



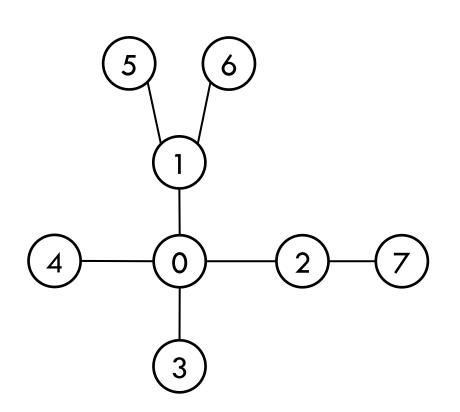
## CONTENT

- 1. Adjacency List Review
- 2. Search
- 3. Depth-first search
- 4. Breadth-first search
- 5. Edge-weighted graphs
- 6. The shortest path
- 7. Dijkstra's algorithm





# ADJACENCY LIST (REVIEW)



AdjList[0]	= (1, 2, 3	, 4)
------------	------------	------

AdjList[1] = 
$$(0, 5, 6)$$

$$AdjList[2] = (0, 7)$$

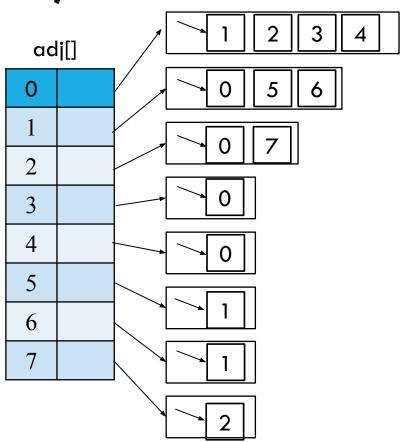
$$AdjList[3] = (0)$$

$$AdjList[4] = (0)$$

$$AdjList[5] = (1)$$

$$AdjList[6] = (1)$$

$$AdjList[7] = (2)$$

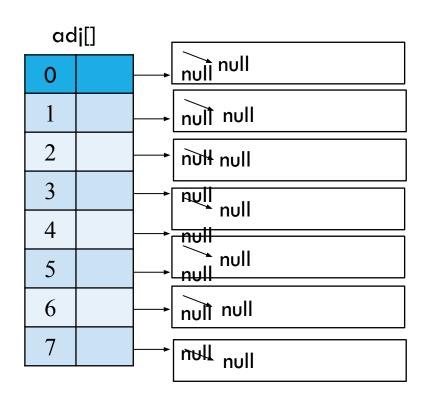






# ADJACENCY LIST (REVIEW)

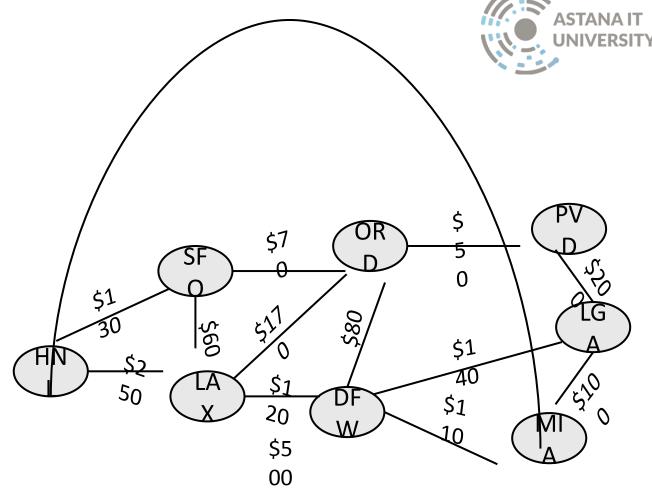
```
public static void main(String[] args) {
public class MyGraph{
                                                           MyGraph g = new MyGraph(8);
    private int V, E;
    LinkedList<Integer> adj[];
                                                           g.addEdge(0, 1);
                                                           g.addEdge(0, 2);
    MyGraph(int nodes){
                                                           g.addEdge(0, 3);
        V = nodes:
                                                           g.addEdge(0, 4);
        this.adi = new LinkedList[nodes];
                                                           g.addEdge(1, 5);
                                                           g.addEdge(1, 6);
        for(int v = 0; v < V; v++) {
                                                           g.addEdge(2, 7);
             adj[v] = new LinkedList<>();
                                                           g.printGraph();
    public void addEdge(int u, int v) {
         adj[u].add(v);
         adj[v].add(u);
    public void printGraph() {
        for(int v = 0; v < V; v++) {
             System.out.print("AdjList[" + v + "]: ");
             for(int w = 0; w < adj[v].size(); w++) {
    System.out.print(adj[v].get(w) + " ");</pre>
             System.out.println();
```





### SEARCH

- Why do we need to search graphs?
- Path problems: e.g. What is the shortest path from node A to node B?
- Connectivity problems: e.g, If we can reach from node A to node B?
- Spanning tree problems: e.g. Find the minimal spanning tree



What is the shortest path from MIA to SFO? Which path has the minimum cost?





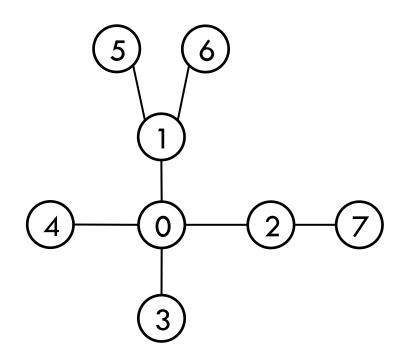
### **SEARCH**

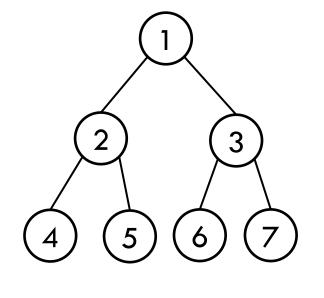
- There are two standard graph traversal techniques:
- Depth-First Search (DFS)
- Breadth-First Search (BFS)
- In both DFS and BFS, the nodes of the undirected graph are visited in a systematic manner so that every node is visited exactly one.





## **DEPTH-FIRST SEARCH**



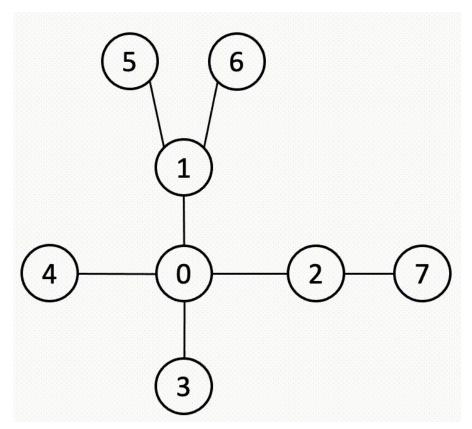






### DEPTH-FIRST SEARCH

- ☐ DFS follows the following rules:
- 1. Select an unvisited node x, visit it, and treat as the current node
- Find an unvisited neighbor of the current node, visit it, and make it the new current node;
- If the current node has no unvisited neighbors, backtrack to the its parent, and make that parent the new current node;
- 4. Repeat steps 3 and 4 until no more nodes can be visited.
- 5. If there are still unvisited nodes, repeat from step 1.
- A **stack data structure** is used to support backtracking when implementing the DFS

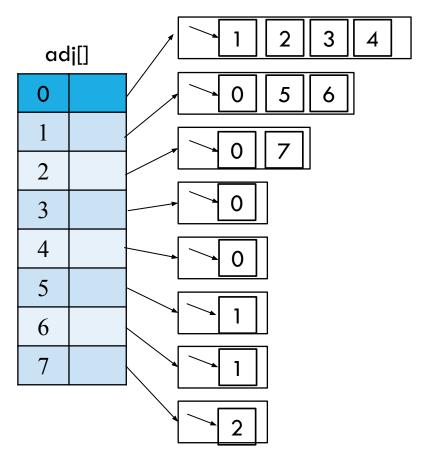






#### DEPTH-FIRST SEARCH

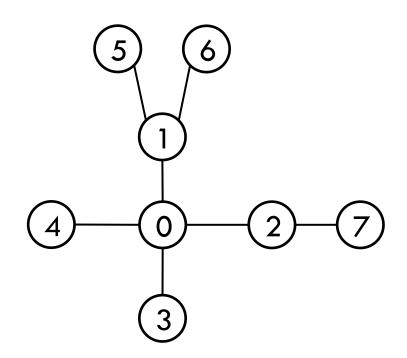
```
public void dfs() {
    boolean[] visited = new boolean[V];
    for(int v = 0; v < V; v++) {
        if(!visited[v]) {
            visitVertex(v, visited);
public void visitVertex(int v, boolean[] visited) {
    visited[v] = true;
    System.out.print(v + " ");
    for(int w = 0; w < adj[v].size(); w++) {</pre>
        if(!visited[adj[v].get(w)]) {
            visitVertex(adj[v].get(w), visited);
```

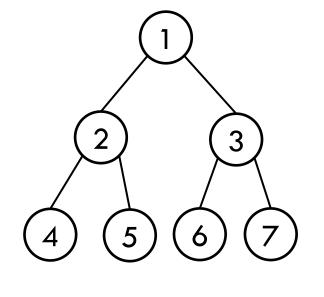






## **BREADTH-FIRST SEARCH**



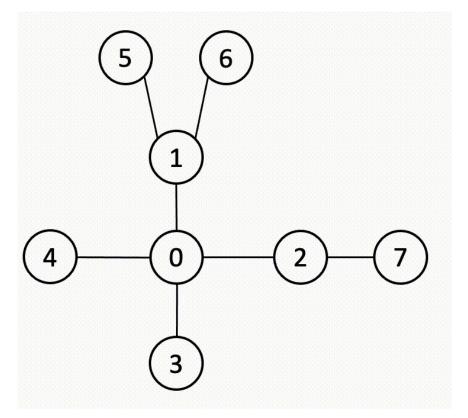






### **BREADTH-FIRST SEARCH**

- ☐ BFS follows the following rules:
- Select an unvisited node x, visit it, have it be the root in a BFS tree being formed. Its level is called the current level.
- 2. From each node z in the current level, in the order in which the level nodes were visited, visit all the unvisited neighbors of z. The newly visited nodes from this level form a new level that becomes the next current level.
- 3. Repeat step 2 until no more nodes can be visited.
- 4. If there are still unvisited nodes, repeat from Step 1.
- A queue data structure is used when implementing the BFS

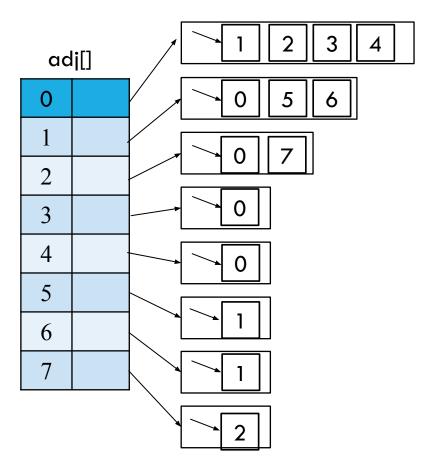






#### **BREADTH-FIRST SEARCH**

```
public void bfs(int start) {
    boolean[] visited = new boolean[V];
    visited[start] = true;
    Queue<Integer> q = new LinkedList<>();
    q.add(start);
    while(!q.isEmpty()) {
        int u = q.poll();
        System.out.print(u + " ");
        for(int w = 0; w < adj[u].size(); w++) {</pre>
            if(!visited[adj[u].get(w)]) {
                visited[adj[u].get(w)] = true;
                q.add(adj[u].get(w));
```







## **EDGE-WEIGHTED GRAPHS**

An edge-weighted graph is a graph model where we associate weights or costs with each edge

Example Applications: **Route** for *Yandex taxi* where the **weight** might represent

- Distance
- Approximate **time**
- Average **speed**
- Or all the above for that section of road

Weight calculation is entirely up to the designer

```
public class Edge<Vertex> {
    private Vertex source:
```

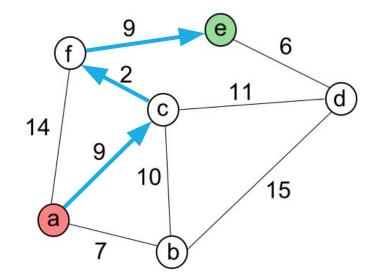


# THE SHORTEST PATH

Find the lowest-cost way to get from one vertex to another

A path weight is the sum of the weights of that path's edges

The **shortest path** from vertex **a** to vertex **e** in an edge-weighted digraph is a directed path from **a** to **e** with the property that no other such path has a lower weight

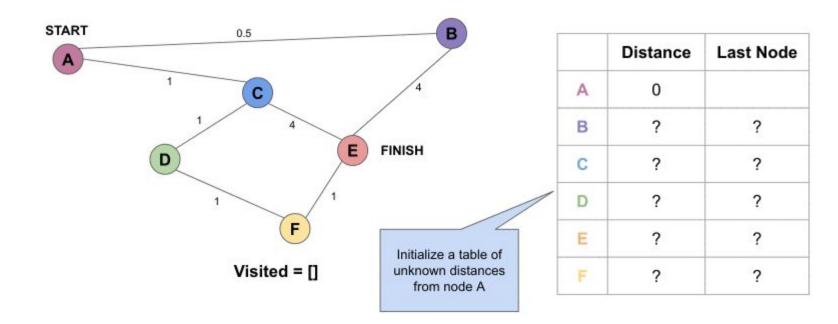






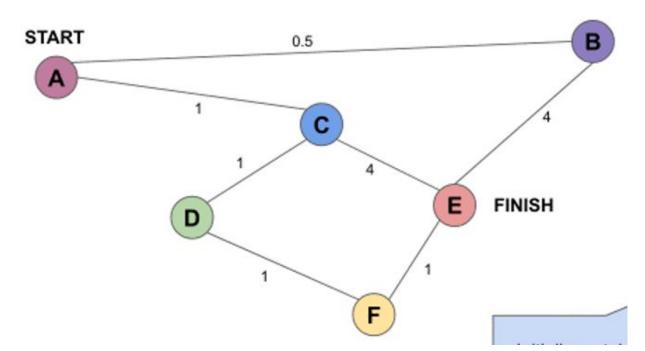
Dijkstra's algorithm solves the single-source shortest-paths problem in edge-weighted digraphs with nonnegative weights

The method keeps track of the current shortest distance between each node and the source node and updates these values whenever a shorter path is discovered









Visited vertex	В	C	D	Е	F
	0.5.	1	inf	inf.	inf
В	0.5.	1	inf	4.5	inf

Chaosse three solist terrates authorholeic lives thoese if the Breain dovinit it is shorter path





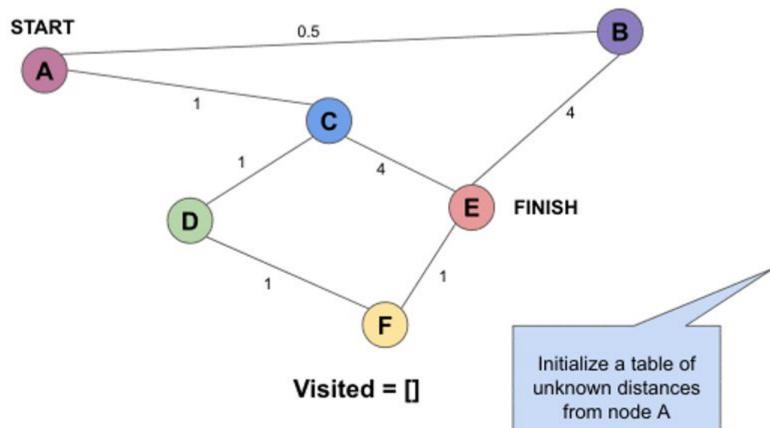
When the algorithm finds the shortest path between two nodes, that node is tagged as "visited" and added to the path

The method is repeated until the path contains all the nodes in the graph

Only graphs with **positive weights** can be used by Dijkstra's Algorithm. This is because the weights of the edges must be added

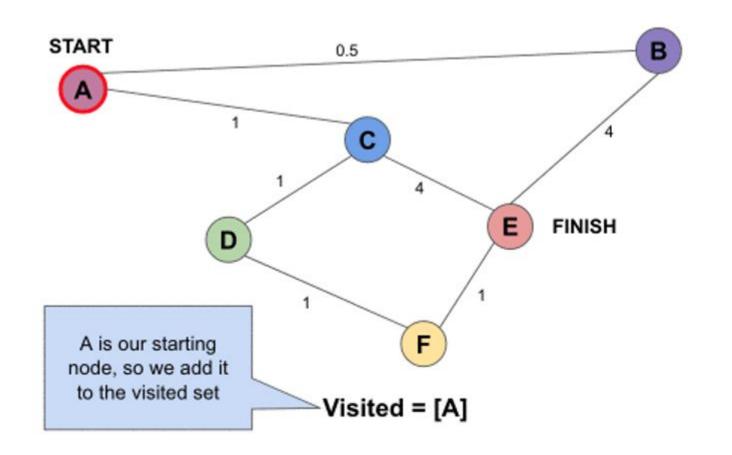






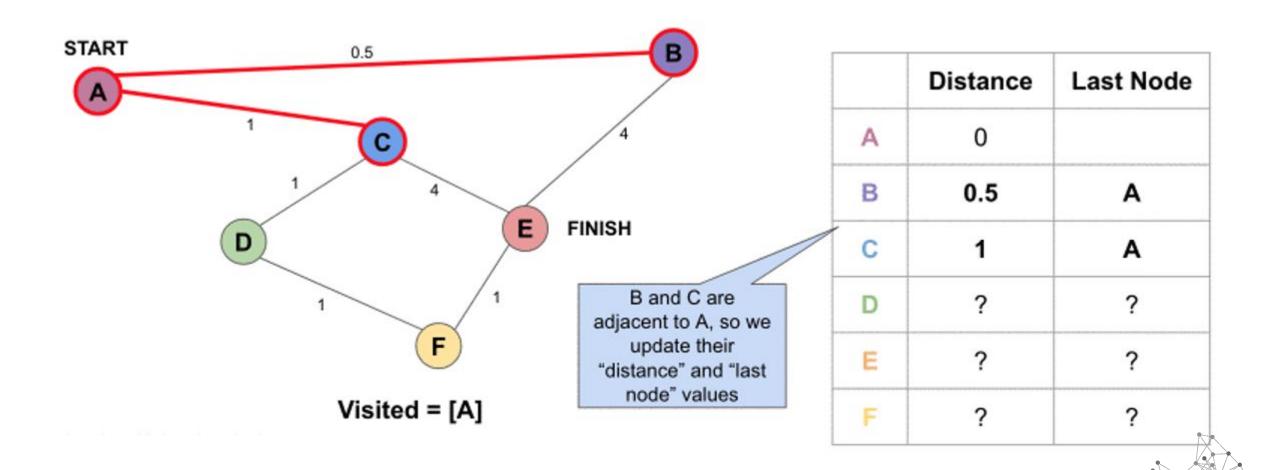
	Distance	Last Node
Α	0	
В	?	?
С	?	?
D	?	?
E	?	?
F	?	?



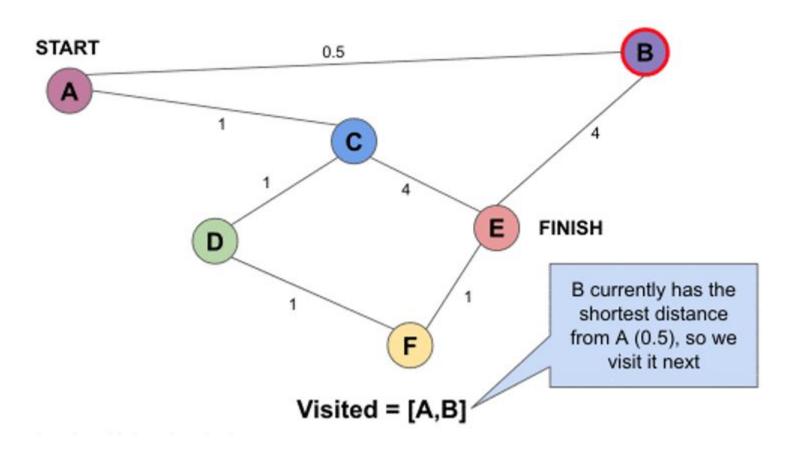


	Distance	Last Node
Α	0	
В	?	?
С	?	?
D	?	?
Е	?	?
F	?	?









	Distance	Last Node
Α	0	
В	0.5	А
С	1	А
D	?	?
E	?	?
F	?	?



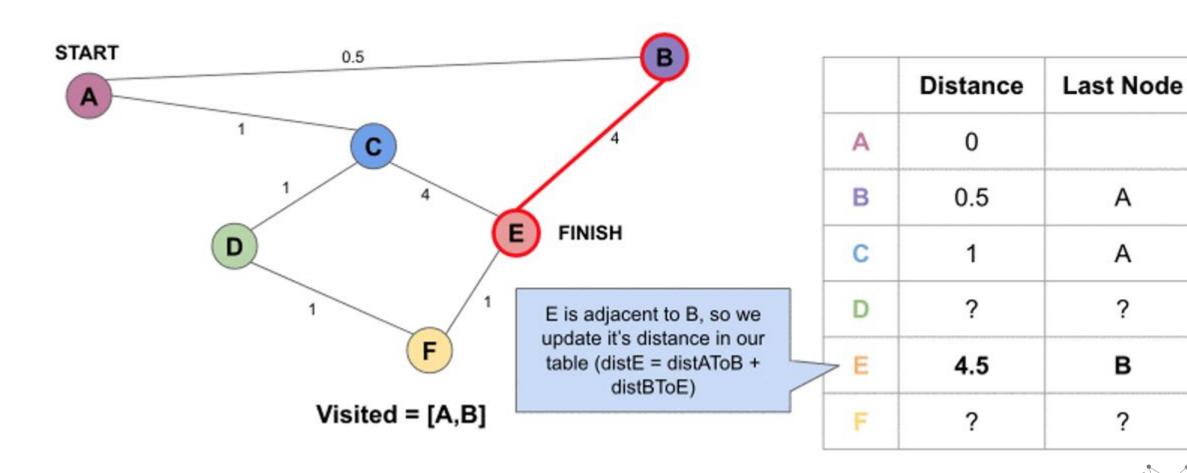
Α

Α

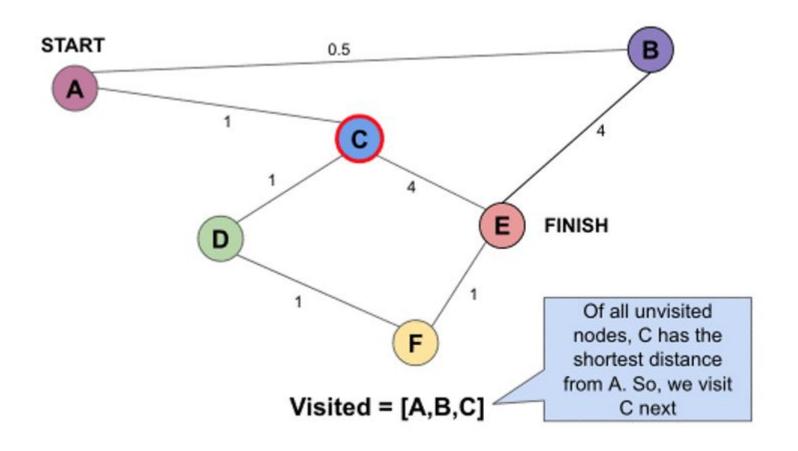
?

В

?

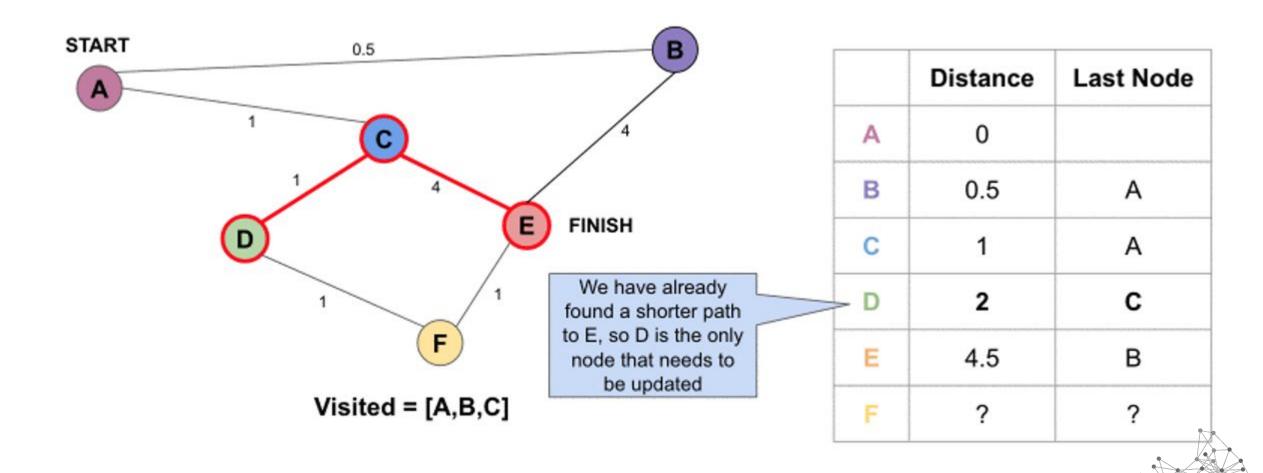




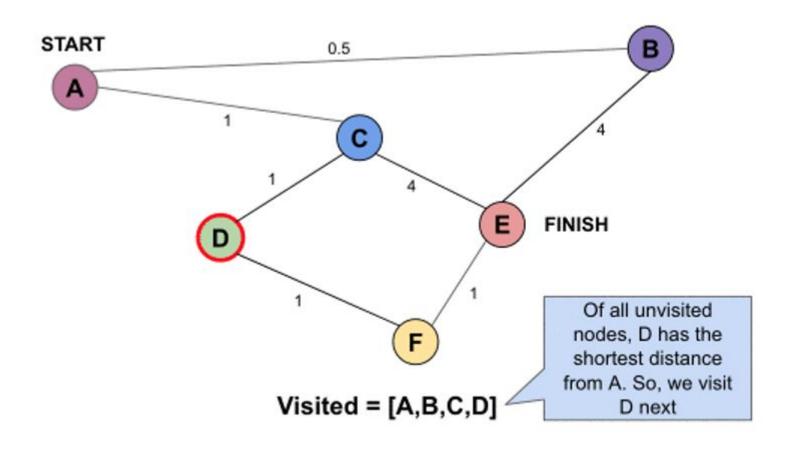


	Distance	Last Node
Α	0	
В	0.5	Α
С	1	А
D	?	?
E	4.5	В
F	?	?



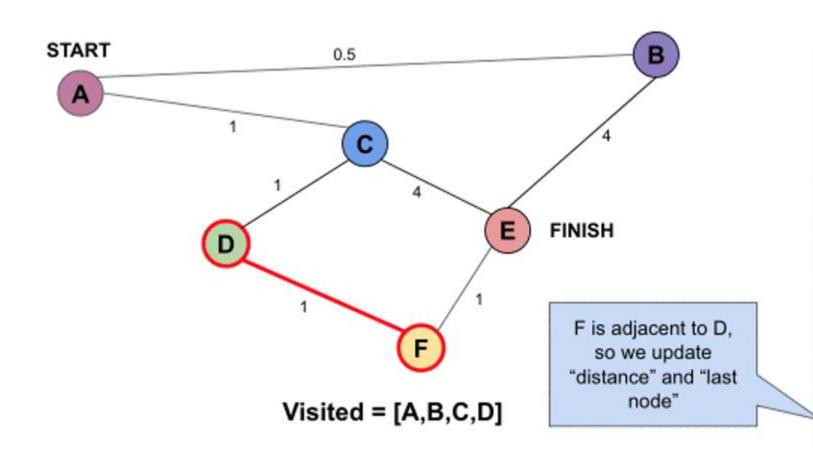






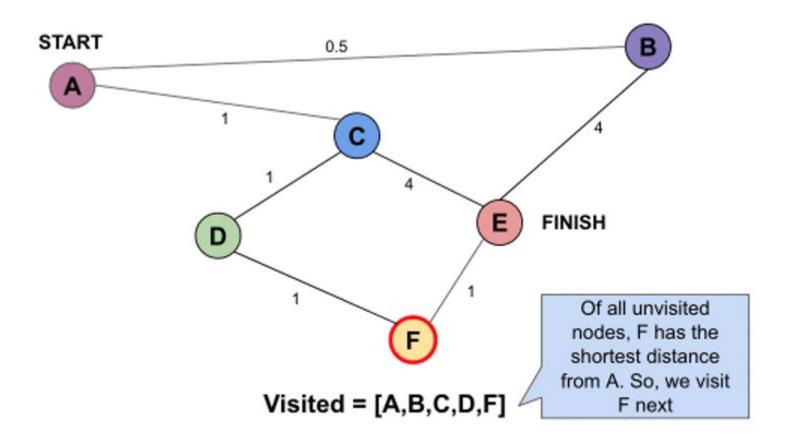
	Distance	Last Node
Α	0	
В	0.5	Α
С	1	Α
D	2	С
E	4.5	В
F	3	D





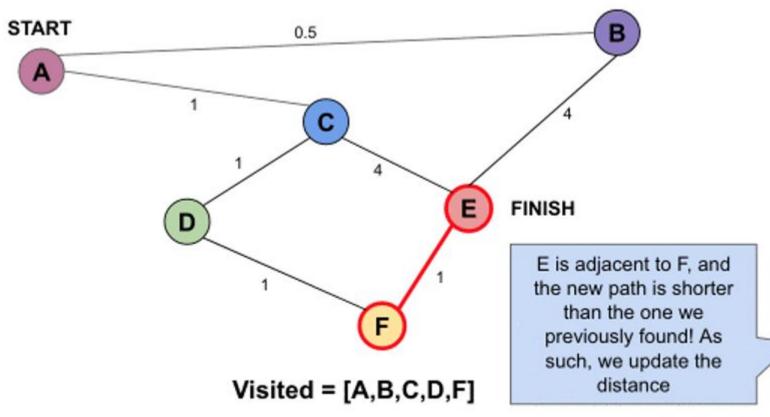
	Distance	Last Node
Α	0	
В	0.5	Α
С	1	А
D	2	С
Ē	4.5	В
F	3	D





	Distance	Last Node
Α	0	
В	0.5	Α
С	1	А
D	2	С
E	4.5	В
F	3	D





	Distance	Last Node
Α	0	
В	0.5	Α
С	1	Α
D	2	С
E	4	F
F	3	D



## **LITERATURE**

Algorithms, 4th Edition, by Robert Sedgewick and Kevin Wayne, Addison-Wesley

Chapter 4

Grokking Algorithms, by Aditya Y. Bhargava, Manning

Chapters 6-8



