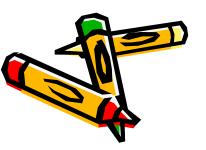




March.2011

Catalogue

- · 1. Introduction of working principle
- 2. Introduction of main circuit (parts different from MMA)
- 3. Introduction of control circuit (parts different from MMA)
- 4. Introduction of panel circuit
- · 5. Introduction of remote circuit
- 6. Troubleshooting
- · 7. Appendix

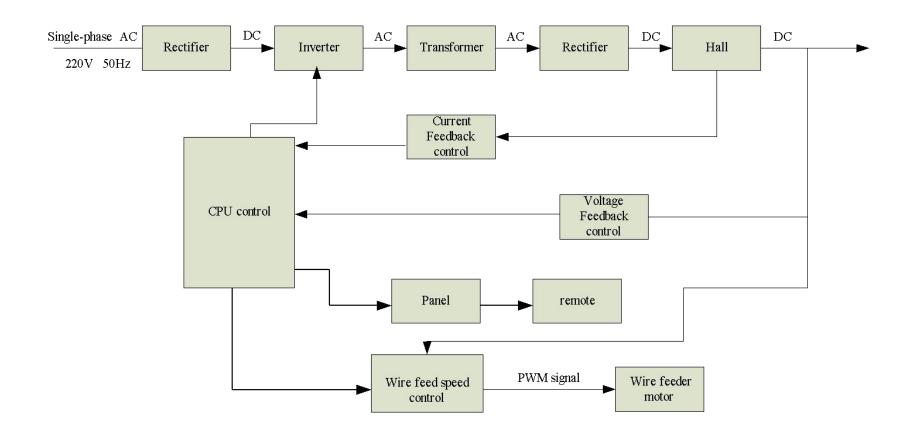




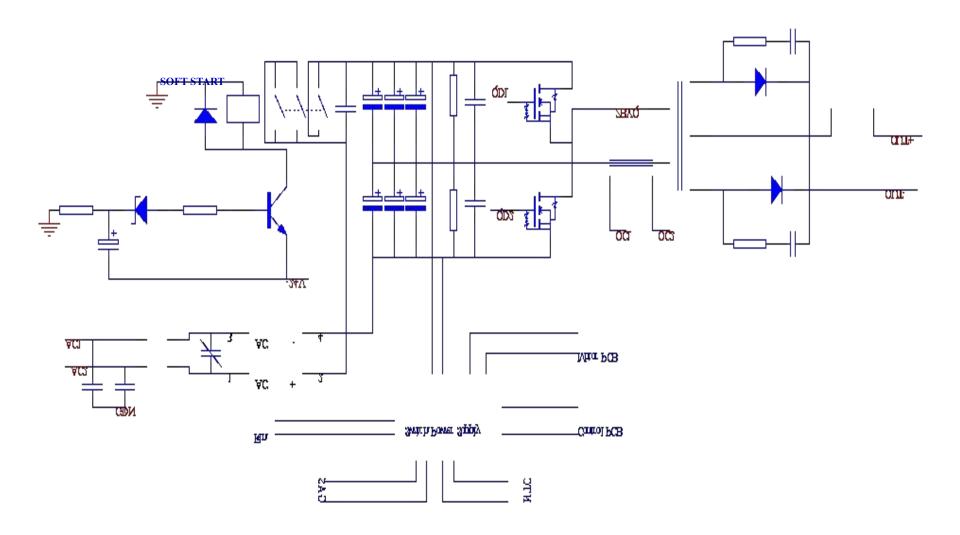
1. Introduction of working principle



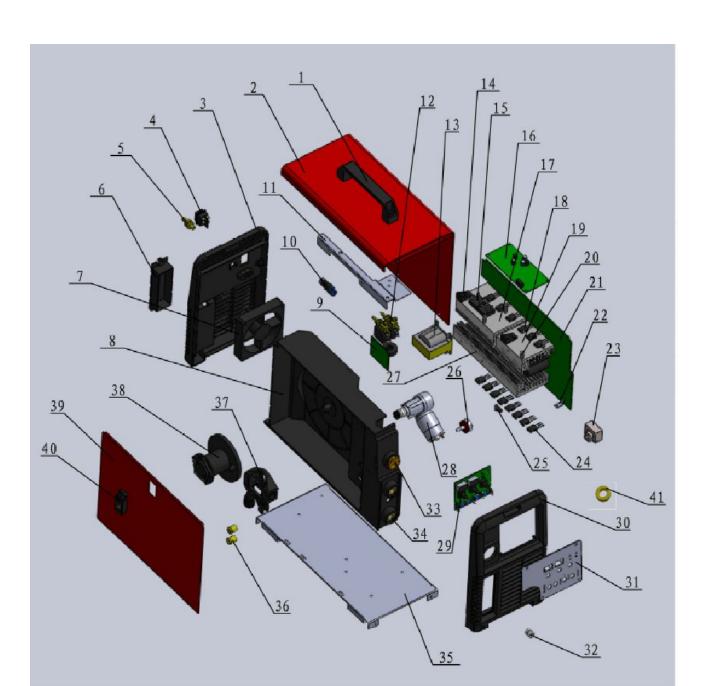




Working principle



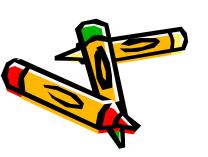
System chart

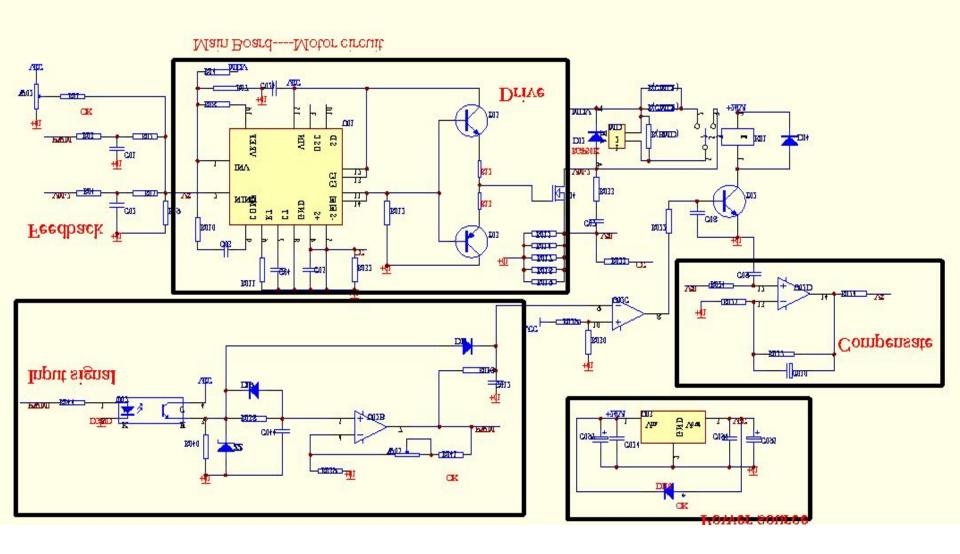


No.	Name	Code	Unit
1	HANDLE	8. 253. 020	1
2	LEFT BOARD	8. 050. 112	1
3	REAR PANEL	8. 068. 984	1
4	SWITCH	7. 232. 730	1
5	AIR INLET	8. 462. 180	1
6	SPARE AND TOOL BOX	8. 831. 010	1
7	FAN	7. 720. 005-B	1
8	CLAPBOARD	8. 124. 623	1
9	MIG EMC BAN	5. 496. 067	1
10	Y TYPE THREE-WAY CONNECTION	7. 624. 281	1
11	GAS VALVES MUNTING PLATE	8. 123. 159-B	1
12	TWO-POSITION SOLENOID VALVE	7. 253. 013	2
13	TRANSFORMER	6. 185. 119	1
14	SHORE	8. 123. 620	1
15	RECTIFIER	7. 411. 015	2
16	MIG CONTROL PCB	5. 496. 996-E	1
17	HEAT SINK II	8. 425. 119	1
18	TRANSISTOR	7. 425. 631	6
19	HEAT SINK III	8. 425. 120	1
20	HEXAGON KEEP POST	7. 503. 530	4
21	MAIN PCB	5. 496. 068-A	1
22	SHORE	8. 123. 633	2
23	HALL	7. 321. 105	1

24	DIODE	7. 421. 107	8
25	NTC HOT RESISTANCE	7. 445. 401	1
26	CHARFILM POTENTIAL	7. 456. 126	1
27	HEAT SINK I	8. 425. 118	1
28	MIG FEDDER POWER	4. 021. 000	1
29	MIG FACEPLATE	5. 495. 994-B	1
30	FRONT PANEL	8. 069. 984	1
31	FRONT BLANKING PLATE	8. 306. 115	1
32	TRIPLEX AVIATION SOCKET	7. 132. 303	1
33	TRANSEND NEB	8. 178. 110	1
34	35∼70MM² SOCKET	7. 152. 315	1
35	BASE	8. 055. 118	1
36	CHANGEOVER CONNECTOR	8. 462. 181	2
37	FEED FIGHT	8. 081. 110	1
38	FEED PLATE	8. 199. 130	1
39	RIGHT BOARD	8. 051. 112	1
40	SQUARENESS BIN	7. 686. 300	1
41	INDUCTANCE	6. 271. 132	1

2. Introduction of main circuit (parts different from MMA)





View of main board

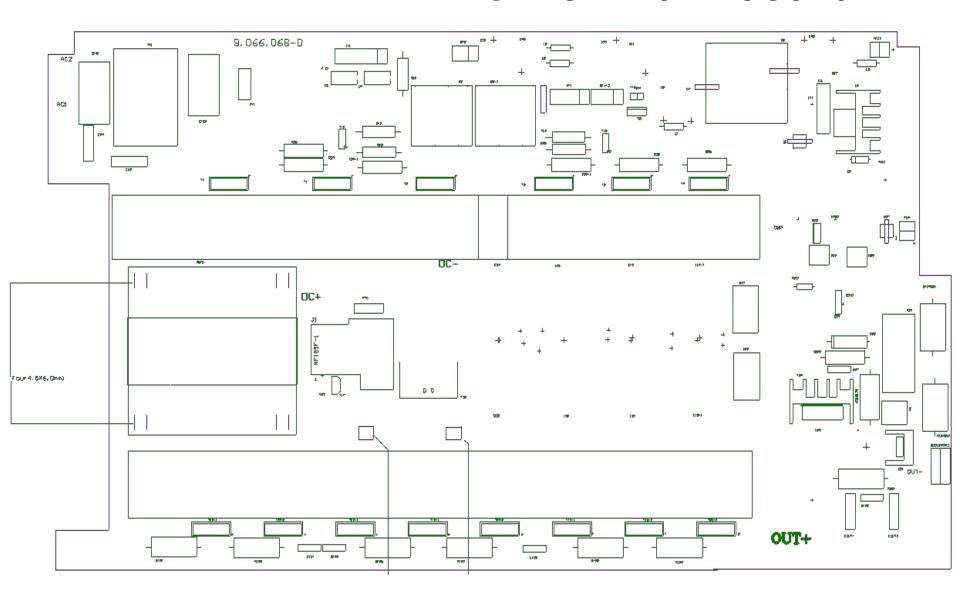


Photo of main board

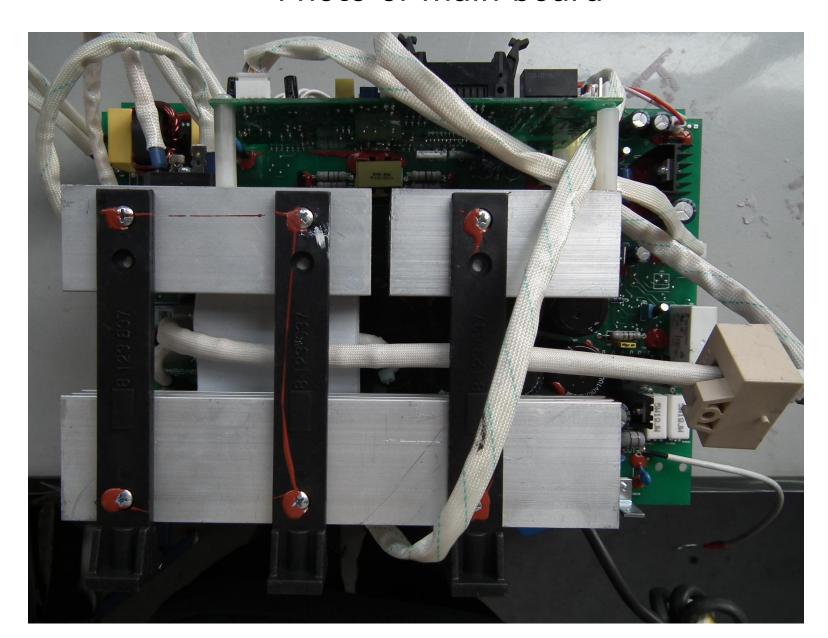
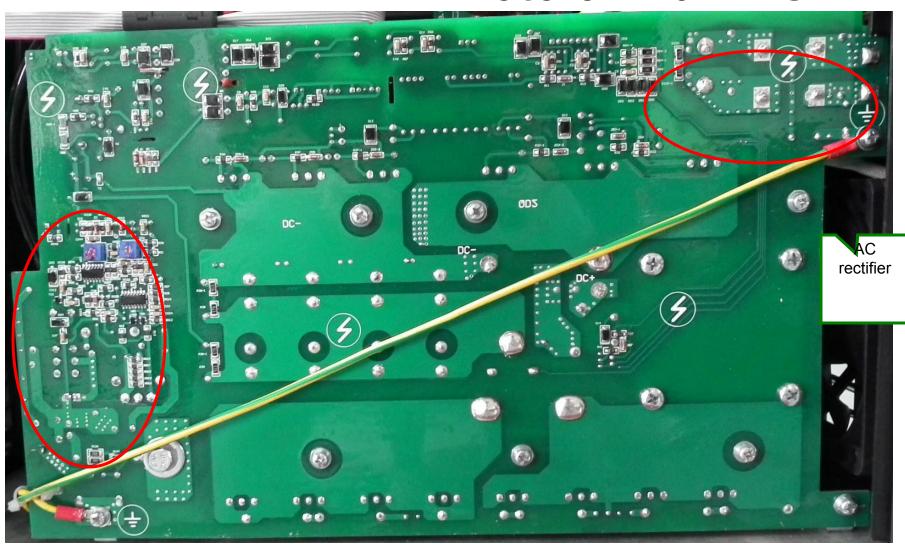
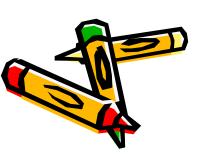


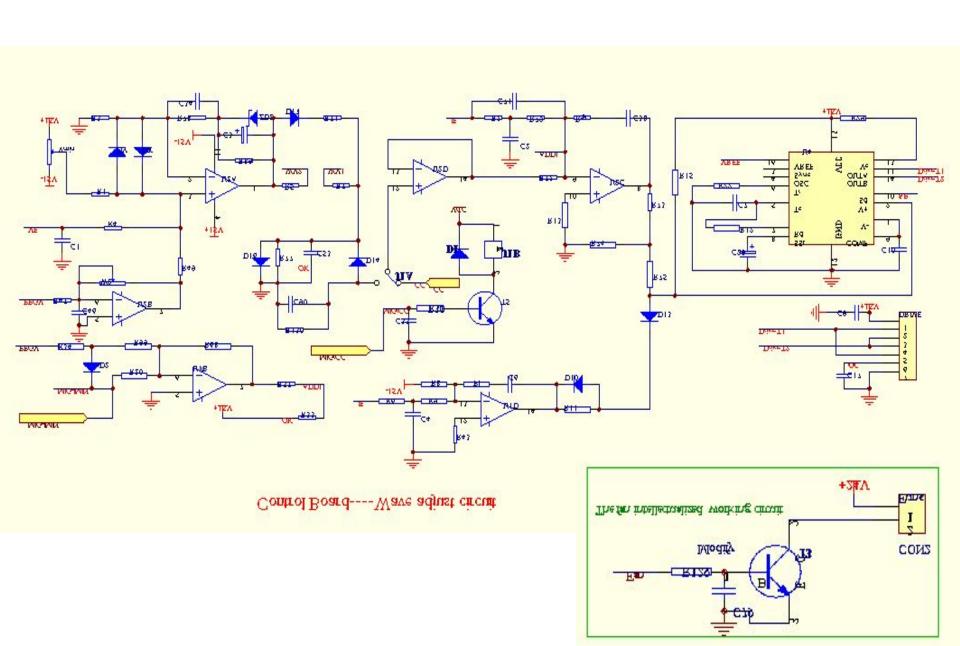
Photo of main PCB

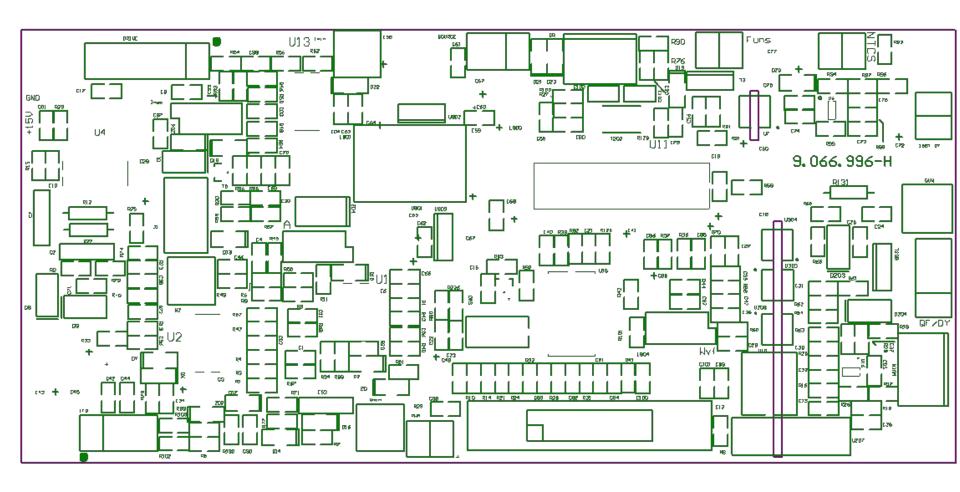


Motor driver circuit

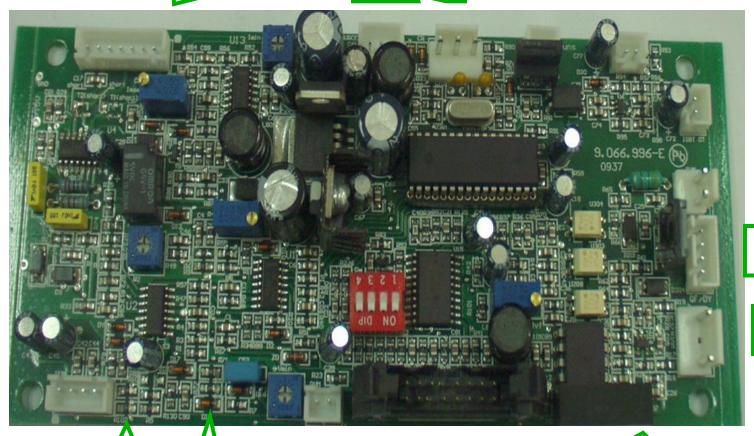
3. Introduction of control circuit (parts different from MMA)







Drive Imax Imin Power CR Funs NTCS



IGBT OT

Gun

QF/DY

WYIN

IFB

W2

A

Vmin

PWM

MB

Wvf

• DRIVE--Connected with main board to provide drive signal for discrete IGBT.

Pin 1---- +15V; Pin 2~5---- Drive signal; Pin 6---- OC; Pin 7---- GND

• SOURCE--Connected with main board to provide control board with power source and test signal of tip.

Pin 1---- +24V; Pin 2---- GND; Pin 3---- -24V.

- MB--Connected with panel board to communicate.
- CR--Connected with crater arc potentiometer, Burn back signal.

Pin 1---- GND; Pin 2---- crater arc; Pin 3---- +5V.

- GUN--Connected with the torch to provide signal of gun.
- QF/DY--Connected with the gas switch.

- IGBT OT--Connected with the IGBT NTC to provide over-temperature signal for MCU.
- WVIN--Connected with the output to sample voltage signal.

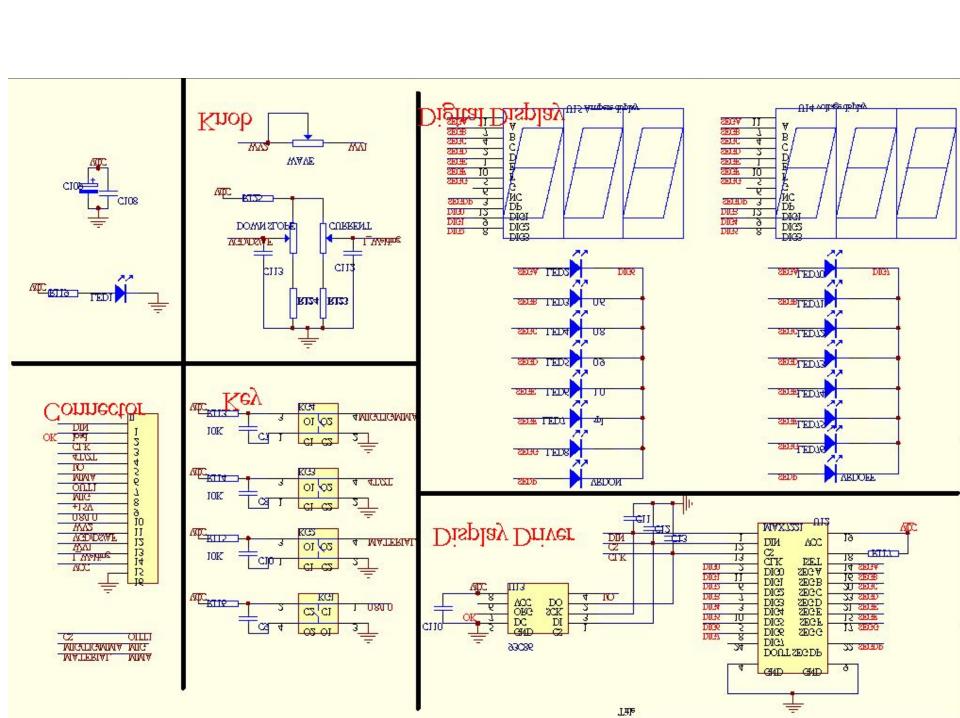
Pin 1---- cathode of output; Pin 2---- positive pole of output.

- IFB--Connected with HALL sensor to sample current signal.
- Pin 1---- +15V; Pin 2---- -15V; Pin 3---- Output of HALL sensor; Pin4---- GND.
- PWM-- Connected with main board to control Motor speed (pulse).
- Fans-- Connected with the fan.

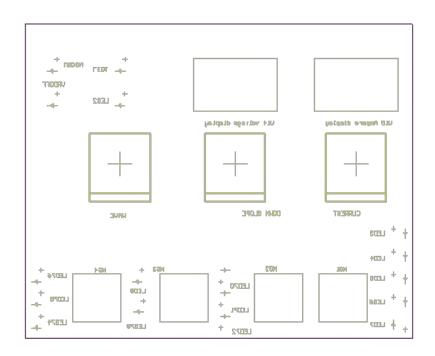
- Imax—used to adjust maximum welding current (MMA).
- Imin—used to adjust minimum welding current (MMA).
- A—used to adjust display current (MMA).
- W2—used to adjust maximum welding voltage (MIG).
- Vmin—used to adjust minimum voltage (MIG).
- Wvf —used to adjust display voltage (MIG).

4. Introduction of panel circuit





View of panel board



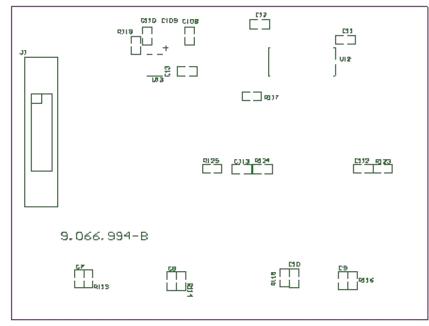


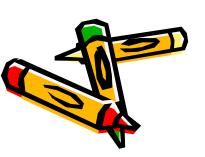
Photo of panel board



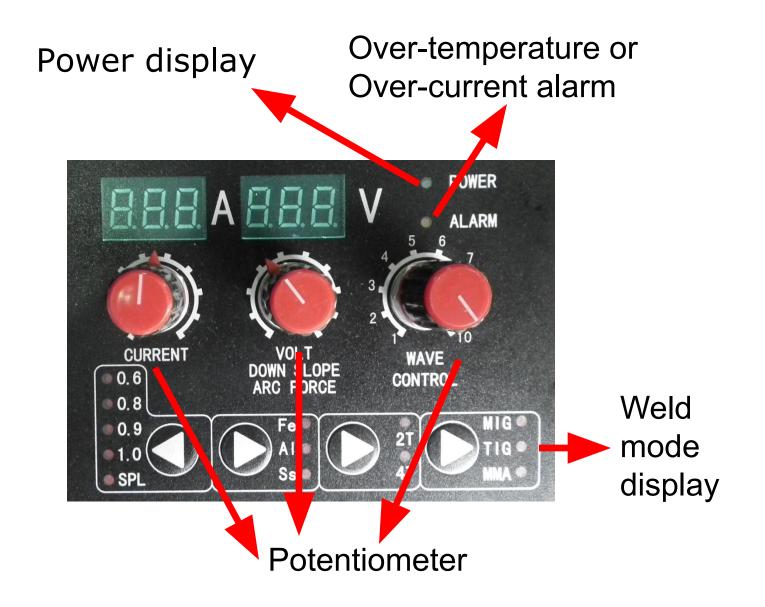
5. Troubleshooting

Series A: Troubles about panel display

Series B: Troubles about power system



A. Presentation of panel



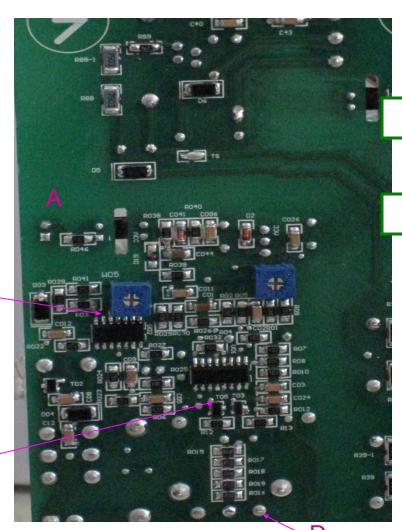
B. Presentation of wire-feeder

Motor drive circuit In Main PCB

Between the two Pins, is CPU speed Voltage

B(U02-6P)

Between the two Pins, is Motor voltage



WD5--Max speed adjust

WD2--Min speed adjust

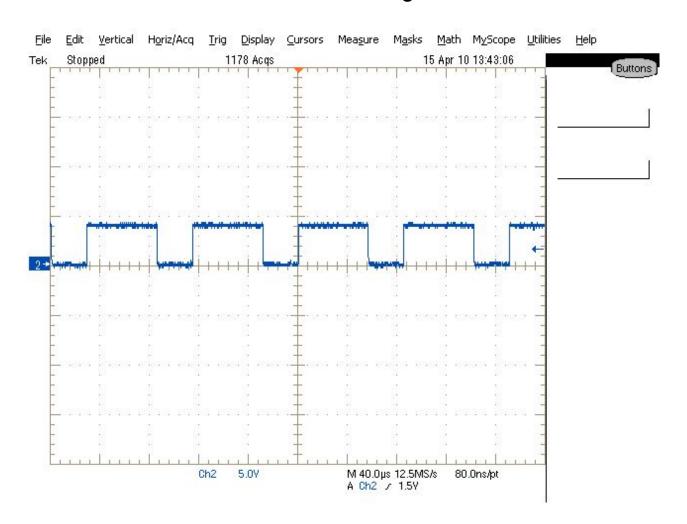
E/F/G wave point is the IC 1/2/3 P

Drive transistor

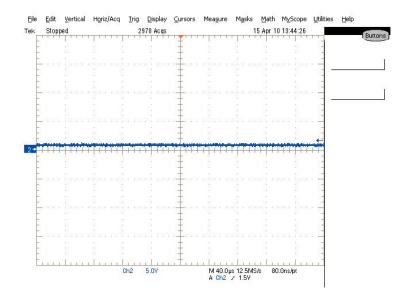
Motor circuit GND (common point)

Test point wave

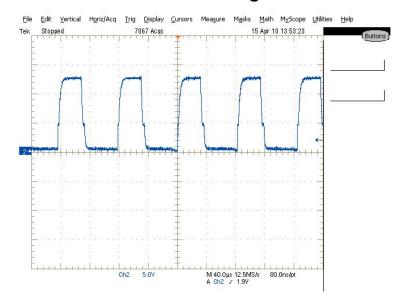
Point A wave :The PWM wave from digital control PCB



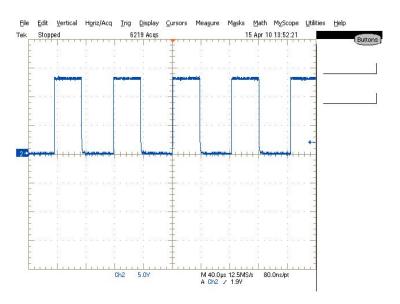
Point B wave :The PWM set point from 6P of U02



Point D wave :The MOSFET gate drive PWM



Point C wave : The drive PWM from SG3524 11P

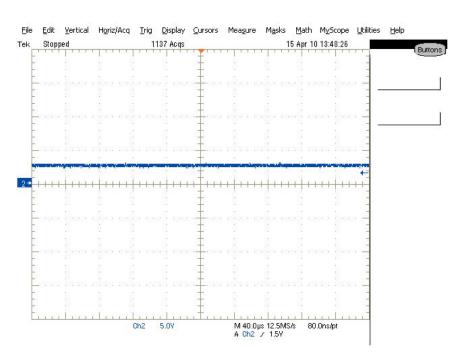


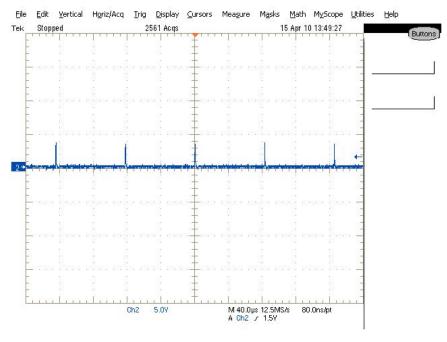
Point E wave: U01 SG3524 1P



Point F wave: U01 SG3524 2P

Point G wave: U01 SG3524 3P





n't k eel «s	The press wheel is loosen or weld wire skids The wheel doesn't fit with	May be the MOS or DIODE in the board is damaged, check it according to the above information. Press it tightly again		
	or weld wire skids			
	The wheel doesn't fit with			
	the diameter of weld wire	Change the wheel		
	Wire reel damaged	Change it		
	Wire feed pipe or tip is jammed	Repair or change it		
_	page16, check the socket isn't +24V,	Check +24V power source and whether the socket link is good.		
If there is +24V,check netlabel Fan , there isn't 5V.		Change control PCB		
If there is +5V,check T3, there isn't 0.7V between B and E.		Change T3		
	reference to 170HF			
_	is +	If there is +5V,check T3, there isn't 0.7V between B and E.		

List of spare part

Title	Unit
Hall	1
Rectifier	1
MIG panel	1
MIG sole plate	1
NTC	1
Waterproof switch	1
Control PCB	1
Wire feed frame	1
Plastic front panel	1
Plastic rear panel	1
Insulated potentiometer	3