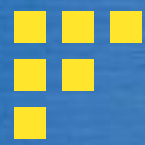




# *ITK Lecture 4*

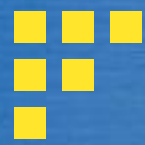
## *Images in ITK*

Methods in Image Analysis  
CMU Robotics Institute 16-725  
U. Pitt Bioengineering 2630  
Spring Term, 2006



# Data storage in ITK

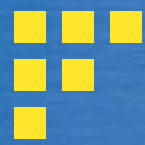
- ITK separates storage of data from the actions you can perform on data
- The DataObject class is the base class for the major “containers” into which you can place data



# Data containers in ITK

- Images: N-d rectilinear grids of regularly sampled data
- Meshes: N-d collections of points linked together into cells (e.g. triangles)
- Meshes are outside the scope of this course, but please see section 4.3 of the ITK Software Guide for more information





# What is an image?

- For our purposes, an image is an N-d rectilinear grid of data
- Images can contain *any* type of data, although scalars (e.g. grayscale) or vectors (e.g. RGB color) are most common
- We will deal mostly with scalars, but keep in mind that unusual images (e.g. linked-lists as pixels) are perfectly legal in ITK



# Images are templated

```
itk::Image< TPixel, VImageDimension >
```

Pixel type



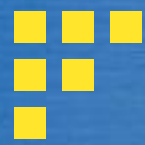
Dimensionality (value)



Examples:

```
itk::Image<double, 4>
```

```
itk::Image<unsigned char, 2>
```

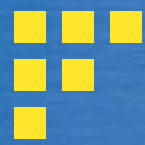


# An aside: smart pointers

- In C++ you typically allocate memory with new and deallocate it with delete
- Say I have a class called Cat:

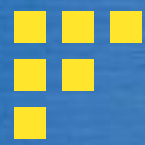
```
Cat* pCat = new Cat;  
pCat->Meow();  
delete pCat;
```





# Danger Will Robinson!

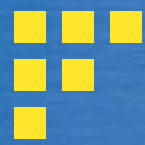
- Suppose you allocate memory in a function and forget to call delete prior to returning... the memory is still allocated, but you can't get to it
- This is a *memory leak*
- Leaking doubles or chars can slowly consume memory, leaking 200 MB images will bring your computer to its knees



# Smart pointers to the rescue

- Smart pointers get around this problem by allocating and deallocating memory for you
- You *do not* explicitly delete objects in ITK, this occurs automatically when they go out of scope
- Since you can't forget to delete objects, you can't leak memory  
(ahem, well, you have to try harder at least)





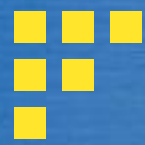
# Smart pointers, cont.

- This is often referred to as *garbage collection* - languages like Java have had it for a while, but it's fairly new to C++
- Keep in mind that this only applies to ITK objects - you can still leak arrays of floats/chars/widgets to your heart's content



# Why are smart pointers smart?

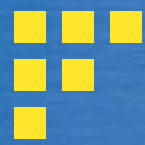
- Smart pointers maintain a “reference count” of how many copies of the pointer exist
- If  $N_{\text{ref}}$  drops to 0, nobody is interested in the memory location and it's safe to delete
- If  $N_{\text{ref}} > 0$  the memory is *not* deleted, because someone still needs it



# Scope

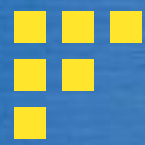
- It's not just a mouthwash
- Refers to whether or not a variable still exists within a certain segment of the code
- Local vs. global
- Example: variables created within member functions typically have local scope, and “go away” when the function returns





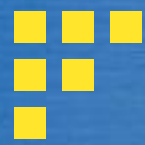
# Scope, cont.

- Observation: smart pointers are only deleted when they go out of scope (makes sense, right?)
- Problem: what if we want to “delete” a SP that has *not* gone out of scope; there are good reasons to do this, e.g. loops



# Scope, cont.

- You can create local scope by using {}
- Instances of variables created within the {} will go out of scope when execution moves out of the {}
- Therefore... “temporary” smart pointers created within the {} will be deleted
- Keep this trick in mind, you may need it

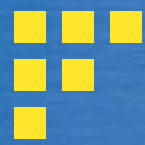


# A final caveat about scope

---

- Don't obsess about it
- 99% of the time, smart pointers are smarter than you!
- 1% of the time you may need to haul out the previous trick



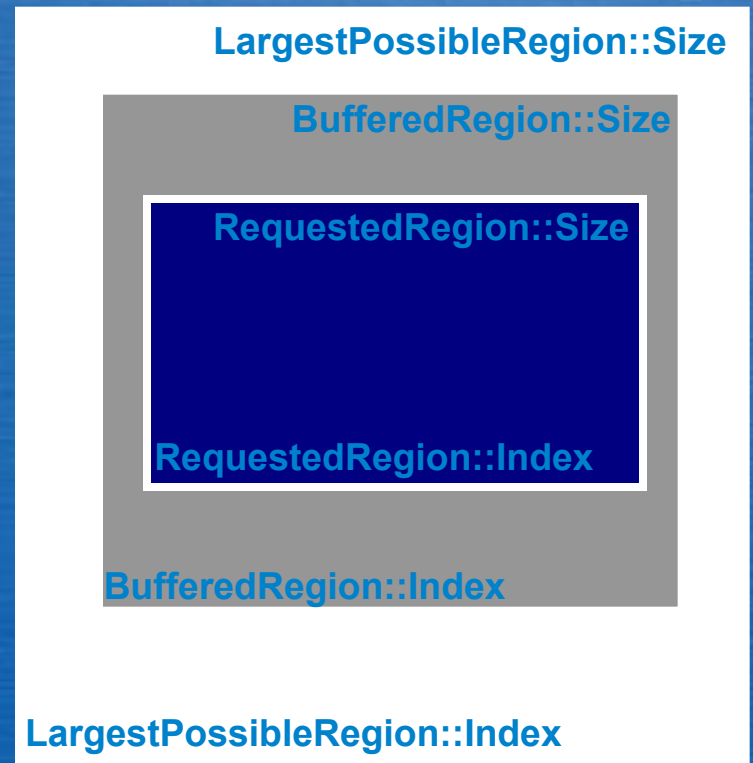


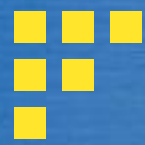
# Images and regions

- ITK was designed to allow analysis of very large images, even images that far exceed the available RAM of a computer
- For this reason, ITK distinguishes between an entire image and the part which is actually resident in memory or requested by an algorithm

# Image regions

- Algorithms only process a region of an image that sits inside the current buffer
- The BufferedRegion is the portion of image in physical memory
- The RequestedRegion is the portion of image to be processed
- The LargestPossibleRegion describes the entire dataset





# Image regions, cont.

- It may be helpful for you to think of the `LargestPossibleRegion` as the “size” of the image
- When creating an image from scratch, you must specify sizes for all three regions - they *do not* have to be the same size
- Don't get too concerned with regions just yet, we'll look at them again with filters

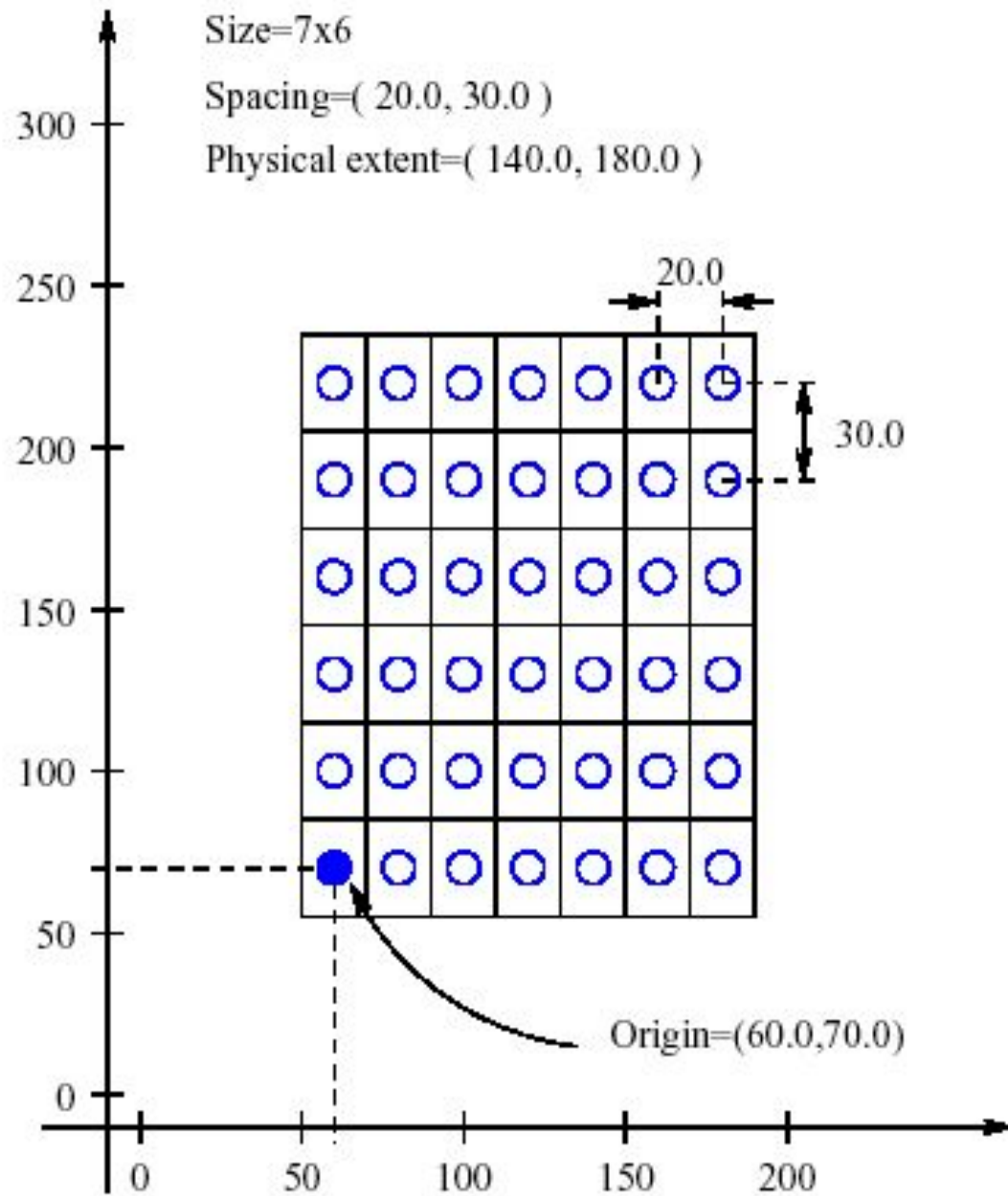
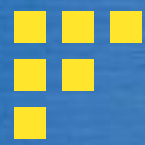




# Data space vs. “physical” space

- Data space is an N-d array with integer indices, indexed from 0 to  $(L_i - 1)$ 
  - e.g. pixel (3,0,5) in 3D space
- Physical space relates to data space by defining the origin and spacing of the image

Length of side  $i$

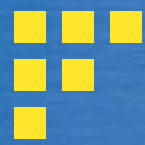




# Creating an image: step-by-step

- Note: this example follows 4.1.1 from the ITK Software Guide, but differs in content - please be sure to read the guide as well
- This example is provided more as a demonstration than as a practical example - in the real world images are often/usually provided to you from an external source rather than being explicitly created





# Declaring an image type

Recall the typename keyword... we first define an image type to save time later on:

```
typedef itk::Image< unsigned short, 3 >  
    ImageType;
```

We can now use ImageType in place of the full class name, a nice convenience



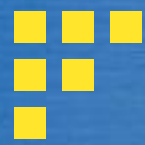
# A syntax note

It may surprise you to see something like the following: (well, not if you were paying attention last week!)

```
ImageType :: SizeType
```

Classes can have typedefs as members. In this case, `SizeType` is a public member of `itk::Image`. Remember that `ImageType` is itself a typedef, so we could express the above more verbosely as

```
itk::Image< unsigned short, 3 >::SizeType
```



# Syntax note, cont.

- This illustrates one criticism of templates and typedefs - it's easy to invent something that looks like a new programming language!
- Remember that names ending in “Type” are types, not variables or class names
- Doxygen is your friend - you can find user-defined types under “Public Types”





# Creating an image pointer

An image is created by invoking the `New()` operator from the corresponding image type and assigning the result to a `SmartPointer`.

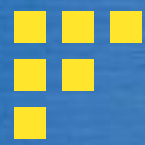
```
ImageType::Pointer image = ImageType::New();
```

Pointer is typedef'd in `itk::Image`



Note the use of “big New”



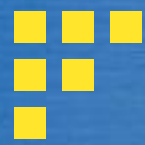


# A note about “big New”

- Many/most classes within ITK (indeed, all which derive from `itk::Object`) are created with the `::New()` operator, rather than `new`

```
MyType::Pointer p = MyType::New();
```

- Remember that you should not try to call `delete` on objects created this way



# When not to use ::New()

- “Small” classes, particularly ones that are intended to be accessed many (e.g. millions of) times will suffer a performance hit from smart pointers
- These objects can be created directly (on the stack) or using `new` (on the free store)

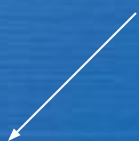




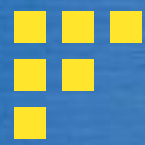
# Setting up data space

The ITK Size class holds information about the size of image regions

SizeType is another typedef



```
ImageType::SizeType size;  
size[0] = 200; // size along X  
size[1] = 200; // size along Y  
size[2] = 200; // size along Z
```

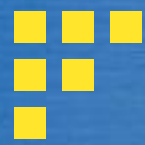


# Setting up data space, cont.

Our image has to start somewhere - how about the origin?

```
ImageType::IndexType start;  
start[0] = 0; // first index on X  
start[1] = 0; // first index on Y  
start[2] = 0; // first index on Z
```

Note that the index object *start*  
was not created with `::New()`



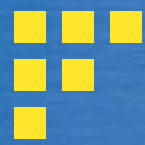
# Setting up data space, cont.

Now that we've defined a size and a starting location, we can build a region.

```
ImageType::RegionType region;  
region.SetSize( size );  
region.SetIndex( start );
```

*region* was also not created with ::New()

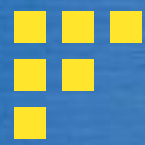




# Allocating the image

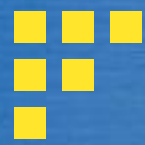
Finally, we're ready to actually create the image. The `SetRegions` function sets all 3 regions to the same region and `Allocate` sets aside memory for the image.

```
image->SetRegions( region );  
image->Allocate();
```



# Dealing with physical space

- At this point we have an image of “pure” data; there is no relation to the real world
- Nearly all useful medical images are associated with physical coordinates of some form or another
- As mentioned before, ITK uses the concepts of origin and spacing to translate between physical and data space

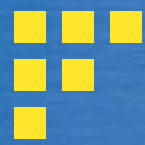


# Image spacing

We can specify spacing by calling the SetSpacing function in Image.

```
double spacing[ ImageType::ImageDimension ];  
spacing[0] = 0.33; // spacing in mm along X  
spacing[1] = 0.33; // spacing in mm along Y  
spacing[2] = 1.20; // spacing in mm along Z  
image->SetSpacing( spacing );
```

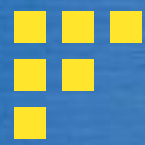




# Image origin

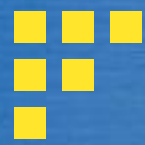
Similarly, we can set the image origin

```
double origin[ImageType::ImageDimension];  
origin[0] = 0.0; // coordinates of the  
origin[1] = 0.0; // first pixel in N-D  
origin[2] = 0.0;  
image->SetOrigin( origin );
```



# Origin/spacing units

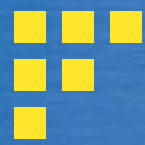
- There are no inherent units in the physical coordinate system of an image
  - I.e. referring to them as mm's is arbitrary (but very common)
- Unless a specific algorithm states otherwise, ITK does not understand the difference between mm/inches/miles/etc.



# Direct pixel access in ITK

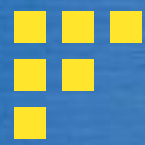
- There are many ways to access pixels in ITK
- The simplest is to directly address a pixel by knowing either its:
  - Index in data space
  - Physical position, in physical space





# Why *not* to directly access pixels


- Direct pixels access is simple conceptually, but involves a lot of extra computation (converting pixel indices into a memory pointer)
- There are much faster ways of performing sequential pixel access, through iterators



# Accessing pixels in data space

- The Index object is used to access pixels in an image, in data space

```
ImageType::IndexType pixelIndex;  
pixelIndex[0] = 27; // x position  
pixelIndex[1] = 29; // y position  
pixelIndex[2] = 37; // z position
```



# Pixel access in data space

- To set a pixel:

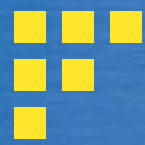
```
ImageType::PixelType pixelValue = 149;  
image->SetPixel(pixelIndex, pixelValue);
```

(the type of pixel stored in the image)

- And to get a pixel:

```
ImageType::PixelType value = image  
->GetPixel( pixelIndex );
```

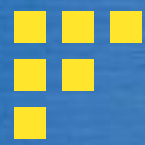




# Why the runaround with PixelType?

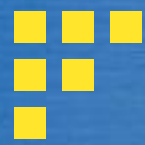
- It might not be obvious why we refer to `ImageType::PixelType` rather than (in this example) just say `unsigned short`
- In other words, what's wrong with...?

```
unsigned short value = image->GetPixel(  
    pixelIndex );
```



# PixelType, cont.

- Well... nothing's wrong in this example
- *But*, in the general case we don't always know or control the type of pixel stored in an image
- Referring to ImageType will allow the code to compile for any type that defines the = operator (float, int, char, etc.)



# PixelType, cont.

That is, if you have a 3D image of doubles,

```
ImageType::PixelType value = image  
->GetPixel( pixelIndex );
```

works fine, while

```
unsigned short value = image->GetPixel(  
    pixelIndex );
```

will produce a compiler warning

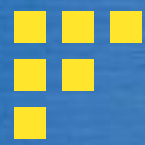




# Walking through an image - Part 1

If you've done image processing before,  
the following pseudocode should look  
familiar:

```
loop over rows
  loop over columns
    build index (row, column)
    GetPixel(index)
  end column loop
end row loop
```



# Image traversal, cont.

- The loop technique is easy to understand but:
  - Is slow
  - Doesn't scale to N-d
  - Is unnecessarily messy from a syntax point of view
- Next week we'll learn a way around this



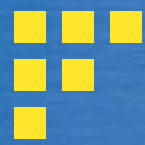
# Accessing pixels in physical space

---

ITK uses the Point class to store the position of a point in N-d space; conveniently, this is the “standard” for many ITK classes

```
typedef itk::Point< double,  
    ImageType::ImageDimension >  
    PointType;
```

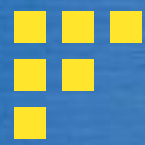




# Defining a point

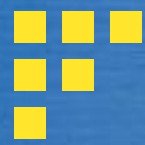
Hopefully this syntax is starting to look somewhat familiar...

```
PointType point;  
point[0] = 1.45; // x coordinate  
point[1] = 7.21; // y coordinate  
point[2] = 9.28; // z coordinate
```



# Why do we need a Point?

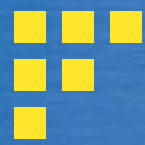
- The image class contains a number of convenience methods to convert between pixel indices and physical positions (as stored in the Point class)
- These methods take into account the origin and spacing of the image, and do bounds-checking as well (i.e., is the point even inside the image?)



# TransformPhysicalPointToIndex

- This function takes as parameters a Point (that you want) and an Index (to store the result in) and returns true if the point is inside the image and false otherwise
- Assuming the conversion is successful, the Index contains the result of mapping the Point into data space





# The transform in action

First, create the index:

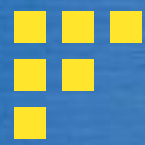
```
ImageType::IndexType pixelIndex;
```

Next, run the transformation:

```
image->TransformPhysicalPointToIndex(  
    point, pixelIndex );
```

Now we can access the pixel!

```
ImageType::PixelType pixelValue =  
    image->GetPixel( pixelIndex );
```



# Point and index transforms

2 methods deal with integer indices:

`TransformPhysicalPointToIndex`

`TransformIndexToPhysicalPoint`

And 2 deal with floating point indices  
(used to interpolate pixel values):

`TransformPhysicalPointToContinuousIndex`

`TransformContinuousIndexToPhysicalPoint`