$

$$\frac{\partial \overline{v}_y}{\partial \overline{x}} = \frac{\partial \overline{v}_x}{\partial \overline{y}} = 0.5, \quad \frac{\partial \overline{v}_x}{\partial \overline{x}} = \frac{\partial \overline{v}_y}{\partial \overline{y}} = -0.5,$$

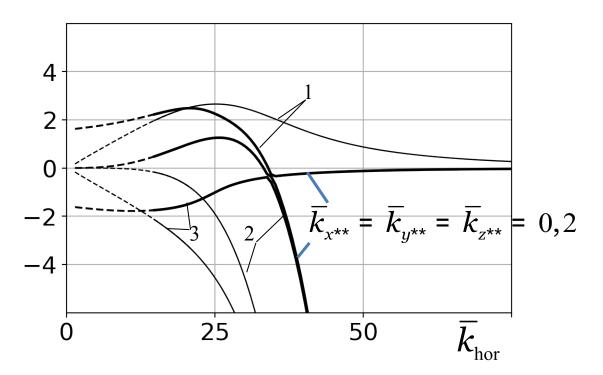
Локальное возмущение для x, y, z > 0

$$\overline{k}_{j*} = \overline{k}_j + i\overline{k}_{j**} \quad (j = x, y, z)$$

$$\begin{split} \boldsymbol{E}_{\star} &= \exp \left( i \left( \overline{k}_{x^{\star}} \overline{x} + \overline{k}_{y^{\star}} \overline{y} + \overline{k}_{z^{\star}} \overline{z} - \overline{\omega}_{\star} \overline{t} \right) \right) = \\ &= \exp \left( \overline{\omega}_{\star \star} \overline{t} - \overline{k}_{x^{\star \star}} \overline{x} - \overline{k}_{y^{\star \star}} \overline{y} - \overline{k}_{z^{\star \star}} \overline{z} \right) \times \exp \left( i \left( \overline{k}_{x} \overline{x} + \overline{k}_{y} \overline{y} + \overline{k}_{z} \overline{z} - \overline{\omega} \overline{t} \right) \right), \end{split}$$



$$\overline{k}_{\text{ver}} = 10, n = 1.5, c_{\mu} = 1$$



(ruse) = 
$$\overline{k}_{hor}^2 / \overline{k}_{ver}^3$$
? 1),  $\overline{\Delta}_{ver}^3 / \overline{\Delta}_{hor}^2$  =

$$\frac{\mathrm{d}p}{\mathrm{d}t} = -g\int_{z}^{H} \left(\frac{\partial(\rho v_{x})}{\partial x} + \frac{\partial(\rho v_{y})}{\partial y}\right) \mathrm{d}z'$$

$$\frac{\partial v_{z}}{\partial z} = -\left(\frac{\partial v_{x}}{\partial x} + \frac{\partial v_{y}}{\partial y}\right) - \frac{1}{\gamma}\frac{M}{M} + \frac{\gamma - 1}{\gamma}\frac{Q^{*}}{gM}$$
Часто использую 
$$\frac{\mathrm{d}\rho}{\mathrm{d}t} = 0$$

$$v_{z} = 0$$

$$\frac{\mathrm{d}\rho}{\mathrm{d}t} = 0$$

$$\frac{\partial\rho}{\partial t} = 0$$

 $\overline{\mathbf{\omega}}^{**} = 0$ 

 $\overline{\mathbf{\omega}}_{*}^{2} = -\frac{\overline{g}}{\overline{\rho}} \frac{\partial \overline{\rho}}{\partial \overline{z}} \frac{\overline{k}_{\text{hor}}^{2}}{\overline{k}_{\text{ver}}^{2}}$ 

 $\overline{\mathbf{\omega}}_{**} = 0$ , if  $\frac{\partial \overline{\rho}}{\partial \overline{z}} < 0$ 

 $\overline{\mathbf{Q}}_{**} \underset{\overline{k}_{hor} \to \infty}{\longrightarrow} \infty$ , if  $\frac{\partial \overline{\rho}}{\partial \overline{z}} > 0$ 

 $ar{\mathbb{B}} \ \overline{G} rac{\overline{k}_{ ext{hor}}}{\overline{k}_{ ext{ver}}} ar{\mathbb{B}} \ oldsymbol{f Y}$ 

Дж. Холтона  $\frac{\partial \boldsymbol{p}}{\partial t} = 0$   $\rho v_z = -\dot{M} \equiv$   $\int_{\mathcal{A}} \left( \frac{\partial (\rho v_x)}{\partial x} + \frac{\partial (\rho v_y)}{\partial y} \right) \mathrm{d}x$ 

 $ar{m{\omega}}_{*}^{2} = -\,rac{\overline{g}}{\overline{
ho}}\,rac{\partial\overline{
ho}}{\partial\overline{z}}rac{k_{
m hor}^{2}}{\overline{k}_{
m ver}^{2}},$ 

 $\overline{\mathbf{\omega}}_{**} = 0$ , if  $\frac{\partial \overline{\rho}}{\partial \overline{z}} < 0$ ,

 $\overline{\mathbf{\omega}}_{**} \underset{\overline{k}_{hor} \to \infty}{\longrightarrow} \infty$ , if  $\frac{\partial \overline{\rho}}{\partial \overline{z}} > 0$ 

Учебник

 $\left(\frac{\mathrm{d}p}{\mathrm{d}t} = -g\rho v_z\right)$ 

# Негиперболичность приводит к некорректной (ill posed)

поста-новке задачи Коши при отсутствии диссипации, при которой

коротковолновые возмущения 
$$\delta W_k \big|_{t=0} = A(k) \big\lceil \sin(kx) \big\rceil$$
 при  $k o \infty$ 

#### растут неограниченно быстро:

$$\delta W = A(k) \times \exp(\omega_{**}(k)t) [\sin(kx)], \qquad \omega_{**}(k) \underset{k \to \infty}{\longrightarrow} \infty$$

$$L_* = \frac{p_0}{\rho_0 g} \sim H \sim 10^4$$
 - линейный размер, следующий из дифференциального оператора и начальных условий  $k_* \approx \frac{2\pi}{L_*} = \frac{2\pi\rho_0 g}{p_0}$  - характерное волновое число метеорологического процесса Конечно-разностная схема **Генерирует «Паразитные»**

Конечно-разностная схема **генерирует «паразитные»** коротковолновые возмущения с длинами волн  $l > 4\Delta x$  и волновым

$$k_x \approx \frac{2\pi}{l_x} \text{ и } k_z \approx \frac{2\pi}{l_z}$$
 если  $k \approx \left(\frac{2\pi}{4\Delta z} \right) >> k_* = \frac{2\pi\rho_0 g}{p_0}, \text{ то } \omega_{**}\tau >> 1, \exp\left(\omega_{**}(k)\tau\right) >> 1$ 

#### Необходим фильтр (численная диссипация) для возмущений

**ТИПа** 
$$A(k) imes \sin(kx)$$
 при  $k \Delta x > 1$   $A(k) o 0$  при  $k o \infty$ 

**Луна и Земля**Снимок с борта Discovery 16.07.15 из точки Лагранжа (1,5 млн км от



# СПАСИБО ЗА ВНИМАНИЕ!