

AGC 150 Basic knowledge



Synchronizing Controllers



GPC-3 Base mounted Non-Power Management



AGC 200 Front mounted Standard Power Management



AGC-4 Base mounted Custom Power Management



AGC 150 Front mounted Simple Power Management

Documentation

www.deif.com contains all manuals for the controllers



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Maximise your business

Award-winning global supplier of innovative power management solutions, engine & genset controllers, switchboard equipment, marine bridge instrumentation and renewable energy control solutions.

Documentation

EFR E	English ∨	About Contact	Career Software Support Training Webinars Whitepapers Publ	ications Documentation	
0			Land Power Marine & Offshore	Wind Power Q	
	Products / AGC 150 AGC	: 150	Q		
	AG Th fun des sm typ	GC 150 - Advanced Genset Controller the AGC 150 is a genset controller containing all necessary inclose for control and protection of a genset. The slim sign makes the controller suitable for paralleling even hall gensets thus the AGC 150 is integrable in nearly all less of gensets .	Pages WEBINAR: AGC 150 Produktvorstellung - WEBINAR: AGC 150 Subsegments INDUSTRY: First-mover in hybrid microgrid solutions - INDUSTRY: Naval vessels - INDUSTRY: Hydro		
		Description Features	Videos & Media Documentation		
		Documents			
		+ Brochures/Handouts			
		+ Data Sheet			
		+ Designer's Handbook			
		+ Installation Instructions			
		+ Operator's Manual			

AGC 150



AGC 150



Typical wiring



Basic Settings

Setup Current Transformer



Basic Settings

Nominal settings



Start Sequence

1. Before starting, start prepare ON (Relay 9). Can be used to activate pre-heating element.

If not required, timer can be changed to 0s to reduce starting time.

2. Shortly after, Starter/crank (relay 6) and Run coil (relay 5), both ON.

Once running feedback detected, Starter/crank is deactivated.

3. Run coil activates continuously all the time, for the duration of engine running.

	View mode: Tree	e O List		
starting G 0000000	 → · Basic settings > · Communication ✓ · Engine > · Running detection 	Start Prepare	· · · · ·	
✓ I/O settings	Device	View mode: Tree	⊖ List	
Inputs Outputs Inputs Outputs Relay 5 I/O number / function Relay 6 I/O number / function Starter (Crank) V	Alarms Local Trending Local Alarms Alarms		Start On Time Description: Setup of Starter ON time during cranking. Timer: 5 Start Off Time Description: Setup of Starter OFF time before a new start of the starter of	sec (1 600)
Relay 9 I/O number / function Start prepare	Advanced Brotection	Start failure Start attempts Crank timers	Timer: 5	sec (1 99)
Relay 10 I/O number / function Stop coil	Trending	 After crank Idle run Warm up ramp Stop sequence Gov 		

Glow plug

10

Checkmark [$\sqrt{}$] = <u>enable</u>

DEIF	View mode:	OList	
	> Basic settings	Over-voltage	
	Basic settings Communication	Over-current	
	Basic settings Communication	Earth fault inverse time over-current	
	> · Basic settings	Over-frequency	
	Basic settings Communication	Under-frequency	
	> Basic settings	Reverse power	
Device Alarms	 Configuration AC configuration AVR Voltage protections Current protections Frequency protections Frequency detection type Over-frequency Under-frequency 	-P> 1 ✓ Description: Reverse power protection level 1 (ANSI 32) Set point: -5 * % (-2000) Timer: 10 * sec (0.1100) Failclass: Trip GB	🛄 🖉 🚖 •
Trending Co Advanced Protection	 Power protections Overload Reverse power Capability curve Reactive power protections Busbar Mains Breakers Synchronisation Power set points 	-P> 2 ✓ Description: Reverse power protection level 2 (ANSI 32) Set point: -5< % (-2000) Timer: 10 sec (0.1100) Failclass: Trip GB	
Parameters	Power management VO settings Functions Alternative configuration	And many more	

Generator Protection

Fail class:



Trip + stop = GB trip, engine stop after cooling down

Safety stop = Extra genset start up & replace faulty genset

Trip MB/GB = In application "Single DG with mains", will trip MB instead

I/O

DIGITAL INPUT

DIGITAL OUTPUT

ANALOG INPUT



12 digital inputs, activated by negative (-) VDC signal

Each can be configured as:

- 1. Alarms
 Setup by <u>Display</u> or <u>USW</u>
- 2. Function \Box setup by <u>USW only</u>



1. Digital input as alarm

Parameter > I/O settings > Inputs > Digital inputs

DEIF	View mode:	⊖ List	
(*)	Basic settings Communication Engine Generator	Digital input 39 Image: Description: Set delay	Digital input
Device	> Busbar > Mains > Breakers > Synchronisation [√] to el	Timer: 10 sec (0100) Failclass: Warning	
Alarms	Power management VO settings Vo settings Digital input	Warning Action Trip GB Trip+stop Description: Safety stop	
Trending	Outputs External VO Functions Alternative configuration USW specific parameters	Timer: Trip MB/GB Controlled stop V Failclass: Warning V	
Advanced Protection		Digital input 41 Description: Setup of digital input on terminal 41	
Parameters		Timer: 10 sec (0100) Failclass: Warning	

2. Digital input as Function

Click icon I/O settings

File Connectio	on Parameters Help		
COURCE Device Device Alarms Local Alarms Alarms Alarms Cource Portection Cource Parameters	DG active power DG current DG reactive power	0 kW 0 kW 0 kW 0 ° 0 kvar 0 ° 0 kvar 0 ° HZ 53 ° 55 50 375 ° 500 125 0 V	Configuration input/output settings

Imputs Outputs Inputs Outputs Start enable I/O number / function Not used I/O number / function Dig. input 39, Term 39 Remote Start I/O number / function Not used Remote Stop I/O number / function Not used Alternative start I/O number / function Not used Remove starter	~
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I/O number / function Not used Alternative start I/O number / function Not used Remove starter	
Alternative start I/O number / function Not used Remove starter	
I/O number / function Not used ~	
Remove starter	
I/O number / function Not used	
Low speed	
I/O number / function Not used ~	
Binary running detection	
I/O number / function Not used	
Remote GB On	~

Default assignment

Terminal no.	Function	Remarks
39	Auto start/stop	For remote start signal
40	Not used	
41	Not used	
42	Not used	
43	Not used	
44	Not used	
45	Not used	
46	Not used	
47	Status MB ON	For application with Mains
48	Status MB OFF	For application with Mains
49	Status GB ON	
50	Status GB OFF	

Digital Output

12 digital outputs (DC outputs)

Require common positive (+) VDC

Configuration by USW





Digital Output

Setup digital output

Click icon I/O settings



Ø 1/O settings		^
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nputs Outputs		
Relay 5		^
I/O number / function	Run coil 🗸	
Relay 6		
I/O number / function	Starter (Crank) 🗸	
Relay 9		
I/O number / function	Start prepare 🗸	
Relay 10		
I/O number / function	Stop coil 🗸	
Polay 11	Stop coil	
Relay 11	Double starter	
I/O number / function	Load group 1	
	Load group 2	
Relay 12	Load group 3	
	Load group 4	
I/O number / function	Load group 5 Y	
Relay 13		
I/O number / function	Not used 🗸	
Relay 14		
I/O number / function	Not used 🗸	
Relav 15		~

Digital output

Default assignment:

Terminal no.	Function	Remarks
4	Common (+) for DO 5-6	Also serves as Emergency stop
5	Run coil	
6	Starter (crank)	
8	Common (+) for DO 9-18	
9	Start prepare	
10	Stop coil	
11	Status OK	
12	Horn	
13	Not used	
14	Not used	
15	MBON	For application with Mains
16	MB OFF	For application with Mains
17	GB ON	
18	GB OFF	

Analog Input

4 multi inputs

Selectable for:

- 4-20 mA RMI Oil Pressure
- 0-10 VDC RMI Water Temperature
- PT100 RMI Fuel Level
- Binary input



Setup by USW



Analog Input

Configuring multi inputs



I type	Configurable	■ Bar/celsius
	Select RMI Type Configurable	
t Alarm	Oil pres. type 1 (bar) Oil pres. type 2 (bar) Oil pres. type 4 (bar)	
rm when input is	High	•
point	5	
ay	10 🔶 Sec.	
class	Warning	•
tput A	Not used	•
tput B	Not used	•
to acknowledge	OFF	•
ibits	Inhibits	•

2nd Alarm	Disable	•
Alarm when input is	High	•
Set point	5	
Delay	10	Sec.
Fail dass	Warning	-
Output A	Not used	-
Output B	Not used	-
Auto acknowledge	OFF	-
Inhibits	Inhibits	-

To change text, use Translations

File Connection	n Parameters Help					
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	Digital input 47	Digital input 47		Digital input 47	Digital input 47	Digital input 47
	Digital input 48	Digital input 48	3 [Digital input 48	Digital input 48	Digital input 48

Input & Output Status

Any digital input/output can be monitored trough USW and display

File Connection	n Parameters Help						
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DEIF	Auto start/stop	39	Run coil relay		5		
	Digital input 40	40	Start relay		6		
- <u>-</u>	Digital input 41	41	Start Prepare		9		
6	Digital input 42	42	Stop coil relay	10			
44	Digital input 43	43	Status ok		11		
Advanced	Digital input 44	44	O Horn	12			
Protection	O Digital input 45	45	Relay 13		13		
1111	Digital input 46	46	Relay 14		14		
LO	Oigital input 47	47	Relay 15	15			
Darametere	Digital input 48	48	Relay 16		16		
Furdineters	GB pos feedback ON	49	GB ON relay		17		
1/0	GB pos feedback OFF	50	GB OFF relay		18		
0	O D+	7					
Inputs/Outputs	C Emergency stop	4					

Ø DEIF utility software - 3.45.0; Connected to "AGC 150 DG" (version 1.00.0 rev. 2617)

AMF		SEMI			
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Digital	input	41	0		
Digital	input	42	0		
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Stop coil relay	0	
Status ok	1	

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Analog Regulation

SPEED REGULATION - ANALOG

VOLTAGE REGULATION - ANALOG



Speed Regulation - Analog

				 Parameter "Reg. 	output GOV" (Channel 2781)	×	
1.	Setup terminal	analog out	out	Set point :			
Par	Parameter > Engine > Gov > General configuration					~	
	j		J	Password level :	service	~	
DEIF	View mode: Tree	() List		Enable High Alarm Inverse proportion	nal		
41	Basic settings Communication		Gen		e		
Device	 Engine Running detection Start sequence 	Reg. output GOV Description:	Selection of regulation output used for governor regulation	Inhibits	Virie	K Cancel	
	Stop sequence Gov Gov General configuration	Set point:	EIC V Relay Analogue Set as analog		<u>11176</u>	Mo	re setting
Alarms	Kelay configuration EIC configuration Speed PID Manuel step	Governor output Description:	EIC Transducer selection number in case of analogue output for the speed governor				
Trending	Offset for control signal Regulation failure Battery/Aux supply	Output A	Disabled V Disabled Set transducer 52	2			
6	Protections Maintenance Shutdown Override		Transducer 55 Transducer 52 PWM Transducer 55 PWM	0000	00000		
Advanced	Senerator				_		_
				47 48 49 50	51 52 53 54 55	56 57 58 58	60
				47 48 49 50	GOV (-) 51 GOV (+) 52 Not used 53 AVR (-) 54 AVR (+) 55	56 57 58 58 59 60	
)	Analogue output		26

Speed Regulation - Analog

2. Setting analog output range (VDC)

Parameter > Engine > Gov > General configuration > AOUT 52 limits

DEIF	View mode: () Tree	⊖ List	
C: Device	 > Basic settings > Communication > Engine > Running detection > Start sequence > Stop sequence > Gov 	AOUT 52 Gov Type Description: Setup of analog out 52 for governor type Set point: Adjustable	
	General configuration AOUT 52 limits PWM 52 setup Relay configuration EIC configuration Speed PID Manuel step	AOUT 52 Limits Description: Minimum limit for analogue output 52 Set point: -10 V (-10.5 5)	100 % 10V
Trending CC Advanced Protection	Offset for control signal Regulation failure Stattery/Aux supply Protections Maintenance Shutdown Override Senerator	AOUT 52 Limits Description: Maximum limit for analogue output 52 Set point: V (-5 10.5)	50 %

-10V

0%

GOV

Speed Regulation - Analog

3. Setting offset / center

Parameter > Engine > Gov > Offset for control signal



GOV

Speed Regulation – Analog Gain

1. PID Island

Parameter > Engine > Gov > Speed PID

> Island (analog/EIC)



DEIF	View mode:	OList	
	Basic settings Communication		Island (analog/EIC)
Device	 Engine Running detection Start sequence Stop sequence Gov 	f Kp Description: Proportional gain value of the PID controller for frequency regulation Set point: 2.5 • • (0 60)	
	 > Relay configuration > EIC configuration > EIC configuration ✓ Speed PID Island (analog/EIC) Island (relay) Load share (analog/EIC) 	f Ti Description: Integral time value of the PID controller for frequency regulation Set point: 1.5 v s (060)	
Trending CC Advanced Protection	Load share (relay) Mains parallel (analog/EIC) Mains parallel (relay) Manuel step Offset for control signal Regulation failure	f Td Description: Differential time value of the PID controller for frequency regulation Set point: 0 • s (0 2)	

Speed Regulation – Analog Gain

2. PID Load sharing

Parameter > Engine > Gov > Speed PID

> Load share (analog/EIC)



View mode: Tree	◯ List	
> Basic settings		Load share (analog/EIC)
bevice bevice	P loadsh. f Kp Description: Set point:	Proportional gain value of the PID controller for load sharing 2.5 (060)
Relay configuration	P loadsh, f Ti	
Alarms > EIC configuration Speed PID	Description:	Integral time value of the PID controller for load sharing
Load share (analog/EIC)	Set point:	1.5 s (060)
Trending Load share (relay)	P loadsh. f Td	
Mains parallel (relay)	Description:	Differential time value of the PID controller for load sharing
Advanced Protection	Set point:	0 s (02)

Speed Regulation – Analog Gain

3. PID Mains parallel

Parameter > Engine > Gov > Speed PID

> Mains parallel (analog/EIC)



DEIF	View mode:	⊖ List	
	Basic settings Communication	Mains parallel (analog/EIC)	
Device	Communication Engine Running detection Start sequence Stop sequence Gov Gov	P Kp Description: Proportional gain value of the PID controller for power regulation Set point: 2.5 (060)	
Alarms	 General configuration Relay configuration EIC configuration Speed PID Island (analog/EIC) Island (relay) I od share (analog/EIC) 	General configuration Relay configuration EIC configuration Speed PID Island (analog/EIC) Island (relay) Load share (analog/EIC)	P Ti Description: Integral time value of the PID controller for power regulation Set point: 1.5 s (060)
Trending CC Advanced Protection	Load share (relay) Mains parallel (analog/EIC) Mains parallel (relay) Manuel step Offset for control signal Regulation failure Battery/Aux supply	P Td Description: Differential time value of the PID controller for power regulation Set point: 0 s (02)	

Voltage Regulation - Analog

1. Setup termina	I analog output	Parameter "Reg. output AVR" (Channel 2782) Set point : Analogue	
Parameter > Generato	or > AVR > General configuration	Password level : v	-
View mode: Tree	OList	High Alarm	
 Basic settings Communication Engine Generator Alarms Communication Engine Generator Alconfiguration Alarms General configuration Relay configuration Voltage PID Manuel step Offset for control signal Regulation failure Voltage protections Frequency protections Reactive power protections Reactive power protections Busbar Busbar Synchronisation Power set points Power management VO settings 	Reg. output AVR Description: Selection of regulation output used for AVR regulation Set point: Analogue AVR output Description: Transducer selection number in case of analogue output for the voltage reg Output A Transducer 55	eneral confi Auto acknowledge whibits gulator	More setting
		(+) AVR (+) Avra of the second	32

Voltage Regulation - Analog

2. Setting analog output range & center

Parameter > Generator > AVR > General configuration > AOUT 55 limits

Parameter > Generator > AVR > Offset for control signal

DEIF	View mode:	List		
	> · Basic settings	AOUT 55 Limits		
Device	Communication Engine Generator AC configuration AVR General configuration	AOUT 55 AVR Type Description: Setup of analog out 55 for AVR type Set point: Adjustable		
<u>\i</u>	AOUT 55 Limits Relay configuration DAVR configuration	AOUT 55 Limits	100 %	10V
Alarms	Voltage PID Manuel step Offset for control signal	Description: Minimum limit for analogue output 55 Set point: -10 V (-10.5 5)		
Trendin	View mode: Tree View mode: Tree · Basic settings · Communication	OList Offset for control	signal 50 %	0V
Advance Protectio	Device > Engine V Generator > AC configuration V AVR > General configuration	AVR output offset 1 Description: Offset of the analogue output used for AVR regulation set point 1 Set point: 50 % (0 100)		
Paramete	Alarms		0 %	-10V
	Manuel step Offset for control signal Regulation failure		AVR	

Voltage Regulation – Analog Gain

Same principle with speed PID

Parameter > Generator > AVR > Voltage PID >

- □ Island (analog/EIC)
- □ Load share (analog/EIC)
- □ Mains parallel (analog/EIC)

DEIF	View mode: Tree S · Basic settings Communication C · Engine	U Kp					Island (analog/EIC)		1
Device	Generator AC configuration AVR Seneral configurat	Basic settings Communication Engine		Q loadsh. U Kp			Load	share (analog/EIC)	
Alarms	 General configuration Relay configuration DAVR configuration DAVR configuration Voltage PID Island (analog) Island (relay) Load share (ar Mains parallel Mains parallel Manuel step Offset for controls Regulation failure Voltage protections Current protections 	Generator AC configuration AVR General configuration Relay configuration DAVR configuration OAVR configuration Voltage PID General canalog/ General canalogeneral canalogeneral canalog/ General canalog/ General ca	or configuration } Basic settings > Communication > Engine > Generator DAVR configuration Voltage PID - Island (analog/EI > Basic settings > Communication > AC configuration > AVR > General configuration > Relay configuration > Relay configuration > Relay configuration		Q Кр	Description: Set point:	Proportional gain value of the PID controller for	Mains pa r reactive power regulation (060)	arallel (analog/EIC)
Advanced Protection		Mains parallel (Manuel step Offset for control s Regulation failure Voltage protections Offset for control s Mains parallel (Mains parallel (R configuration ge PID sland (analog/EIC) sland (relay) oad share (analog/EIC) oad share (relay) lains parallel (analog/EIC) lains parallel (relay)	Q TI Q Td	Description: Set point:	Integral time value of the PID controller for read	ctive power regulation	
		Voltage protections Current protections	→ Manu → Offse → Regu > · Voltage p > · Current p	el step et for control signal lation failure rotections rotections		Description: Set point:	Differential time value of the PID controller for	s (02)	

Analog Regulation Status

Check **Device**

- > Governor reg.
- > AVR reg.



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GB/TB on 49 49 40 GB/TB off 50 GC	GOV (-) 51	CS (+) Analog	off AVR (L) 54	AVR (+) 55 54	22	L1 (S1) 56	L2 (S1) 57 L3 (S1) 58 58 58	± ⊕ Com (S2) 59 51	P L4 (S1) 60 50	(H) L4 (S2) 61 20		N 62	Eg []	79 27 re A-s	F1 65 64	999 N AC	r1 67 60	
DEIF A/S Frisenborgvej 33 DK-7800 Skive						AC o Controller type CT Genset controller Ge Mains controller Ma BTB controller Bu						onnection -side A-side n Gen ins Mains s A Bus A			B-side BB/Main: BB Bus B			
) US LISTED 2KD2. Se nt. Eq. Type 1 do	A produce prod	tion 6				WARNING SHORT ALL CURRENT TRANSFORMERS BEFORE DISCONNECTING TERMINALS 56-61												
utput (configurable) Analic D ont t 13 O nt t t 13 O nt t t 13 O nt t t 14 O nt t t 14 O nt t t 14 O nt t t 0 U t t 0 U t t 0 U t t 0 U					R /	22 In 23 In 23 In 24 Pos 25 SCR 26 Neg 27 High 27 High 28 Data (GND) 28 Data 20 Iour						31 Deta (GND) SWd AVS			33 Data + (A) 34 Data (GND) 35 Data - (B)			
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Relay regulation

SPEED REGULATION - RELAY

VOLTAGE REGULATION - RELAY


1. Change Gov setting to relay

Parameter > Engine > Gov > General configuration



2. Setup pulse signal and choosing relay terminals

Parameter > Engine > Gov > Relay configuration > Output and period



> Basic settings	Output and pe
Communication Communication Communication Communication Sequence Start sequence Stop sequence	GOV ON time Description: The min. ON time of the relay outputs used for governor relay regulation Set point: 500 ms (10 6500)
	GOV period time Description: The regulator period time used for governor relay regulation
Ing Battery/Aux supply Control signal Control signa	Set point: 2500 ms (250 32500) Output A Terminal 13 Increase Output B Terminal 14 Decrease

3. Setup speed Gain

Parameter > Engine > Gov > Speed PID >

- □ Island (relay)
- □ Load share (relay)
- □ Mains Parallel (relay)

View mode:	Tree) List f deadband	Island (relay)
Device Starts	Basic settings Communication Engine Nunning detection	P LS f deadband	Load share (relay)
Alarms Treading	 Start sequence Stop sequence Gov General configuration Relay configuration EIC configuration EIC configuration Speed PID Island (analog/EIC) Island (relay) Load share (analog/ Load share (relay) Mains parallel (analo Mains parallel (relay) Manuel step Offset for control signal Regulation failure Battery/Aux supply 	 > · Basic settings > · Communication > · Engine > · Running detection > · Start sequence > · Stop sequence > · Gov > · General configuration > · Relay configuration > · EIC configuration > · EIC configuration > · Speed PID - · Island (relay) - Load share (analog/EIC) - · Mains parallel (analog/EIC) - · Manuel step - Offset for control signal - Regulation failure 	Mains parallel (relay) P deadband Description: Deadband of the controller for frequency regulation Set point: P Kp relay Description: Proportional gain value of the controller for frequency regulation Set point: (0100)

Regulation Deadband



Regulator

When commissioning, set deadband to minimum to check genset response After completed, set deadband back to prolong relay lifetime

Voltage Regulation - Relay

1. Change AVR setting to relay

Parameter > Generator > AVR > General configuration



Voltage Regulation - Relay

2. Setup pulse signal and choosing relay terminals

Parameter > Generator > AVR > Relay configuration > Output and period





Voltage Regulation - Relay

3. Setup voltage Gain

Parameter > Generator > AVR > Voltage PID >

- □ Island (relay)
- □ Load share (relay)
- □ Mains Parallel (relay)

When commissioning, set deadband to minimum to check genset response After completed, set deadband back to prolong relay lifetime

	View mode:	Tree List		Island (relay)
Advanced Protection	 Engine Generator AC configu AVR Generation 	 > Basic settings > Communication > Engine > Generator > AC configuration 	Q LS U deadband Description: Deadband of the volta	age regulation in load sharing
Parameters	 ✓ Relay of — Our → DAVR (✓ Voltage — Isla — Loi — Loi 	 AVR General configuration Relay configuration DAVR configuration Voltage PID Island (analog/EIC) Island (relay) Load share (analog/EIC) Load share (relay) Mains parallel (analog/EIC) Mains parallel (relay) Manuel step Offset for control signal Regulation failure Voltage protections Current protections 	 Basic settings Communication Engine Generator AC configuration AVR General configuration Relay configuration DAVR configuration DAVR configuration Solution Voltage PID Island (analog/EIC) Island (relay) Load share (analog/EIC) Load share (relay) Mains parallel (analog/EIC) Mains parallel (relay) Manuel step Offset for control signal Regulation failure 	Q deadband Description: Deadband of the controller for reactive power regulation Set point: 2 * % (0 10) Q Kp relay Description: Proportional gain value for the reactive power regulation Set point: 10 * (0 100)

Relay Regulation Status

Check Device

- > Governor reg.
- > AVR reg.



Synchronisation



Synchronisation

AGC <u>always</u> perform synchronism check before closing breakers

All modes: Auto, Semi Auto, and Manual





Allowed maximum slip frequency: **0.3Hz**

Synchronisation

Change slip frequency & voltage

Synchronisation > Dynamic synchronisation

View mode: Tree	() List	
Advanced Advanced Advanced	Slip Frequen Sync. dfMax Description: Max. allowable frequency difference	e for Dynamic synchronisation
Protection > Breakers Synchronisation — Synchronisation type — Dynamic synchronisation — Synchronisation regulator > Static synchronisation > Static synchronisation > CBE (Close before excitation)	Sync. dfMin Description: Min. allowable frequency difference Set point:	for Dynamic synchronisation 0 Hz (-0.50.3)
lere, to sync with 50.0Hz 400V busbar Freq between 50.0 – 50.3Hz	; genset need to run:	Sync. dUMax Slip Voltage Description: Max. allowable voltage difference for Dynamic synchronisation Set point: 5 % (210)
voltage between 380 – 420v	ngs	Sync. dUMin Description: Max. allowable value the regulated voltage must be below voltage to sync to Set point: -5 % (-10 0)

Application

SINGLE GENSET

MULTIPLE GENSETS



Adapting Mimic



Standalone Island



Standalone AMF



Standalone Parallel without MB





DEIP FIXED POWER SENT BH L1 50.00Hz 4007 1.00% 449KN 6 449kVN 707 L1 50.00Hz 449K.VD Okvar 400V E H-LIN 231¥ ÷ • ۲ ത



Genset

MAINS+TB

MAINS

BTB

Typical Applications for AGC 150

- Single Genset •
- Single Genset with Mains ۲



(SW packagers dependent)



SINGLE GENSET

- □ Application configuration
- □ New plant configuration



Single Genset with Mains



(CAN bus off (stand-alone application)

O Breaker and engine cmd. active Breaker and engine cmd. inactive

Cancel

Application emulation

Off

OK

Alternative setup:*



Select Genset Mode

Parameter > Basic settings > Application type > Genset type > Genset/plant mode



Enable Back Synchronising

Parameter > Synchronisation > Mains parallel settings



AMF delay settings

Parameter > Mains > AMF function > AMF timer



•

Mains failure voltage setpoint

Parameter > Mains > Voltage and frequency limits > Voltage limits

	View mode:	Tree O List	
\bigcirc	> · Basic settings	Voltage s	settings
	 > Communication > Engine > Generator > Busbar > Mains > Protections 	Low Voltage Description: set point for mains voltage range low Set point: 90 % (30 100)	
	Alarms Voltage and fre Alarms Voltage set Sector Frequnecy Sector Synchronisation	equency limits ttings vestings Description: set point for mains voltage range high Set point: 110 % (100 120)	

Done setup single genset?

Check Application Supervision





Or Device

For detailed monitoring







MULTIPLE GENSETS

□ Application configuration □ New plant configuration









Cancel

Application emulation

O Breaker and engine cmd. active O Breaker and engine cmd. inactive

Off

OK

Select Genset Mode

Parameter > Basic settings > Application type > Genset type > Genset/plant mode



Setup ID Number

Parameter > Communication > Power management ID

		DEIF	View mode: Tree	() List			
			> Basic settings			Power manage	ment ID
		(6)	Power management ID RS485	Int. comm. ID Description:	Internal communication ID number		
ID: 1	ID: 2	Device	CAN protocols Ethernet comm. error	Set point:	•	1 (1 32)	
		<u>\!\</u>	> Generator > Busbar	1		add ID on every genset	
		Alarms	Mains Breakers Synchronisation				
			 Power set points Power management 				
		Trending	> VO settings > Functions				
		(C	 Alternative configuration USW specific parameters 				
Genset 1	Genset 2						

CANbus wiring



Check Application Supervision

Genset 1





Power Management

LOAD DEPENDENT START/STOP

MULTI START





Genset 1





Load dependent start/stop

Configure Start/stop based on load Percentage

Parameter > Power management > Load dependent start/stop configuration





Load dependent start/stop

Start percentage setpoint

Parameter > Power management > Load dependent start 1

		> Basic settings		Load dependent start 1
	Advanced Protection	 Communication Engine Generator Busbar Mains Breakers Synchronisation Power set points Power management Start/stop for Island Easy connect Load dependent Start/stop configuration Load dependent start 1 Load dependent start 2 Load dependent stop 1 Load dependent stop 2 Multi start set Priority Available power Communication failures 	Ld. start limit P Description: Set point:	Setting for Load dependent Start in kW 100 kW (1 20000)
	Parameters		Ld. start limit S Description: Set point:	Setting for Load dependent Start in kVA 100 kVA (120000)
	Inputs/Outputs		Ld. start limit % Description: Set point:	Setting for Load dependent Start in Percentage
Genset 1 Genset 2	Options	Communication railures Busbar alarms Additional power management settings VO settings Functions Alternative configuration USW specific parameters	Ld. start timer Description: Timer:	Setup of Load dependent Start limits Start delay

Load dependent start/stop

Stop percentage setpoint

Parameter > Power management > Load dependent stop 1

			> Basic settings			Load dependent stop 1
	Advanced Protection	 Communication Engine Generator Busbar Mains Breakers Synchronisation Power set points Power management Start/stop for Island Easy connect Load dependent Start/stop configuration 	Ld. stop limit P Description: Set point:	Setting for Load dependent Stop in KW	kW (1 20000)	
	Parameters		Ld. stop limit S Description: Set point:	Setting for Load dependent Stop in kVA	kvA (1 20000)	
		Inputs/Outputs	Load dependent start 2 Load dependent stop 1 Load dependent stop 2 Multi start set Priority Available power Communication failures	Ld. stop limit % Description: Set point:	Setting for Load dependent Stop in Percentage	% capacity after 1 genset removed % (1100)
Genset 1	Genset 2	Options	Communication failures Busbar alarms Additional power management settings VO settings Functions Alternative configuration USW specific parameters	Ld. stop timer Description: Timer:	Setup of Load dependent Stop limits Sto	pping delay sec (5 990)

Multi start

Setup of how many gensets start together

Parameter > Power management > Multi start set



Genset 1

Genset 2

Questions?



/DEIFgroup



/company/DEIFgroup







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Thank you



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