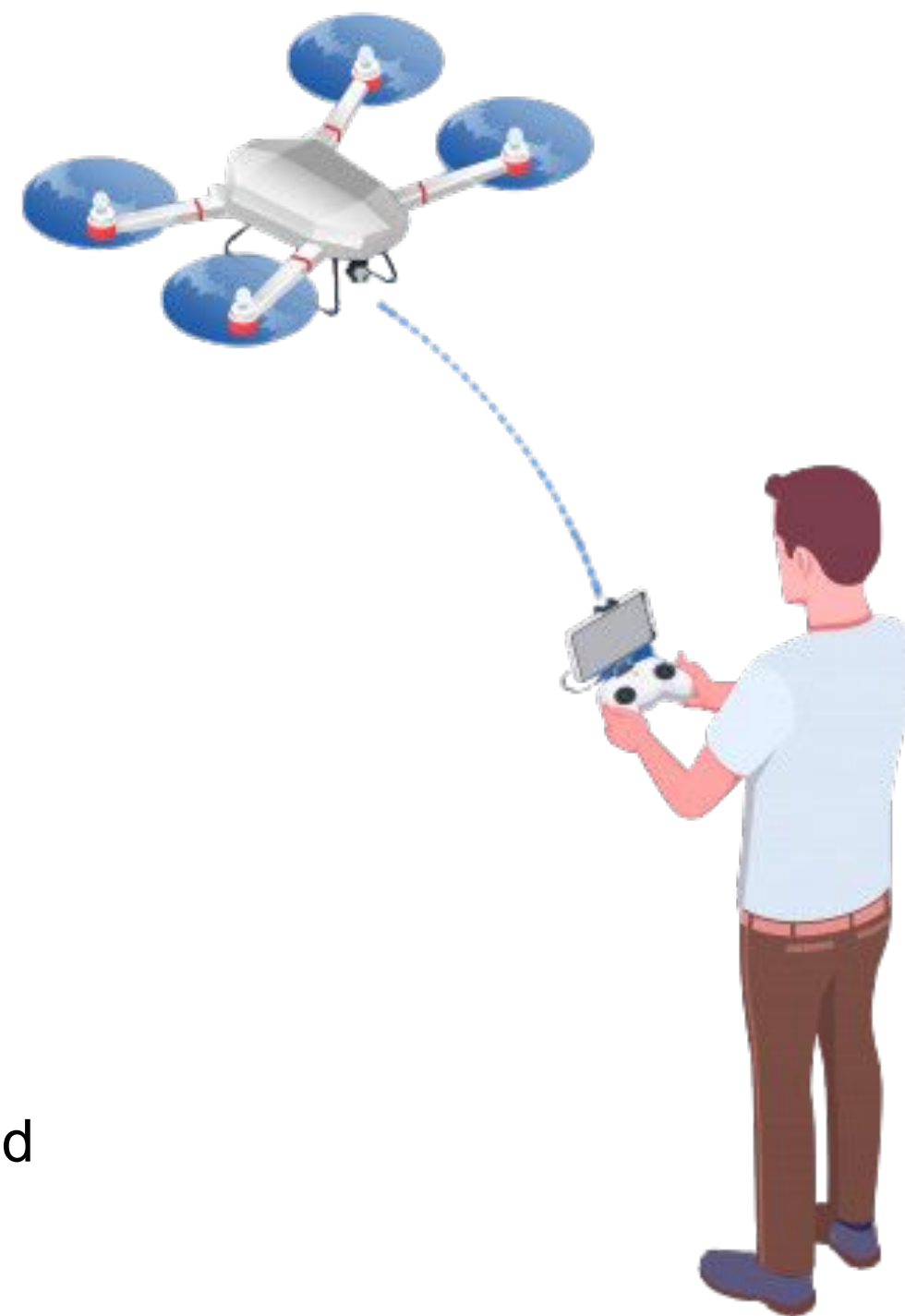


PROTECTION – PASSIVE COHERENT LOCATION RADAR, RADIO MONITORING AND ANTI-UAV SYSTEM



PROBLEM

- Unlawful transmission of various objects across the state border using UAV
- Unauthorized photo/video shooting and audio recording of sensitive sites
- Obstruction to movement of vehicles (airborne, maritime and ground vehicles), as well as causing emergency situations
- Use of UAV while preparing and performing unlawful acts



OUR SOLUTION

Detection, tracking, identification and countermeasures against unmanned aerial vehicles.

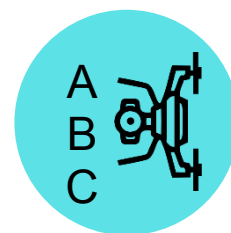
TASKS PERFORMED



Continuous monitoring of airspace for moving UAV (and other purposes)



Visual representation on a topographic map of the site when UAV is detected



Determined target type identification and distinguishing the UAV class



UAV flight route display on a topographic map



Determination of UAV control panel location



Issue of target indication to external (interfaced) UAV elimination and suppression system



Suppression of control signals and global positioning system (GPS)

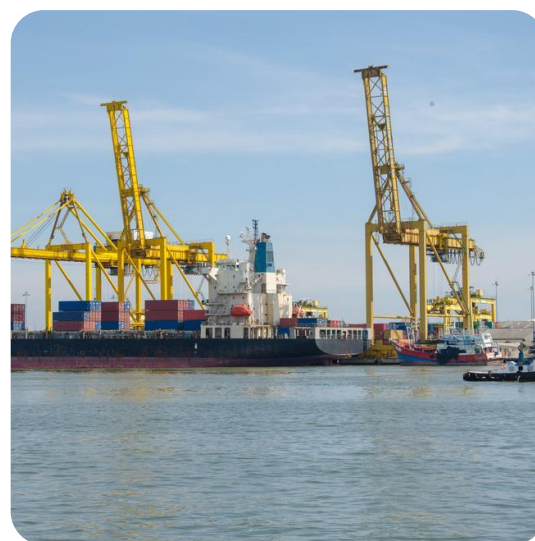
KEY SITES THAT NEED PROTECTION FROM UAV



Stadiums



Airports



Ports



Oil and gas infrastructure



Oil and gas lines



Chemical plants



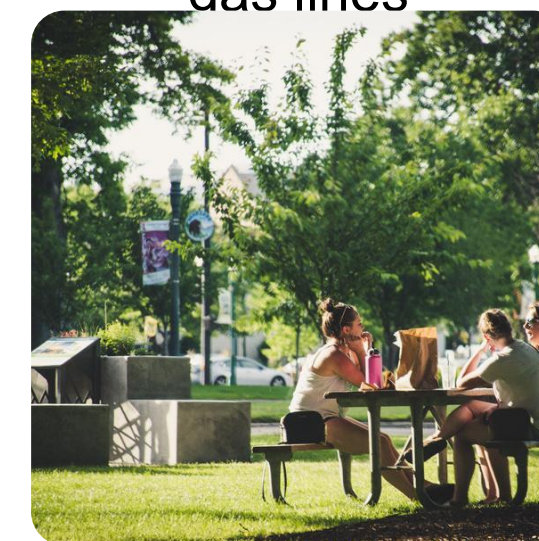
Hydropower plants



Nuclear power plants



Corrective labour institutions



Social infrastructure

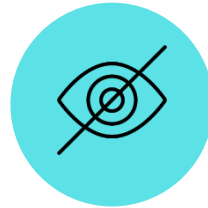
ADVANTAGES OF THE SYSTEM



Mobility – the system is implemented on the basis of portable case containers and can be placed at any location



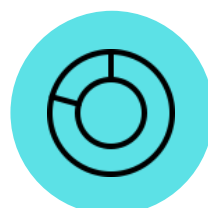
System deployment time not more than 30 minutes



Operates in passive mode, no active radiation



Can be interfaced with UAV suppression and elimination equipment



Selective action against intruder drone



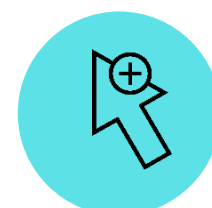
Detects location of UAV and remote control panel



Displays UAV route on a topographic map



Year-round operation in any weather conditions

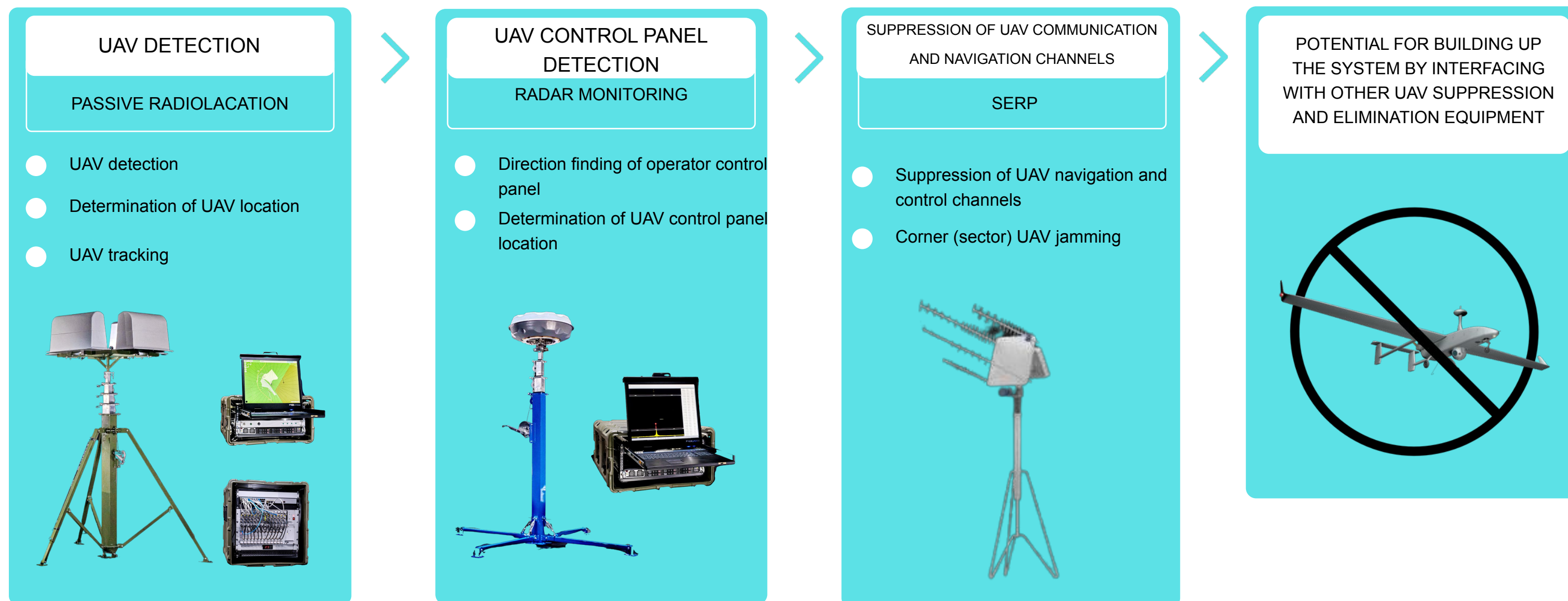


No EMI effect on infrastructure of the monitored site

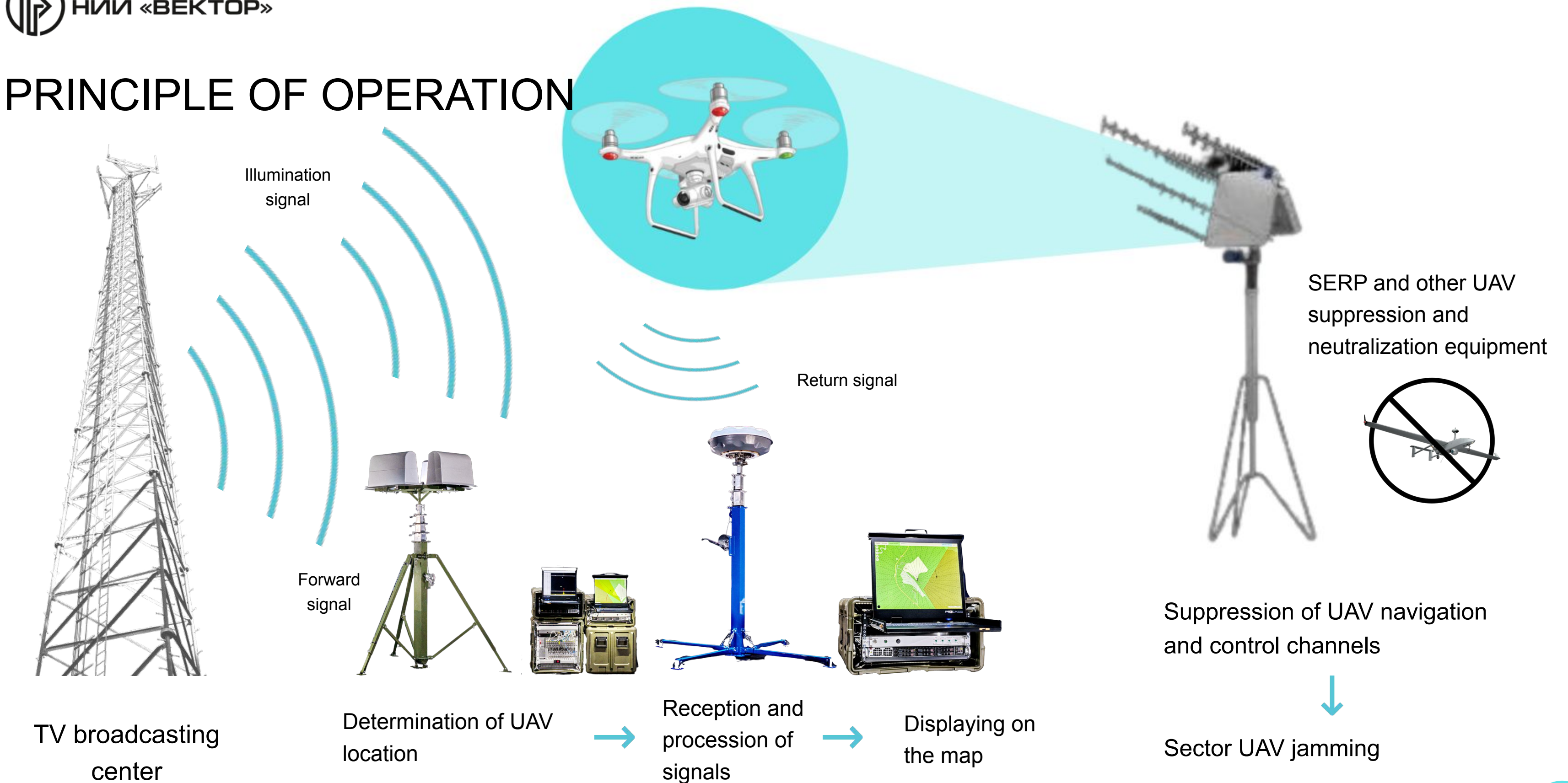


Coverage area – 360 degrees

PROTECTION – PASSIVE COHERENT LOCATION RADAR AND RADIO MONITORING SYSTEM WITH ANTI-UAV FEATURE



PRINCIPLE OF OPERATION



PCLR (PASSIVE COHERENT LOCATION RADAR)

PURPOSE AND COMPOSITION



Passive coherent location radar equipment is designed for position determination of moving and radio silent targets. Principle of operation is based on detecting and processing the digital TV signals reflected from the target.

Composition:

1. Antenna-feeder equipment of passive coherent location radar system.
2. Radio receiver of passive coherent location radar system.
3. Processing and display unit.
4. Set of communication equipment.

PCLR (PASSIVE COHERENT LOCATION RADAR) TECHNICAL CHARACTERISTICS

- Elevation coverage, degrees **not less than 60**
- Maximum number of simultaneously tracked targets **not less than 50**
- Operating frequencies of passive coherent location radar system, MHz **470-790 MHz**
- Frequency range of receiving channels for passive coherent location radar system **not less than 8 MHz**
- Sensitivity of receiving channels for passive coherent location radar system **not more than -95 dB/mW in 7,8 MHz band**
- Number of receiving channels for passive coherent location radar system **not less than 24**
- Number of antenna elements in the antenna for passive coherent location radar system **not less than 24**

RADIO MONITORING. PURPOSE AND COMPOSITION



Radio monitoring equipment is designed for tracking the objects using their own control signal. The data allow to identify both the drone and the operator.

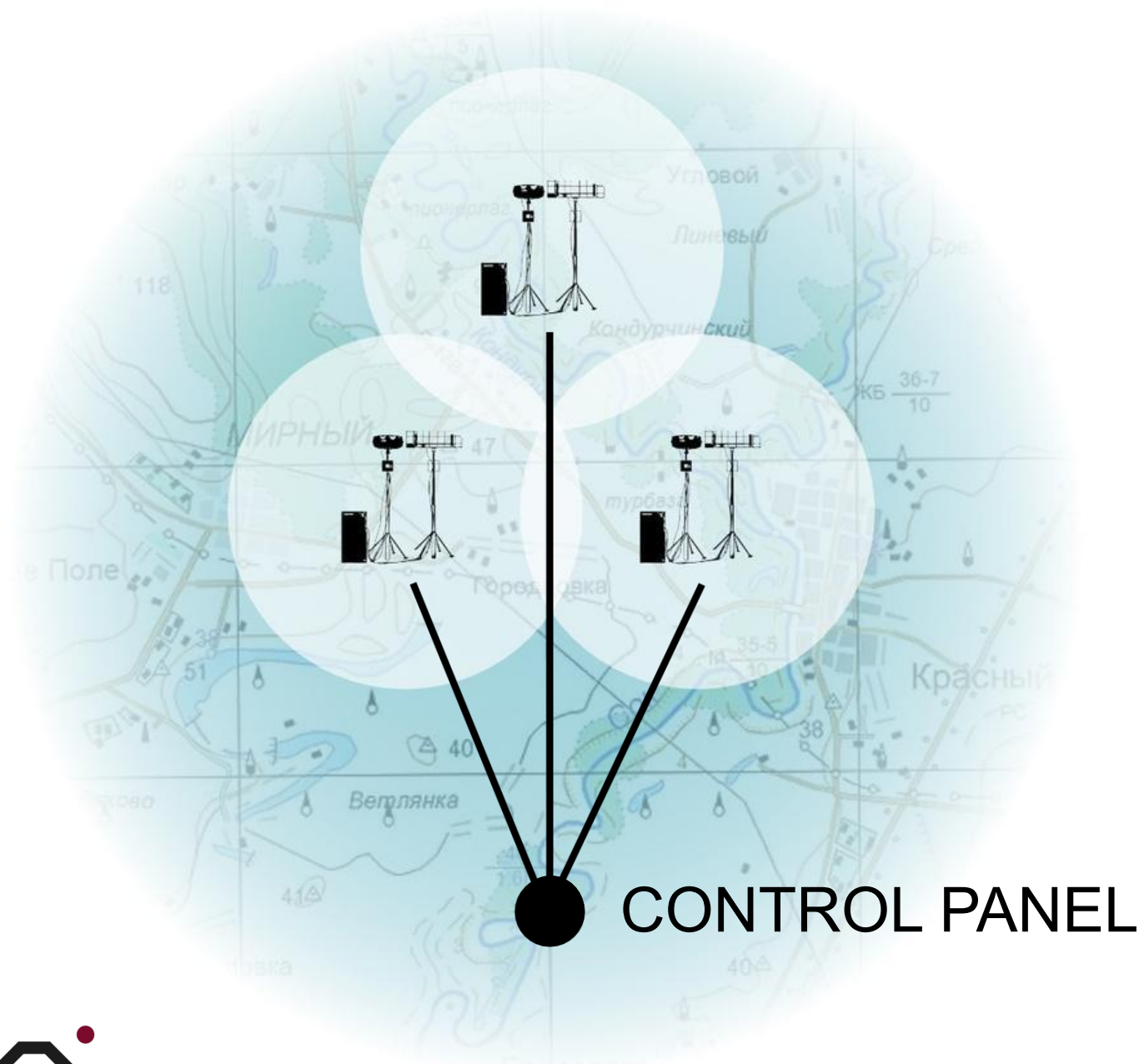
Composition:

1. Antenna-feeder system of radio monitoring.
2. Equipment for receiving the radio monitoring signals.



DETERMINATION OF EXACT COORDINATES OF DRONE AND CONTROL PANEL

Using one system allows to determine the drone coordinates and direction to its control panel, but using three systems allows to find exact coordinates for both the drone and the control panel.



RADIO MONITORING. TECHNICAL CHARACTERISTICS

- Operating frequencies of radio monitoring **300-6,000 MHz**
- Number of antenna elements in the antenna for radio monitoring **two letters 9 elements each**
- Frequency range used during simultaneous analysis for radio monitoring in the mode of detection and direction finding **100 MHz**
- Scan rate with simultaneous direction finding during radio monitoring **1 GHz/s**
- Direction finding time **during radio monitoring, 100 ms for 100 MHz band**



SERP JAMMER

PURPOSE AND COMPOSITION

PROVIDES:

- Suppression of GPS and GLONASS (L1, L2, L5), GSM900, WiFi signals
- Suppression of control channels and data transmission to UAV



COMPOSITION:

- Control generation unit IVB111
- 5-band antenna system
- Power supply unit IVB112
- Quadro-pod
- HF cables set
- Power supply cable
- Ethernet cable

Antennas within the frequency range from 900 to 5,600 MHz

SERP. TECHNICAL CHARACTERISTICS

- Suppression of signals within the range of 300 to 5,600 MHz
- Elevation sector of suppression 0-60 degrees
- Suppression range up to 20 km



RANGE OF COVERAGE



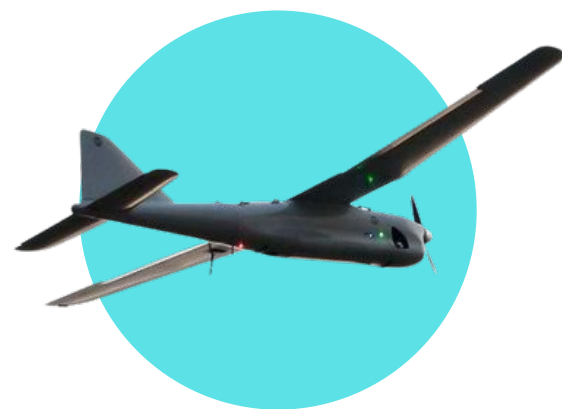
Quadcopter
(RCS 0.01 m²)

2 KM



Light airplane
(RCS 2 m²)

11.3 KM



Orlan
(RCS 15 m²)

7 KM



Helicopter
(RCS 1.5 m²)

10.5 KM

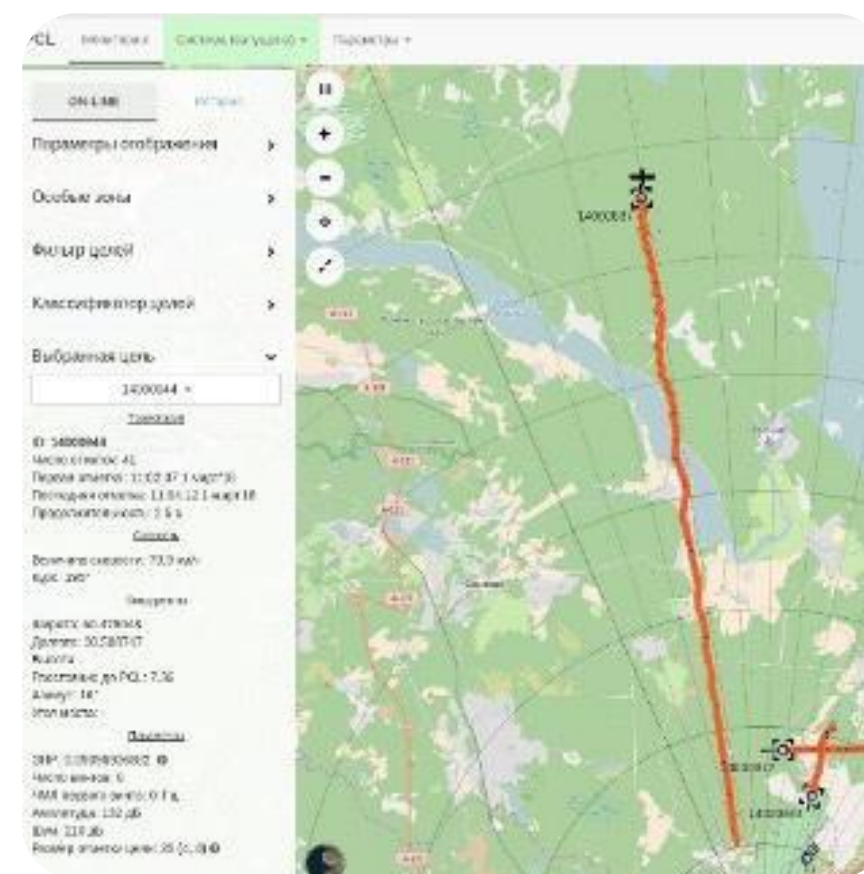
*Estimation for equivalent monostatic range when using the receiver with equivalent radiation power of 1 kW. When distance between the target and transmitter increases, the range decreases proportionally.

SYSTEM INTERFACE

System operation algorithm allows to find the direction and flight route of unmanned vehicle. The received information is displayed on topographic maps, installed in the server of control device.



Passive coherent location
radar data display unit



Data displayed on a
topographic map

BUILDING UP THE MULTIPOSITION COMPLEX OF PASSIVE COHERENT LOCATION RADAR AND RADIO MONITORING EQUIPMENT

Different versions of Multi-position complex of passive coherent location radar and radio monitoring equipment can include one to eight receiving positions.

Expanding the complex to 8 receiving positions allows to achieve the maximum coverage area.

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